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NUMERICAL APPLICATION OF ONE NEW APPROXIMATE METHOD FOR SOLVING BOUNDARY VALUE PROBLEMS

by M. A. Aleksidze, N. M. Arveladze, and N. L. Lekishvili

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ANNOTATION

This monograph analyzes the questions involved in the numerical application of one new method for solving boundary value problems — the method of functional equations — and derives the proper general purpose programs.

TABLE OF CONTENTS

				PAGE
ANNOTATION				iii
INTRODUCTION				1.
§ 1. Dirichlet Problem and Green Formulas	•	٠	ø	2
§ 2. Fundamental Formula for the Theory of Harmonic Functions	•	•		7
§ 3. Some Concepts of Functional Analysis	0	٠	G	16
§ 4. Linear Independence and Completeness of Several Systems of Harmonic Functions	ø	0	•	27
§ 5. Approximate Method for Solving the Dirichlet Problems	•	e	œ	35
§ 6. Solution to Boundary Value Problems with the Aid of Nonorthogonal Series	6	0	۰	53
§ 7. Series of Nonorthogonal Systems of Functions	٠	9	•	65
§ 8. Nonorthogonal Series in Variational Methods	e		۰	89
§ 9. Approximate Solution to One Mixed Boundary Value Problem in the Theory of Harmonic Functions		9	6	95
§ 10. Approximate Solution to the Reimann-Hilbert Problem .	•	۰	٠	104
§ 11. Solution to the External Dirichlet Problem for the Laplace Equation Using the Method of Functional Equations	;	•		120
§ 12. Solution to the Two-Dimensional External Dirichlet Proble by the Method of Generalized Fourier Series	m.		•	151
REFERENCES				187

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INTRODUCTION

Many important problems in natural science can be reduced to so-called boundary value problems. Development of general methods for solving these problems and investigation of the total automation of their approximate solution on general purpose computers are problems of paramount significance. In the Department of Numerical Methods of the Computer Center, Academy of Sciences, Georgian SSSR under the direction of V.D. Kupradze, a general approximate method was developed for solving boundary value problems. In the present publication this method is discussed relative to the first internal boundary value problem of the theory of harmonic functions. The general purpose programs cited at the end of this publication make it possible to find solutions to the external Dirichlet boundary value problems for ellipsoidal regions on the high speed electronic computer BESM-2. These problems arise in computing gravity, magnetic, electric and heat fields, in solving problems in hydrodynamics of an ideal fluid, in solving certain problems in the theory of elasticity, etc.

In 1961, at a seminar held at the Computer Center of the Academy of Sciences, Georgian SSR, V. D. Kupradze indicated the possiblity of finding an approximate solution to boundary value problems with the aid of integral Expressions (5.1) and (5.2) by replacing them with quadrature formulas. Solution to numerous examples carried out by N.A. Papumashvili showed that this approach to the approximate solution of boundary value problems (in Reference [3], it was called the second approach) leads to the very poorly stipulated systems of linear equations. In several instances an increase in the number of points in the quadrature formula leads to a deterioration of the final results. This is due to the fact that (5.2) is a functional equation of the first sort, and that its approximate solution is an improper problem. A

special seminar was held to discuss the questions of justifying and approving this method; at this seminar a new method was developed and justified for an approximate solution to the boundary value problems that is also based on Expressions (5.1) and (5.2) (Reference [3], calls this the first approach). The results obtained at this seminar are discussed in Reference [1-3].

Initially the present publication was regarded as a collection of general-purpose programs, instructions for them and numerical examples, solved approximately using these general purpose programs. Then part of the general purpose programs for solving the internal Dirichlet problem was published in Moscow ("Giprotis")* [27,28], which made it possible to give a more complete discussion of the approximate method and to define certain concepts as well as the proof and conclusions of known theorems and formulas, which were used in demonstrating the approximate method. It seems to us that this will facilitate understanding of the material discussed.

§ 1. Dirichlet Problem and Green Formulas

Let V be a finite region bounded by a closed Lyapunov surface S. The internal Dirichlet problem is as follows: We seek a harmonic function u in the region V, i.e.,

$$\Delta u = \frac{\partial^2 u}{\partial x_1^2} + \frac{\partial^2 u}{\partial x_2^2} + \frac{\partial^2 u}{\partial x_3^2} = 0,$$
(1.1)

which at the boundary s assumes specified values $\psi(s)$:

$$u \mid_{S} = \psi(s). \tag{1.2}$$

16

The external infinite region with the boundary s is denoted by V_e . The external Dirichlet problem is as follows. We seek a harmonic function in V_e which at the boundary s satisfies Expression (1.2).

^{*} Translator's note: State Institute for Standard Experimental Planning and Technical Research.

The method discussed below for solving the boundary value problems is based on several integral expressions. For the Dirichlet and Neumann boundary value problems (both interior and exterior) such an expression is called the Green formula.

First let us find the Gauss divergence theorem which establishes the relationship between the triple integral over the volume V and the integral over the surface S which bounds this area [9].

Let $A_1(x)$, i = 1, 2, 3, be functions which have continuous first derivatives in the region V. We can use the following rule [9] for computing the triple integrals.

For reduction of the triple integral

$$\iiint\limits_V f(x_1, x_2, x_3) dV$$

to a single and double integral: (1) let us map the surface S, which bounds the region V, onto the plane x_1 , x_2 in the form of the region δ ; (2) let us determine the coordinates $x_3^{(1)}$ and $x_3^{(2)}$ of the points of entry and exit of the straight line, parallel to the axis $0x_3$ and passing through the point (x_1, x_2) of the region δ ; (3) if we assume x_1, x_2 to be constants, we can compute the integral

$$\int_{X_3^{(1)}}^{X_3^{(2)}} f(x_1, x_2, x_3) dx_3,$$

and then the double integral

$$\iint_{\tilde{t}} d\sigma \int_{X_3^{(1)}}^{X_3^{(2)}} f(x_1, x_2, x_3) dx_3.$$

Applying this rule to the function $\frac{\partial A_1}{\partial x_1}$ and recalling that the integral of the derivative is equal to the difference in values of the primitive function at the upper and lower limits, we obtain

$$\iiint\limits_{V} \frac{\partial A_{1}}{\partial x_{1}} \ dV = \iint\limits_{\delta} d\sigma \int\limits_{x_{3}^{(1)}}^{x_{3}^{(2)}} \frac{\partial A_{1}}{\partial x_{1}} \ dx_{2} = \iint\limits_{\delta} \left[A_{1}(x_{1}, x_{2}, x_{3}^{(2)}) - A_{1}(x_{1}, x_{2}, x_{3}^{(1)}) \right] d\sigma.$$

Let us divide the surface S into three parts: S_1 is the set of points of entry into the region V of the straight lines parallel to the axis Ox_1 ; S_2 is the set of points of exit from the region V of the straight lines parallel to the axis Ox_1 ; S_3 is the set of points belonging to the parallel axis Ox_1 , tangent to S. Let us denote by (n_x, x_1) the angle between the axis Ox_1 and the outer normal n_x to S at the point $x \in S$.

From the trivial equations

$$d\sigma = \cos(n_x, x_1) ds$$
 for S_1 , $d\sigma = -\cos(n_x, x_1) ds$ for S_2 ,

where ds is the element of S (area of an infinitely small vicinity of the point $x \in S$ for S), we find

$$\iiint\limits_{V} \frac{\partial A_{1}}{\partial x_{1}} dV = \iint\limits_{S_{2}} A_{1}(x_{1}, x_{2}, x_{3}^{(2)}) \cos(n_{x}, x_{1}) ds + \int\limits_{S_{1}} A_{1}(x_{1}, x_{2}, x_{3}^{(1)}) \cos(n_{x}, x_{1}) ds,$$

or taking the fact into account that at the points S_3

$$\cos(n_1, x_1) = 0$$

we find (the index x at the normal will be dropped in the future)

$$\iiint\limits_V \frac{\partial A_1}{\partial x_1} dV = \iint\limits_S A_1 \cos(n, x_1) ds.$$

After writing analogous equations for the functions ${\bf A}_2$ and ${\bf A}_3$ and combining them, we find ultimately the Gauss divergence theorem

$$\iiint\limits_{V} \sum_{i=1}^{3} \frac{\partial A_{i}}{\partial x_{i}} dV = \iint\limits_{S} \sum_{i=1}^{3} A_{i} \cos(n, x_{i}) ds.$$
 (1.3)

Let us note that Formula (1.3) is valid also for those regions whose boundaries s contain individual lines with points which have no normal n [4]. However, the measure (area) of the set of such points must be equal to zero. As a result, the exclusion of these points will not influence the value of the $\frac{8}{100}$ limit to which the integral sums tend. In practice the boundary s must consist of a finite number of surfaces such that a normal n exists for each interior point.

Let us analyze the adjoint linear differential operations

$$Lu = \sum_{i=1}^{3} \sum_{j=1}^{3} \frac{\partial}{\partial x_{i}} a_{i,j} \frac{\partial u}{\partial x_{j}} + \sum_{i=1}^{3} b_{i} \frac{\partial u}{\partial x_{i}} + cu,$$

$$L^{*}u = \sum_{i=1}^{3} \sum_{j=1}^{3} \frac{\partial}{\partial x_{i}} a_{i,j} \frac{\partial u}{\partial x_{j}} - \sum_{i=1}^{3} \frac{\partial(b_{i}, u)}{\partial x_{i}} + cu.$$

It is not difficult to prove directly that they satisfy the following equations:

$$vLu - uL^*v = \sum_{i=1}^{3} \sum_{j=1}^{3} \frac{\partial}{\partial x_j} a_{i,j} \left(v \frac{\partial u}{\partial x_i} - u \frac{\partial v}{\partial x_i} \right) + \sum_{i=1}^{3} \frac{\partial}{\partial x_i} (b_i uv). \tag{1.4}$$

If we assume that u and v have continuous derivatives up to second order inclusively, by integrating (1.4) and taking Formula (1.3) into account we obtain

$$\iiint_{V} vLu - uL^*v) dV = \iint_{S} \left[\sum_{i=1}^{3} \sum_{j=1}^{3} n_{j}a_{i}, \int_{I} \left(v \frac{\partial u}{\partial x_{i}} - u \frac{\partial v}{\partial x_{i}} \right) + \sum_{i=1}^{3} b_{i}n_{i}uv \right] ds.$$
 (1.5)

Expression (1.5) is called the Green formula. Since we obtain from it the so-called fundamental formula of the theory of harmonic functions, then it is important to know in which instances it remains valid. Let the functions u and v have integrable derivatives of second order which are continuous only inside the region V. Thus, for example, when region V approaches the boundary s, the second derivatives of the functions u and v may increase

without bound, undergoing an infinite discontinuity at the boundary points. It is easy to show [4] that in this case the Green formula remains valid. Let us look at the region V' which is contained inside the region V along with its own boundary s'. Since the left-hand side of Formula (1.5) is integrable, then when $V' \rightarrow V$ the limit of the integral of V' does not depend on the way that V' approaches V and by definition is an integral over the region V. The expression under the sign of the integral in the right-hand side of the Green formula is continuous in the region V up to its boundary. Therefore, when $V' \rightarrow V$ the integral of this expression at the boundary s' of the region V' varies continuously and converges to a limit which may be only the integral over s. But as long as $V' \neq V$, Formula (1.5) is valid; consequently, when $V' \rightarrow V$ its left- and right-hand sides approach the same limit.

When $a_{i,m} = 1$ (i,j = 1,2,3) and $b_{i} = 0$ (i = 1,2,3), if we take into account the fact that the expression

$$\sum_{i=1}^{3} \sum_{j=1}^{3} n_j a_{i,j} \frac{\partial}{\partial x_i} = \sum_{j=1}^{3} n_j \frac{\partial}{\partial x_j} \equiv \frac{d}{dn}$$
/9

in this case represents the differentiation operator in the direction of the outer normal n to s, for the Green formula we find

$$\iiint\limits_{V} (v\Delta u - u\Delta v) dV = \iint\limits_{S} \left(v \frac{\partial u}{\partial n} - u \frac{\partial v}{\partial n} \right) ds. \tag{1.6}$$

In the two-dimensional case, Formulas (1.5) and (1.6) assume, respectively, the following form:

$$\iiint\limits_{V} (vLu - uL^*v) dV = \int\limits_{S} \left[\sum_{i=1}^{2} \sum_{j=1}^{2} n_j a_{i,j} \left(v \frac{\partial u}{\partial x_i} - u \frac{\partial v}{\partial x_1} \right) + \sum_{i=1}^{2} b_i n_i uv \right] ds, \qquad (1.7)$$

$$\iiint\limits_{V} (v\Delta u - u\Delta v) dV = \int\limits_{S} \left(v \frac{\partial u}{\partial n} - v \frac{\partial v}{\partial n} \right) ds. \tag{1.8}$$

§ 2. Fundamental Formula for the Theory of Harmonic Functions.

Let us analyze the function

$$\frac{1}{r} = \frac{1}{\sqrt{\sum_{i=1}^{3} (y_i - x_i)^2}},$$

where y_i and x_i (i - 1,2,3) are coordinates of the two points y and x.

We can show that when $y \neq x$ it satisfies the Laplace equation

$$\Delta \frac{1}{r} = 0.$$

In fact, the following expressions are valid:

$$\frac{\partial}{\partial x_{i}} \frac{1}{r} = \frac{x_{i} - y_{i}}{r^{3}}, \quad \frac{\partial^{2}}{\partial x_{i}^{2}} \frac{1}{r} = -3 \frac{(x_{i} - y_{i})^{2}}{r^{5}} + \frac{1}{r^{3}},$$

from which we find that

$$\Delta \frac{1}{r} = \sum_{i=1}^{3} \frac{\partial^{2}}{\partial x_{i}^{2}} \frac{1}{r} = \frac{3}{r^{3}} - \frac{3}{r^{5}} \sum_{i=1}^{3} (x_{i} - y_{i})^{2} = 0.$$

The function

$$\Gamma(x, y) = \frac{1}{4\pi} \left[\frac{1}{r(x, y)} + \varphi(x, y) \right],$$

where $\varphi(x, y)$ is harmonic with respect to y and continuous along with its first derivatives in the region V, is called the fundamental solution to the Laplace equation in the region V. Let x not belong to the bounded region V. Then, the fundamental solution $\Gamma(x, y)$ is harmonic in this region as a result of $\frac{10}{10}$ which, after substitution into the Green Formula (1.6),

$$v(y) = \Gamma(x, y),$$

we find

$$\iiint\limits_{V}\Gamma\left(x,\ y\right)\Delta u\left(y\right)Vd_{y}=\iiint\limits_{S}\left[\Gamma\left(x,\ y\right)\ \frac{du\left(y\right)}{dn_{y}}-u\,\frac{d\Gamma\left(x,\ y\right)}{dn_{y}}\right]ds_{y},\quad x\in V_{c}.$$

This latter equation for the harmonic function u assumes the following form (below we shall drop the indices at the normal and the variable of integation):

$$\iint \left(\Gamma \frac{du}{dn} - u \frac{d\Gamma}{dn}\right) ds = 0, \quad x \in V_e.$$
 (2.1)

Let us analyze the case when the point x lies inside the region V and denote by W_{ϵ} a sphere with an arbitrarily small radius ϵ with the center at the point x, lying completely in the region V. Using the Green Formula (1.6) in the region V - W_{ϵ} , we obtain

$$\iint_{S} \left(\Gamma \frac{du}{dn} - u \frac{d\Gamma}{dn} \right) ds = \iiint_{V-W_{\mathcal{E}}} \Gamma \Delta u \, dV - \iint_{W_{\mathbf{I}}} \Gamma \frac{du}{dn} \, ds + \iint_{W_{\mathbf{I}}} u \, \frac{d\Gamma}{dn} \, ds, \tag{2.2}$$

where W_1 is the surface of the sphere W_{ϵ} . With regard to the expression for the fundamental function Γ , the third integral in the right-hand side of this latter equation assumes the following form:

$$\iint\limits_{W_1} u \, \frac{d\Gamma}{dn} \, ds = \frac{1}{4\pi} \iint\limits_{W_1} u \, \frac{d\varphi}{dn} \, ds + \frac{1}{4\pi} \iint\limits_{W_2} u \, \frac{d}{dn} \left(\frac{1}{r}\right) \, ds.$$

Taking into account the fact that on the spherical surface W_1 $\frac{d}{dn} = -\frac{d}{dr}$ (n is the outer normal), $r = \varepsilon$, and that the first integral in the right-hand side of the last equation vanishes when $\varepsilon \to 0$, we find

$$\iint_{\widetilde{W}_1} u \frac{d\Gamma}{dn} \cdot ds = \frac{1}{4\pi\epsilon^2} \iint_{\widetilde{W}_1} u ds;$$

or by using the mean value theorem and the equation

$$\iint\limits_{W} ds = 4\pi \, \varepsilon^2,$$

we ultimately find the following asymptotic equation:

$$\lim_{\varepsilon \to 0} \iint_{\widetilde{W}_1} u \frac{d\Gamma}{dn} ds = \lim_{\varepsilon \to 0} \frac{u_{\text{av}}}{4\pi\varepsilon^2} \iint_{\widetilde{W}_1} ds = \lim_{\varepsilon \to 0} u_{\text{av}} = u(x), \tag{2.3}$$

where u is the value of the function u at a certain point belonging to the sphere $W \, \epsilon \, .$

The first integral in the right-hand side of Expression (2.2), when $\epsilon \rightarrow 0$ /11 approaches the improper integral

$$\lim_{\varepsilon \to 0} \iiint_{V \to W_{\varepsilon}} \Gamma \Delta u \, dV - \iiint_{V} \Gamma \Delta u \, dV, \tag{2.4}$$

if this latter exists, and the second integral in the right-hand side of (2.2) vanishes when $\epsilon \rightarrow 0$

$$\lim_{\epsilon \to 0} \iint_{W_1} \Gamma \frac{du}{dn} ds = 0 \tag{2.5}$$

since the derivative $\frac{\partial u}{\partial n}$ is continuous (based on the assumption used in deriving the Green formula) and consequently is bounded, and the function Γ increases when $\epsilon \to 0$ on W_1 as $1/\epsilon$, whereas the area of the surface W_1 decreases as ϵ^2 .

Substituting Equations (2.3) - (2.5) into (2.2) we find

$$\iint_{S} \left(\Gamma \frac{du}{dn} - u \frac{d\Gamma}{dn} \right) ds = \iiint_{V} \Gamma \Delta u \, dV + u \, (x), \quad x \in V - s.$$

This latter equation for the harmonic function u assumes the following form:

$$\iint_{S} \left(\Gamma \frac{du}{dn} - u \frac{d\Gamma}{dn} \right) ds = u(x), \quad x \in V - s.$$
(2.6)

Let us finally analyze the case when the point x is located at the boundary of the surface S. Let us denote by W_{ϵ} the part of the sphere W_{ϵ} which lies in the region V and use the Green Formula (1.6) in the region V - W_{ϵ}

$$\iint_{s-W_2} \left(\Gamma \frac{du}{dn} - u \frac{d\Gamma}{dn} \right) ds = \iint_{V-W_2} \Gamma \Delta u \, dV - \iint_{W_3} \Gamma \frac{du}{dn} \, ds + \iint_{W_3} u \, \frac{d\Gamma}{dn} \, ds, \tag{2.7}$$

where W_2 is the part of the boundary s, lying in the sphere W_{ϵ} ; W_3 is the part of the surface of the sphere W_{ϵ} lying in the region V.

Repeating all the arguments of the previous case, we must have the value of the integral $\iint_{W_3} ds$, equal to the area of the part of the surface

of the sphere W_{ϵ} which lies in the region V. To compute this integral, let us introduce at point x a local system of coordinates ξ_1 , ξ_3 , ξ_4 , with ξ_3 directed along the outer normal to the surface S at point x. We shall assume that the equation for the surface S inside the sphere W_{ϵ} can be written in the form

$$\xi_3 = f(\xi_1, \xi_2),$$
 (2.8)

/12

where the function f and its first-order derivatives are continuous and vanish at point x. We can show [4] that any sufficiently smooth surface can be described in the form of (2.8) in a sphere of sufficiently small radius. Expanding the function $f(\xi_1, \xi_3)$ in a Taylor series in the immediate vicinity of point x and taking into account all first-order terms, we find the following relationship

$$\xi_3 = f'_{\xi_1}(\overline{\xi}_1, \overline{\xi}_2) \xi_1 + f'_{\xi_2}(\widetilde{\xi}_1, \overline{\xi}_2) \xi_2, \tag{2.9}$$

where $|\xi_i| \leqslant |\xi_i| > |\widetilde{\xi}_i|$, $f'_{\xi_i}(\xi_i, \xi_2)$ (i=1, 2) are the values of the derivative of the function f with respect to variable ξ_i at the point (ξ_1, ξ_2) and on the strength of the above, they vanish simultaneously with ξ_1, ξ_2 . Substituting into (2.9) the values ξ_i (i=1, 2, 3), expressed with the aid of the spherical coordinates

 $\xi_1 = r \sin \theta \cos \varphi$, $\xi_2 = r \sin \theta \sin \varphi$, $\xi_3 = r \cos \theta$,

we find

$$\cos \theta = f'_{\xi_1} \sin \theta \cos \varphi + f'_{\xi_2} \sin \theta \sin \varphi = h(r, \theta, \varphi),$$

where h is a function which is bounded and vanishes simultaneously with r, and θ is an angular coordinate of the point on the surface S. Now let us concern ourselves with computing the integral that is of interest to us

$$\frac{1}{4\pi\varepsilon^{2}} \iint_{W_{3}} ds = \frac{1}{4\pi\varepsilon^{2}} \iint_{W_{3}} r^{2} \sin\theta \, d\theta \, d\varphi = \frac{1}{4\pi} \int_{0}^{2\pi} d\varphi \int_{0}^{\overline{0}} \sin\theta \, d\theta = \frac{1}{4\pi} \int_{0}^{2\pi} d\varphi \int_{0}^{\pi/2} \sin\theta \, d\theta + \frac{1}{4\pi} \int_{0}^{2\pi} d\varphi \int_{\pi/2}^{\overline{0}} \sin\theta \, d\theta = \frac{1}{2} + \frac{1}{4\pi} \int_{0}^{2\pi} d\varphi \left[-\cos\theta \right]_{\pi/2}^{\overline{0}} = \frac{1}{2} + \frac{1}{4\pi} \int_{0}^{2\pi} h\left(\varepsilon, \overline{\theta}, \varphi\right) d\varphi = \frac{1}{2} + H\left(\varepsilon\right), \tag{2.10}$$

where

$$H(\varepsilon) = \frac{1}{4\pi} \int_{0}^{2\pi} h(\varepsilon, \overline{\theta}, \varphi) d\varphi$$

is a bounded function which vanishes simultaneously with ϵ . Taking (2.10) into account and using the mean value theorem for the third integral in the right-hand side of (2.7) we find the following asymptotic equation:

$$\lim_{\varepsilon \to 0} \iint_{W_2} u \frac{d\Gamma}{dn} ds = \lim_{\varepsilon \to 0} \frac{u_{\rm cp}}{4\pi\varepsilon^2} \iint_{W_3} ds = \lim_{\varepsilon \to 0} u_{\rm cp} \left[\frac{1}{2} + H(\varepsilon) \right] = \frac{u(x)}{2}.$$

Applying the arguments of the previous case ($s \in V - S$), to the other two integrals in the right-hand side of Expression (2.7), we find the relationship

$$\iint_{V} \left(\Gamma \frac{du}{dn} - u \frac{d\Gamma}{dn} \right) ds = \iiint_{V} \Gamma \Delta u \, dV + \frac{u(x)}{2}, \quad x \in S,$$

which for the harmonic function u takes the form

function u takes the form
$$\iint\limits_{S} \left(\Gamma \frac{du}{dn} - u \frac{d\Gamma}{dn} \right) ds = \frac{u(x)}{2}, \quad x \in S.$$
 (2.11)

After combining Formulas (2.1), (2.6) and (2.11) into one, we find the basic formula for the theory of harmonic functions

$$\iint_{S} \left(\Gamma \frac{du}{dn} - u \frac{d\Gamma}{dn} \right) ds = \begin{cases} 0 & \text{when } x \in V_{e} \\ \frac{1}{2} u(x) & \text{when } x \in S \\ u(x) & \text{when } x \in V - S. \end{cases}$$
 (2.12)

Formula (2.12) remains in force if V is an infinite region with a finite boundary s. For this let us analyze the sphere W of finite radius ρ , containing the boundary s inside itself. The intersection (part) of the regions V and W can be denoted by V*. After using Formula (2.12) in the region V*, we arrive at a formula whose left-hand side will differ in form from the left-hand side of Formula (2.12) in that the integral

$$\iint\limits_{W_{\bullet}} \left(\Gamma \frac{du}{dn} - u \frac{d\Gamma}{dn} \right) ds, \tag{2.13}$$

is added to it, where $\mathbf{W}_{\mathbf{\Delta}}$ is the surface \mathbf{W} of the sphere.

To prove that this integral equals zero, we must know the asymptotic behavior of the harmonic functions at infinity [4]: the function u, which is harmonic in the infinite region, satisfies the inequality

$$|u(x)| < \frac{A}{r}, \left|\frac{\partial u}{\partial x_i}\right| < \frac{A}{r^2} \quad (i=1, 2, 3),$$
 (2.14)

where

$$r = \sqrt{\sum_{i=1}^{3} x_i^2}.$$

Inequality (2.14) is a simple corollary of Kelvin's theorem [4]. Taking (2.14) into account and determining the fundamental solution, we conclude that when $\rho \to \infty$ the integrand in (2.13) decreases as $1/\rho^3$, whereas the area of the surface W_4 of the sphere W increases as ρ^2 . Passing to the limit when $\rho \to \infty$, we again find Formula (2.12).

In the two-dimensional case, the function

$$\Gamma(x, y) = \frac{1}{2\pi} \left[\ln \frac{1}{r(x, y)} + \varphi(x, y) \right],$$
 (2.15)

is called the fundamental solution to the Laplace equation, where r(x,y) is the distance between points x and y on the plane, and $\varphi(x,y)$ is a function which is harmonic in the two-dimensional region V with respect to the coordinates of the point y. It is easy to prove that when $x \neq y$ the function $\ln 1/r$ is $\frac{14}{4}$ harmonic for the coordinates of points x and y.

The fundamental formula of the theory of harmonic functions for the two-dimensional bounded region V has the following form:

$$\int_{s} \left(\Gamma \frac{du}{dn} - u \frac{d\Gamma}{dn} \right) ds = \begin{cases} 0 & \text{when } x \in V_{e} \\ \frac{1}{2} u(x) & \text{when } x \in s. \\ u(x) & \text{when } x \in V - s. \end{cases}$$
 (2.16)

It is derived completely in analogy with Equation (2.12), and therefore, we shall not give its derivation.

In the two-dimensional case, we must especially analyze [4] the case of the infinite region with a finite boundary s. Let us look at the finite region V_1 , included between the boundaries S and C, where C is a circle of radius a with the center at the origin, encompassing S. Let us use Formula (2.6) in the region V_1

Tegron
$$v_1$$

$$\frac{1}{2\pi} \int_{s} \left(\frac{du}{dn} \ln \frac{1}{r} - u \frac{d}{dn} \ln \frac{1}{r} \right) ds + \frac{1}{2\pi} \int_{c} \left(\frac{du}{dn} \ln \frac{1}{r} - u \frac{d}{dn} \ln \frac{1}{r} \right) ds =$$

$$= \begin{cases} 0 & \text{when } x \in R - V_1 \\ \frac{1}{2} u(x) & \text{when } x \in S + C \\ u(x) & \text{when } x \in V. \end{cases}$$
where R is the entire plane.

If we assume that $\frac{du}{dn} \ln \frac{1}{r}$ vanishes no more slowly than

$$\frac{\ln(x_1^2+x_2^2)}{x_1^2+x_2^2},$$

we find that

$$\lim_{a \to \infty} \int_{C} \frac{du}{dn} \ln \frac{1}{r} ds = 0.$$
 (2.18)

Since on the circle $C \frac{d}{dn} \ln \frac{1}{r} = -\frac{1}{a}$, then the integral

$$-\frac{1}{2\pi} \int\limits_C u \, \frac{d}{dn} \ln \frac{1}{r} \, ds$$

approaches the "mean value of the function at infinity"

$$u_{\infty} = \lim_{a \to \infty} \frac{1}{2\pi a} \int_{C} u ds. \tag{2.19}$$

as $a \rightarrow \infty$.

Substituting Formulas (2.18) and (2.19) into (2.17), we find the fundamental formula for the harmonic functions in the infinite two-dimensional region

$$\frac{1}{2\pi} \int_{s} \left(\frac{du}{dn} \ln \frac{1}{r} - u \frac{d}{dn} \ln \frac{1}{r} \right) ds + u_{\infty} = \begin{cases} 0 \text{ when } x \in R_2 - V \\ \frac{1}{2} u(x) \text{ when } x \in s \\ u(x) \text{ when } x \in V. \end{cases}$$
 (2.20) /15

Substituting into Formula (2.12) the values

$$u=1, \Gamma=\frac{1}{4\pi}\frac{1}{r},$$

we find the Gauss formula

$$\iint_{S} \frac{d}{dn} \frac{1}{r} ds = \begin{cases} -4\pi & \text{when } x \in V \\ -2\pi & \text{when } x \in S \\ 0 & \text{when } x \in V_{e}. \end{cases}$$
 (2.21)

In the two-dimensional case, the Gauss formula has the form

$$\int_{S} \frac{d}{dn} \ln \frac{1}{r} ds = \int_{S} \frac{\cos \varphi}{r} ds = \begin{cases} -2\pi & \text{when } x \in V \\ -\pi & \text{when } x \in S \\ 0 & \text{when } x \in V_{e}, \end{cases}$$
 (2.22)

where ϕ is the angle between directions n and r.

Let us denote by

$$\frac{du(\xi)}{dn_e}$$
, $\frac{du(\xi)}{dn_i}$

the limiting values of the derivatives of $u(x) = \iint \frac{\rho}{r} ds$ in the direction of the normal when the point x approaches $\xi \in S$ from outside S and from inside S respectively and by du/dn_0 the value of the derivative with respect to the normal of the expression for the potential of a single layer (2.23) at the point $x = \xi \in S$.

The values $\mathrm{du}(\xi)/\mathrm{dn}_{e}$ and $\mathrm{du}(\xi)/\mathrm{dn}_{i}$ are called [4], respectively, the outer and inner normal derivative of the potential of a single layer at the point ξ , and the value $\mathrm{du}/\mathrm{dn}_{0}$ is the true value of the normal derivative at this same point. If we use the continuity at point ξ of the Expression [4]

$$\iint\limits_{S} \rho \frac{d}{dn_0} \frac{1}{r} ds - \rho_0 \iint\limits_{S} \frac{d}{dn} \frac{1}{r} ds,$$

where d/dn_0 is differentiation with respect to the outer normal to s at point ξ , d/dn is differentiation with respect to the outer normal at a variable point of the surface S, $\rho_0 = \rho(\xi)$ and taking into account the Gauss Formula (2.21), we find

$$\frac{du(\xi)}{dn_c} = \frac{du(\xi)}{dn_0} - 2\pi\rho(\xi),$$

$$\frac{du(\xi)}{dn_i} = \frac{du(\xi)}{dn_0} + 2\pi\rho(\xi).$$
(2.24) /16

In the two-dimensional case, the analogous relationships have the form

$$\frac{du(\xi)}{dn_e} = \frac{du(\xi)}{dn_0} - \pi \rho(\xi),$$

$$\frac{du(\xi)}{dn_l} = \frac{du(\xi)}{dn_0} + \pi \rho(\xi).$$
(2.25)

§ 3. Some Concepts of Functional Analysis

Let us introduce some concepts [7] of functional analysis, which will be used in the future.

The set R of elements x, y, z... is termed linear, if in it we define the operations of addition, denoted by a "+" sign and multiplication by numbers (real or complex), which do not go beyond the limits of R and which satisfy the following conditions:

- 1. Addition is associative, i.e., (x + y) + z = x + (y + z).
- 2. There exists a zero element 0 such that x + 0 = 0 + x = x for any $x \in R$.
- 3. Addition is commutative: x + y = y + x.
- 4. $(\alpha + \mu) x = \alpha x + \mu x$.
- 5. $\alpha(x+y) = \alpha x + \alpha y$.
- 6. $\alpha(\mu x) = (\alpha \mu) x$.
- 7. $1 \cdot x = x$.

Here the Latin letters denote elements of R, and the Greek letters denote numbers.

We shall say that scalar product is defined in the linear set R if corresponding to each pair of its elements x and y, taken in a given order, there is a complex number (x, y), this number is called the scalar product of these elements and satisfies the following conditions:

1. The scalar products (x,y) and (y,x) are complex conjugate numbers

$$(x, y) = (\overline{y, x}).$$

2. For any elements x, y, $z \in R$ and any complex numbers α_1 and α_2 the following equation is valid

$$(\alpha_1 x + \alpha_2 y, z) = \alpha_1 (x, z) + \alpha_2 (y, z).$$

3. The scalar product of the element x by itself is a nonnegative number, equal to zero only when x = 0, i.e., $(x, x) \ge 0$.

The set R is called a metric space if for any two of its elements x and y $\frac{17}{17}$ the concept of distance $\rho(x, y)$ is defined to satisfy the following conditions:

- 1. $\rho(x, y) > 0$ and $\rho(x, y) = 0$ when and only when x coincides with y.
- 2. $\rho(x, y) = \rho(y, x)$.
- 3. $\rho(x, y) < \rho(x, z) + \rho(z, y)$ for any three elements x, y, z, belonging to R (triangle axiom).

The set D of metric space R is termed dense in the set $D_0 \subset R$, if for each $x \in D_0$ and $\varepsilon > 0$ there is a point $z \in D$ such that $\rho(x, z) < \varepsilon$. It is clear that the concept of density is transitive [11], if D is dense in D_0 and D_1 is dense in D, then D_1 is dense in D_0 . Here, of course, it is assumed that the metrics are fixed.

Metric space is called separable, if it includes a denumerable dense subset.

The linear set R is called a normalized space if to each element $x \in R$ a real number ||x|| > 0 is associated; this number is called the norm of the elements x, and the following conditions are satisfied:

- 1. ||x|| = 0 when and only when x = 0.
- 2. $\|\lambda x\| = |\lambda| \|x\|$.
- 3. ||x+y|| < ||x|| + ||y||.

The sequence $\{x_n\}$ of points of metric space R is called self-convergent if $\rho(x_m, x_n) \to 0$ when $m, n \to \infty$, i.e., $\rho(x_m, x_n) < \varepsilon$ when $m, n > N_{\varepsilon}$.

The metric space R is called complete if each self-convergent sequence $\{x_n\}$ converges, i.e., a point $x_0 \in R$ exists such that $x_n \to x_0$.

The normalized space R is called unitary if in it we can introduce a scalar product associated with the norm by the relationship

$$||x|| = V(\overline{x, x}).$$

The complete unitary space is called a Hilbert space (1).

For interpolation of the spaces L^p we must have the concept of a measurable function and a measurable set. Here we shall assume that we know the concept of the outer measure [8] of the set.

The set R is called measurable if it can be closed by an open set D such that the outer measure of the difference R - D is as small as desired.

The function f(p) given on the measurable set R is called measurable if for any real a the sets $D[f \ge a]$; D[f < a]; D[f > a]; $D[f \le a]$ are measurable. The symbol $D[f \ge a]$ denotes a set of those points R for which the condition contained in the brackets is satisfied.

By the space $L^p(s)$ we mean a set of all measurable functions given on the measurable set S, the Rth power of the modulus of which is integrable in the Lebesgue sense, i.e., if $f \in L^p$, then $|f|^p \in L(s)$. The norm in the space $L^p(s)$ is interpolated from the formula

/18

$$N_p(f) = \| f \|_p = \left(\iint |f|^p dx \right)^{\frac{1}{p}}.$$

⁽¹⁾ Sometimes [5] the following definitions are used: the linear space R is called a Hilbert space if it is separable and if a scalar product is introduced in it. This definition is not equivalent to that given above. In [7] and [10] examples of nonseparable Hilbert spaces are cited.

It satisfies the following inequality:

$$N_1(f, g) < N_p(f) N_{p'}(g),$$

where p and p' are adjoint indices: 1/p + 1/p' = 1 is the Hölder inequality [8] (when p = 2 it is the Buniakowski-Schwartz inequality);

$$N_{p}(f+g) < N_{p}(f) + N_{p}(g)$$

is the Minkowski inequality [8].

When $p \rightarrow \infty$

$$N_{p}(f) \rightarrow \text{Max } |f|,$$

where Max |f| denotes the intrinsic upper bound [11] of |f|, i.e., the least value of n such that $|f| \le \eta$ almost everywhere. Therefore, L^{∞} is denotes as a class of intrinsically bounded functions or functions of equivalent (2) bounded functions. Let us note that in the space C of all continuous functions of the norm $N_C(f) = \text{Max } |f|$, $N_C(f) = \text{Max } (f)$ is also defined but here Max is the ordinary maximum.

The set of all possible elements such as $\sum\limits_{i=1}^n \lambda_i \varphi_i$, where λ_i are arbitrary real numbers, is called the span of the system $\{\phi_n\}$.

When n = 1, 2, ..., let $\{\phi_n(s)\}$ represent a system of nonzero functions of $L^2(s)$. If

$$(\varphi_m, \varphi_n) = \iint_S \varphi_m \, \varphi_n \, ds = 0$$

⁽²⁾ The functions f and g are called equivalent if f = g almost everywhere.

when m \neq n, then we say that $\{\varphi_{n}^{}\}$ is an orthogonal system on s. If furthermore,

$$\cdot (\varphi_n, \varphi_n) = \iint_{S} |\varphi_n|^2 ds = (\|\varphi_n\|_2)^2 = 1$$

for all n, then we say that $\{\phi_n\}$ forms an orthogonal normalized (orthonormalized) system on S.

The system $\{\phi_n(s)\}$ is called [11] complete in $L^p(S)$, where $1 \le p \le \infty$, or in C if no nonzero function exists from $L^p(s)$ or C(s) that is orthogonal to each ϕ_n , i.e., if for $f \in L^p(s)$ ($f \in C(s)$),

$$\iint\limits_{S} f \varphi_n ds = 0 \qquad (n = 1, 2...)$$

we imply $f \equiv 0$. Since, if $f \in L^q(s)$, then $f \in L^p(s)^1$ (3), where 'b $\stackrel{-}{>}$ d; then from the definition of completeness it follows that if $\{\phi_n\}$ is complete in $L^p(s)$ then it is complete in C and $L^q(s)$ when q < p.

/19

The system $\{\phi_n\}$ of functions from $L^p(s)$ (or C) is called [11] closed in $L^p(s)$ (or C) if the span of the system $\{\phi_n\}$ is dense in $L^p(s)$ (or C).

The following statement will be used often and therefore, we formulate it as a theorem.

$$\iint_{S} |f|^{p} ds = \iint_{S_{1}(|f| \le 1)} |f|^{p} ds + \iint_{S_{2}(|f| > 1)} |f|^{p} ds < |s| + A,$$

where |s| is the size of the set s, and

$$A=\iint\limits_{S}|f|^{q}\,ds<\infty.$$

⁽³⁾ For proof of this assumption consider the integral

Theorem 3.1. An orthonormalized system $\varphi_i(M)$, obtained from a complete (closed) system, is complete (closed).

Let us prove the following theorem [11].

Theorem 3.2. If $\Phi_n = \sum_{m=0}^n \gamma_m \, \varphi_m$ is a certain polynomial of the orthonormalized system $\{\varphi_n\}$, then

$$N_2^2(f-\Phi_n) = N_2^2(f) - \sum_{m=0}^n C_m^2 + \sum_{m=0}^n (C_m - \gamma_m)^2,$$

where C_m are Fourier coefficients of the function f for the system $\{\phi_n\}$. Considering the easy-to-prove equations

$$\iint\limits_{S} f \Phi_n ds = \sum_{m=0}^{n} C_m \gamma_m, \iint\limits_{S} \Phi_n^2 dx = \sum_{m=0}^{n} \gamma_m^2,$$

we obtain

$$N_{2}^{2}(f-\Phi_{n})=N_{2}^{2}(f)-2\sum_{m=0}^{n}C_{m}\gamma_{m}+\sum_{m=0}^{n}\gamma_{m}^{2}=N_{2}^{2}(f)-\sum_{m=0}^{n}C_{m}^{2}+\sum_{m=0}^{n}(C_{m}-\gamma_{m})^{2}.$$

The following theorems are a direct consequence of the proved theorem.

Theorem 3.3. Of all the polynomials Φ_n of a given order the best mean square approximation of the function is given by the Fourier polynomial

$$f_n = \sum_{m=0}^n C_m \varphi_n \quad \text{and the following expressions are valid}$$

$$N_2^2 = (f - f_n) = N_2^2(f) - \sum_{m=0}^n C_m^2,$$

$$\sum_{m=0}^\infty C_m^2 < N_2^2(f) = \iint_S f^2 ds.$$

The following important theorem, which is given without proof, will be used below.

Theorem 3.4 (Ritz-Fisher) [11]. Let $\sum_{n=0}^{\infty} C_n^2 < \infty$. Then a function f exists from L²(s) which has its own Fourier coefficients C_n. Furthermore, in the sense of the metric L²(s), i.e.,

$$\iint\limits_{S} (f_n - f)^2 \, ds \to 0 \tag{3.1}$$

and

$$\iint_{S} f^{2} ds = \sum_{n=0}^{\infty} C_{n}^{2}.$$
 (3.2)

Theorem 3.5 is a direct corollary of the Ritz-Fisher theorem.

Theorem 3.5. If the orthonormalized system $\{\varphi_n\}$ is complete, $f \in L^2(s)$ and $C_n (n = 1, 2, ...)$ is a Fourier coefficient of the function f for the system $\{\varphi_n\}$, then f and C_n satisfy (3.1) and (3.2).

In fact on the strength of Theorem 3.3 $\sum_{n=0}^{\infty} C_n^2 < \infty$ and f is equivalent to the function f in the Ritz-Fisher theorem.

Let us prove that closure and completeness of equivalent in $L^2(s)$.

Theorem 3.6. The system of functions from $L^2(s)$ is closed when and only when it is complete.

On the strength of Theorem 3.1, it is sufficient to prove equivalence for the system $\{\varphi_n\}$, obtained after orthonormalization.

Let $\{\varphi_n\}$ be complete and $f \in L^2$, then according to Theorem 3.5, $f_n \rightarrow f$ in the sense of the metric L^2 (s). Hence, on the strength of the definition, the closure follows.

Let $\{\varphi_n\}$ be closed and all Fourier coefficients of the function be equal to zero. We must prove that $f\equiv 0$ (completeness). Since $\{\varphi_n\}$ is closed, then a sequence of polynomials Φ_n exists such that $\Phi_n\to f$ in the sense of the metric

L²(s), i.e., $N_2(f-\Phi_n)\to 0$, but on the strength of Theorem 3.3, $N_2(f-f_n)=0$. But $f_n=0$ and therefore, $N_2(f)=0$, $f\equiv 0$ and the completeness of the system $\{\varphi_n\}$ is proved.

Let us give without proof analogous theorems for the spaces \textbf{L}^p which will be used below.

Theorem 3.7. [11]. If $1 and <math>\{\varphi_n\}$ is closed in $L^p(s)$, then it is complete in $L^p(s)$.

Theorem 3.8 [11]. If $1 < \rho < \infty$ and $\{\varphi_n\}$ is complete in $L^p(s)$, then it is closed in $L^{p'}$.

When p = 1 Theorem 3.8 is not valid.

Below we shall use the following Theorem [11].

Theorem 3.9. If $l , then the sets of functions of the space <math>L^q(s)$ $(p < q < \infty)$, and also the sets of bounded B(s), of continuous C(s) which have a continuous k^{th} derivative of the C_k function are complete in $L^p(s)$.

Using Theorem 3.9, we can prove the following theorem.

/21

Theorem 3.10. If the system $\{\varphi_i(M)\}$ is closed in $L^p(s)$ and 1 < q < p, then the system $\{\varphi_i(M)\}$ is also closed in $L^q(s)$. For proof let us look at the mean value of the function f in the interval (a,b) with the index p [11].

$$M_{p}(f) = \left(\frac{1}{b-a} \iint_{S} |f|^{p} dx\right)^{\frac{1}{p}}.$$

The mean values have the property [11]

$$M_q(f) \le M_p(f)$$
 when $q < p$.

Let us note that the norm N $_p$ (f) does not have this property. Let $f \in L^q(s)$; then according to Theorem 3.9 we find such a function $g \in L^p(s)$ that $N_q(f-g) < \frac{1}{2} \epsilon$. But $\{\varphi_i(M)\}$ is closed in $L^p(s)$ and therefore, there exists such a polynomial ψ , that

$$N_p(g-w)<\frac{1}{2}\varepsilon(b-a)^{\frac{1}{p}-\frac{1}{q}}.$$

If we take into account the trivial equation

$$N_{p}(f) = (b-a)^{\frac{1}{p}} M_{p}(f)$$

and the mean value property, we find

$$N_q(f) < (b-a)^{\frac{1}{q} - \frac{1}{p}} N_p(f).$$

Therefore, considering Minkowski's inequality, we have

$$N_q(f-w) \leq N_q(f-g) + N_q(g-w) < \frac{1}{2} \varepsilon + (b-a)^{\frac{1}{q} - \frac{1}{p}} N_p(g-w) < \varepsilon.$$

Let us note that if $\{\varphi_n\}$ is closed in $C(s_1)$, then it also is closed in $L^p(s)$ when $1 (but not necessarilly closed in <math>L^\infty$).

Let G be a certain subspace of the Hilbert space R, formed by the system $\{\varphi_i\}$ (G is the span of the system $\{\varphi_i\}$). We can prove the following theorem.

Theorem 3.11 [10]. If there exists in G an element (vector) y, which is the least distance from $x \in R$ (x does not belong to G), then the vector x-y is orthogonal to each vector g from G, i.e.,

$$(x-y, g)=0$$
 $(g \in G)$

and in the case of a finite-dimensional subspace G, formed by the linearly independent vectors φ_1 , φ_2 ,..., φ_n for the square of the error with which the vector y approximates the vector x, we have

$$\delta^{2} = \min_{\alpha_{k}} \|\bar{x} - \alpha_{1} \varphi_{1} - \alpha_{2} \varphi_{2} - \cdots - \alpha_{n} \varphi_{n}\|^{2} = \frac{G(x, \varphi_{1}, \varphi_{2}, \dots, \varphi_{n})}{G(\varphi_{1}, \varphi_{2}, \dots, \varphi_{n})},$$
(3.3)

where

 $y = \sum_{i=1}^{n} \alpha_{i} \varphi_{i},$ $G(\varphi_{1}, \varphi_{2}, ..., \varphi_{n}) = \begin{vmatrix} (\varphi_{1}, \varphi_{1}), & (\varphi_{2}, \varphi_{1}) & ... & (\varphi_{n}, \varphi_{1}) \\ (\varphi_{1}, \varphi_{2}) & (\varphi_{2}, \varphi_{2}) & ... & (\varphi_{n}, \varphi_{2}) \\ ... & ... & ... & ... \\ ... & ... & ... & ... \\ (\varphi_{1}, \varphi_{n}) & (\varphi_{2}, \varphi_{n}) & ... & (\varphi_{n}, \varphi_{n}) \end{vmatrix}$

is the Gram determinant of the system of vectors $\varphi_1, \varphi_2, \ldots, \varphi_n$.

Let us assume that a vector f exists in G for which

$$(x-y, f)=r \neq 0,$$

and analyze the vector

$$z=y+\frac{r}{(f, f)}f\in G.$$

For z we have

$$\|x-z\|^2 = (x-y-\frac{r}{(f, f)}f, x-y-\frac{r}{(f, f)}f) = \|x-y\|^2 - \frac{|r|^2}{(f, f)} < \|x-y\|^2$$

and the resultant contradiction (on the assumption that y is a near point to x) proves the first part of the theorem. For proof of (3.3) we write in detail the equations

$$(x-y, \varphi_k)=0,$$
 $k=(1, 2, ..., n),$ (3.4)

using the expression for y,

$$\sum_{i=1}^{n} \alpha_i (\varphi_i, \ \varphi_h) = (x, \ \varphi_h), \ k = (1, \ 2, \dots, \ n).$$
 (3.5)

Taking (3.4) into account, for δ^2 we find

$$\delta^2 = (x - y, x - y) = (x - y, x) - (x - y, y) = (x - y, x) = (x, x) - (y, x),$$

or expanding the expression (y,x)

$$(x, x) - \delta^2 = \sum_{i=1}^n \alpha_i (\varphi_i, x).$$

Combining (3.6) with System (3.5) we find a system of n+1 equations with n unknowns $(\alpha_1, \alpha_2, ..., \alpha_n)$.

To solve this system it is necessary and sufficient that the ${\sf rank}$ of its matrix be equal to the rank of the resolved matrix

$$A = \left| \begin{array}{c} (\varphi_{1}, \ \varphi_{1}) \ \dots \ (\varphi_{n}, \ \varphi_{1}) \ (x, \ \varphi_{1}) \\ \vdots \\ (\varphi_{1}, \varphi_{n}) \ \dots \ (\varphi_{n}, \ \varphi_{n}) \ (x, \ \varphi_{n}) \\ (\varphi_{1}, \ x) \ \dots \ (\varphi_{n}, \ x) \ (x, \ x) - \hat{o}^{2} \end{array} \right| \cdot$$

Hence we find that A = 0 and

/23

$$\delta^2 = \frac{G(x, \varphi_1, \varphi_2, \dots, \varphi_n)}{G(\varphi_1, \varphi_2, \dots, \varphi_n)}.$$
(3.7)

We can prove that

$$G(\varphi_1, \varphi_2, \dots, \varphi_n) < G(\varphi_1, \varphi_2, \dots, \varphi_m) G(\varphi_{m+1}, \varphi_{m+2}, \dots, \varphi_n),$$
 (3.8)

where m < n and $\varphi_1, \varphi_2, \ldots, \varphi_n$ are linearly independent vectors.

It is obvious that

$$\min_{\alpha} \| \varphi_k - \alpha_{k+1} \varphi_{k+1} - \cdots - \alpha_n \varphi_n \| < \min_{\beta} \| \varphi_k - \beta_{k+1} \varphi_{k+1} - \cdots - \beta_m \varphi_m \|$$

and

$$\min \| \varphi_m - \alpha_{m+1} \varphi_{m+1} - \cdots - \alpha_n \varphi_n \| < \| \varphi_m \|.$$

Taking into account these latter inequalities, from (3.7) we find

$$\frac{G(\varphi_{h}, \varphi_{h+1}, \dots, \varphi_{n})}{G(\varphi_{h+1}, \dots, \varphi_{n})} < \frac{G(\varphi_{h}, \varphi_{h+1}, \dots, \varphi_{m})}{G(\varphi_{h+1}, \dots, \varphi_{m})},$$

$$\frac{G(\varphi_{m}, \varphi_{m+1}, \dots, \varphi_{n})}{G(\varphi_{m+1}, \dots, \varphi_{n})} < G(\varphi_{m}).$$
(3.9)

Since $G(\varphi_i, \varphi_{i+1}, ..., \varphi_i) > 0$ (j < 1), then (3.9) can be written in the form

$$\frac{G(\varphi_{h}, \varphi_{h+1}, \ldots, \varphi_{n})}{G(\varphi_{h}, \varphi_{h+1}, \ldots, \varphi_{m})} < \frac{G(\varphi_{h+1}, \varphi_{h+2}, \ldots, \varphi_{n})}{G(\varphi_{h+1}, \varphi_{h+2}, \ldots, \varphi_{m})} \quad (k=1, 2, \ldots, m-1).$$

Thus,

$$\frac{G(\varphi_1,\ldots,\varphi_n)}{G(\varphi_1,\ldots,\varphi_m)} \leqslant \frac{G(\varphi_2,\ldots,\varphi_n)}{G(\varphi_2,\ldots,\varphi_m)} \leqslant \ldots \leqslant \frac{G(\varphi_m,\ldots,\varphi_n)}{G(\varphi_m)} \leqslant G(\varphi_{m+1},\ldots,\varphi_n).$$

§4. <u>Linear Independence and Completeness of Several Systems</u> of Harmonic Functions.

Proof of convergence of the approximate method discussed below for solving the Problem (1.1) - (1.2) is based on the linear independence and completeness of a certain system of harmonic functions. Therefore, we shall give several proofs for completeness of this system.

Let G_1 be a region with a sufficiently smooth boundary S (it is sufficient, for example, that S_1 be a Lyapunov surface (4)) which completely includes the

⁽⁴⁾ All the material discussed below is valid also for the two-dimensional region. In the latter case only the System [1-3] of functions $\{|nr(M_0,M)|\}$ which differs from (4.1) is analyzed.

region G and the minimal distance from S to \mathbf{S}_1 be greater than zero, i.e., the surface \mathbf{S}_1 is not tangent to the surface S.

Let us introduce the definition:

$$\frac{1}{r(M_i, M)} = \omega_i(M) \quad (i = 1, 2, ...), \tag{4.1}$$

where $M_i \in S_1$ are elements of the denumerable set of points which are everywhere dense on the surface S_1 .

Theorem 4.1 The system of functions $\{\omega_i(M)\}$ is linearly independent on the curve S, i.e., for any N from the equation /24

$$\sum_{i=1}^{N} C_i \omega_{k_i}(M) \equiv 0, \quad M \in S$$
(4.2)

it follows that

$$\sum_{i=1}^{N} |C_i| = 0,$$

where all k are whole numbers.

Let us assume the opposite: let there be found such bounded number C_i which are not all equal to zero that for a certain N Expression (4.2) is satisfied and a certain $C_r \neq 0$ ($r \leq N$). From (4.2) and the theorem of uniqueness for the Dirichlet problem it follows that

$$\sum_{i=1}^{N} C_i \, \omega_{k_i}(M) \equiv 0, \quad M \in \overline{G} = G + S, \tag{4.3}$$

and from the analyticity of the left-hand side of (4.3) it follows that

$$\sum_{i=1}^{N} C_i \, \omega_{k_i}(M) \equiv 0, \quad M \in G_1.$$
 (4.4)

Let M approach M_k . Then $|C_r\omega_{k_r}|\to\infty$, and all other terms in (4.4) remain bounded, thus contradicting Equation (4.4) and consequently our assumption that $C_r \neq 0$.

From Theorem 4.1 there follows the validity of the following theorem.

Theorem 4.2. We can construct such a system of functions $\{\varphi_i(M)\}$ orthonormalized on S such that

$$\varphi_{i}(M) = \sum_{k=1}^{i} A_{i,k} \omega_{k}(M), \qquad (4.5)$$

where $A_{i,k}$ are the coefficients of orthonormalization.

The system $\{\varphi_i(M)\}$ can be constructed [5] successively. Since the system $\{\omega_i(M)\}$ is linearly independent, then

$$\iint_{S} \varphi_{i}^{2} ds > 0 \qquad (i = 1, 2, ...).$$

Therefore, we have

$$\varphi_1(M) = \frac{\omega_1(M)}{\sqrt{\iint\limits_{S} \varphi_1^2 ds}}.$$

It is clear that $\varphi_1(M)$ is normalized. Let us construct the elements $\overline{\varphi}_2(M) = \omega_2(M) + \alpha_{2,1} \varphi_1$ orthogonal to φ_1

$$\iint\limits_{S} \varphi_1 \overline{\varphi_2} ds = \iint\limits_{S} \varphi_1 \omega_2 ds + \alpha = 0.$$
 (25)

For $\alpha_{2,1}$ we find the equation

$$\alpha_{2,1} = \iint\limits_{S} \varphi_1 \omega_2 \, ds.$$

From the linear independence of the system $\{\omega_i(M)\}$ it directly follows that

$$\iint\limits_{s} \overline{\varphi_2^2} \, ds > 0.$$

Therefore, we have

$$\varphi_2 = \frac{\overline{\varphi_2}}{\sqrt{\iint\limits_{S} \overline{\varphi_2^2} \ ds}},$$

which guarantees both normalization of the element φ_2 and orthogonality of φ_1 and φ_2 . Let us construct the orthonormalized elements $\varphi_1, \varphi_2, \dots, \varphi_k$. The next element will be sought in the form

$$\varphi_{k+1} = \frac{\overline{\varphi}_{k+1}}{\sqrt{\iint_{S} \overline{\varphi}_{k+1}^{2} ds}},$$
(5.6)

where

$$\bar{\varphi}_{k+1} = \omega_{k+1} + \alpha_{k+1,1} \, \varphi_1 + \cdots + \alpha_{k+1,k} \, \varphi_k. \tag{4.7}$$

The coefficients $\alpha_{k+1,\;i}$ $(i=1,\,2,\,\ldots,\;k)$ are determined from the condition of orthogonality $\iint\limits_s \overline{\varphi}_{k+1}\,\varphi_i\,ds=0$ $(i=1,\,2,\ldots,\;k)$. We find

$$\alpha_{k+1, i} = \iint_{S} \omega_{k+1} \, \varphi_i \, ds.$$

From Expression (4.7), if we take into account that $\varphi_1, \varphi_2, \ldots, \varphi_k$ do not contain ω_{k+1} , it follows that the denominator of the right-hand side of (4.6) is nonzero. Thus, we construct any element of the orthonormalized system $\{\varphi_i(M)\}$. To obtain Expression (4.5) we must substitute the values $\varphi_1, \varphi_2, \ldots, \varphi_k$, into (4.6) expressed through $\omega_1, \omega_2, \ldots, \omega_k$. Theorem 4.2 is proved.

The algorithm described above gives $\varphi_l(M)$ in the following form:

$$\varphi_{l}(M) = \sum_{k=1}^{i-1} \bar{A}_{i, k} \varphi_{k} + \bar{A}_{i, i} \omega_{i+1}.$$
 (4.8)

As will be shown in §5, of this Chapter [for the discussed approximate method $\varphi_l(M)$] we must bear in mind (4.5) because $A_{i,k}$ directly participates in the algorithm of the solution. From (4.8), we can obtain the coefficients

 A_{ik} of Expression (4.5). In fact, it is easy to prove the following expression:

$$A_{i, i} = \overline{A}_{i, i}, A_{i, k} = \sum_{i=k}^{i-1} \overline{A}_{i, j}.$$
 (4.9)

Since in any computer center there are standard subprograms for computing the $\frac{/26}{1}$ integral with any preassigned accuracy and for computing the determinant, then from the viewpoint of simplicity of carrying out machine computation, the following algorithm for computing the coefficients $A_{i,k}$ possesses a certain advantage over that described above. $A_{i,k}$ are computed from the following expression [6].

where G is the Gram determinant of the functions $\omega_1,\;\omega_2,\;\ldots,\;\omega_n$

$$G_{n} = \left| \begin{array}{c} \iint \omega_{1}^{2} ds, \iint \omega_{1} \omega_{2} ds, \dots, \iint \omega_{1} \omega_{n} ds \\ \iint \omega_{1} \omega_{2} ds, \iint \omega_{2}^{2} ds, \dots, \iint \omega_{2} \omega_{n} ds \\ \vdots \\ \vdots \\ \iint \omega_{n} \omega_{1} ds, \iint \omega_{n} \omega_{2} ds, \dots, \iint \omega_{n}^{2} ds \end{array} \right|$$

$$(4.11)$$

The integrals in (4.10) and (4.11) are taken on the surface S.

Let us prove the following assumption.

Theorem 4.3. The Gram Determinant (4.11) for the linearly independent system $\{\omega_i(M)\}$ is nonzero.

Let us assume the opposite. Let $G_n=0$. We can analyze the system of linear equations relative to $\alpha(\alpha_1,\,\alpha_2,\,\ldots,\,\alpha_n)$ written in vector form

$$G_n \alpha = 0. \tag{4.12}$$

Since the determinant of this system is equal to zero, then there exists a nontrivial solution $\alpha(\alpha_1,\ \alpha_2,\dots,\ \alpha_n)$.

Let us show that

$$\delta = \iint_{S} \left(\sum_{i=1}^{n} \alpha_{i} \omega_{i} \right)^{2} ds = 0. \tag{4.13}$$

In fact

$$\delta = \sum_{j=1}^{n} \alpha_{j} \sum_{i=1}^{n} \alpha_{i} \iint_{S} \omega_{i} \omega_{j} ds.$$

But since $\alpha_1, \alpha_2, ..., \alpha_n$ are nontrivial solutions to System (4.13), it is then $\frac{/27}{}$ clear that

$$\sum_{i=1}^{n} \alpha_{i} \iint_{S} \omega_{i} \omega_{j} ds = 0 \qquad (j=1, 2, \ldots, n)$$

and therefore $\delta = 0$ or

$$\sum_{i=1}^n \alpha_i \, \omega_i = 0.$$

The resultant contradiction (linear dependence of the system $\{\omega_i(M)\}$) proves Theorem 4.3.

However, we must note that with the approximate method (with a finite number of digits) for accomplishing the above algorithms the first approach possesses a substantial advantage. This problem will be analyzed below.

Let us prove the following theorem.

Theorem 4.4. The orthonormalized system of functions $\{\varphi_i(M)\}$ is closed in the space $L^2(s)$ of the square-integrable functions given on the boundary S.

First let us prove the completeness of the system of functions $\{\varphi_{\ell}(M)\}$ in the space $L^2(s)$. Let $\gamma(M) \in L^2(s)$. We can analyze the function

$$\iint_{S} \gamma (M) \frac{1}{r(M, N)} ds_{\varkappa}, \quad N \in S_{1}.$$

This function, continuous on S_1 , assumes zero values on the everywhere dense set of points $N_l \in S_1$; therefore

$$\iint_{S} \gamma(M) \frac{1}{r(M, N)} ds_{M} \equiv 0, \quad N \in S_{1}. \tag{4.14}$$

But (4.14) is the potential of a single layer and since on the closed Lyapunov surface S_1 and at infinity it is equal to zero, then on the strength of the uniqueness of the solution to the external Dirichlet problem (uniform conditions at infinity) it is everywhere equal to zero in V_e . This is possible only in the event [12] if the density of the potential is equal to zero. Thus, the completeness of the system $\{\omega_\ell(M)\}$ in the space $L^2(s)$ is proven.

But on the strength of Theorem 3.6, the system $\{\omega_i(M)\}$ is closed. For final proof of Theorem 4.4, we must use Theorem 3.1.

From the proved theorem and the definition of completeness it directly follows that the system $\{\varphi_i(M)\}$ is complete in C and $L^q(s)$, where q>2. As far as the closure is concerned, from Theorem 3.10 it follows that our system $\{\varphi_i(M)\}$ is closed in the space $L^q(s)$, where q<2. Therefore, from Theorem 4.4, it does not follow that the system $\{\varphi_i(M)\}$ is closed in C or $L^q(s)$ when

q > 2. Now let us prove the theorem that the analyzed system is closed in C and consequently closed in $L^q(s)$ for all $q < \infty$ $(q \ge 1)$.

Theorem 4.5. The system $\{\varphi_i(M)\}$ is closed in the space C(s) of all continuous functions, i.e., for any function $\gamma(M) \in C(s)$ and for any $\varepsilon > 0$ there is an $N_0(\varepsilon)$ and a system of coefficients a_i (i = 1, 2, ..., n) such that if $n > N_0(\varepsilon)$, then

$$\max_{M \in \mathcal{S}} \left| \gamma(M) - \sum_{i=1}^{n} a_{i} \varphi_{i}(M) \right| < \varepsilon.$$

For proof of this theorem we use the following statement from Reference [13]: any function that is continuous on the surface S may be uniformly approximated by means of harmonic polynomials, if the region V with the boundary s contains a stable solution of the Dirichlet problem with respect to deformation of the region (5).

Let $\mathbb{P}_{m}(M)$ be a harmonic polynomial of order m for the function $\gamma(M) \in C(s)$

$$\max_{M \in S} |\gamma(M) - P_m(M)| < \frac{\varepsilon}{2}.$$

Let us analyze the internal Dirichlet problem in the region $\mathbf{V}_{\underline{\mathbf{1}}}$ with the boundary $\mathbf{s}_{\underline{\mathbf{1}}}$

$$\Delta u = 0$$
 B V_1 ,
 $u \Big|_{S_1} = P_m \Big|_{S_1}$, (4.15)

and write its solution in the form of the potential of a single layer

⁽⁵⁾ In the two-dimensional case when s is a curve an analogous statement directly follows from the theorems corresponding to the Weierstrass theorems in the complex region (see, for example, the Runge Theorem [3], concerning the uniform approximation of the function of the complex variable by a complex polynomial).

$$u(M) = \iint_{S_1} \Omega(M) \ln \frac{1}{r(x, M)} ds_x, \qquad (4.16)$$

where the density $\Omega(M)$ is expressed through the normal derivatives of the solutions to the internal and external Dirichlet problems. Sufficient smoothness of S_1 produces smooth boundary values for Problem (4.15) and therefore, guarantees existence of these derivatives. Let us look at Expression (4.16) for the points $M_i \in S_1$. The integrand will be bounded and continuous (if the density is continuous) and therefore, the integral can be replaced by a Riemann sum with the number of terms m_1 (or by some kind of cubature formula with nodes at the point $x_i = M_i \in S_1$), such that

$$\max_{M \in S} \left| \iint_{s_1} \Omega(M) \ln \frac{1}{r(x, M)} ds_x - \sum_{i=1}^{m_1} a_i \ln \frac{1}{r(x_i, M)} \right| < \frac{\varepsilon}{2}.$$

Let $n \ge max (m, m_1) = N_0(\epsilon)$; then we find

$$\max_{M \in S} \left| \gamma(M) - \sum_{i=1}^{n} a_{i} \omega_{i}(M) \right| \leq \max_{M \in S} \left| \gamma(M) - P_{m}(M) \right| + \\
+ \max_{M \in S} \left| P_{m}(M) - \sum_{i=1}^{n} a_{i} \omega_{i}(M) \right| \leq \frac{\varepsilon}{2} + \max_{M \in S} \left| \iint_{S_{1}} \Omega(M) \ln \frac{1}{r(x, M)} ds_{x} - \\
- \sum_{i=1}^{n} a_{i} \ln \frac{1}{r(x_{i}, M)} \right| \leq \varepsilon$$

$$\frac{1}{2} \left| \sum_{i=1}^{n} \alpha_{i} \ln \frac{1}{r(x_{i}, M)} \right| \leq \varepsilon$$

and the closure of the system $\{\omega_t(M)\}$ is proved. To complete proof of Theorem 4.5, we must use Theorem 3.1.

§ 5. Approximate Method for Solving the Dirichlet Problems

Let us analyze the Problem (1.1) - (1.2) and, after substituting $\Gamma = 1/4\pi$ 1/r into it, write the basic formula for the theory of harmonic functions (2.12) for the points $x \in V$ and $x \in V_e$, respectively

$$u(x) = \frac{1}{4\pi} \iint_{S} \frac{d}{dn} \frac{1}{r(x, M)} \psi(M) ds_{M} - \frac{1}{4\pi} \iint_{S} \frac{1}{r(x, M)} \varphi(M) ds_{M}, \quad x \in V$$
 (5.1)

$$0 = \frac{1}{4\pi} \iint_{S} \frac{d}{dn} \frac{1}{r(x,M)} \psi(M) ds_{\mu} - \frac{1}{4\pi} \iint_{S} \frac{1}{r(x,M)} \varphi(M) ds_{\mu}, \quad x \in V_{e},$$
 (5.2)

where

$$\psi(M) = u \mid_{s}, \quad \varphi(M) = \frac{du}{dn} \mid_{s}.$$

Since in the case of the Dirichlet problem the function $\psi(M)$ is given, then (5.2) can be written in the form

$$\iint_{S} \frac{1}{r(x,M)} \varphi(M) ds_{M} = F(x), \qquad (5.3)$$

where F(x) is a known function

$$F(x) = \iint_{S} \Phi(M) \frac{d}{dn} \frac{1}{r(x, M)} ds_{x}.$$

Below we shall show that from Condition (5.3) we can determine the function $\varphi(M)$ for the Dirichlet problem in the following manner. We can construct coefficients for expanding the unknown function $\varphi(M)$ into a Fourier series for the complete system $\{\varphi_i(M)\}$, obtained by orthonormalization of System (4.1). After substituting the approximate values found for the function $\varphi(M)$ into Formula (5.1) and carrying out the necessary cubatures, we find the approximate value of the solution to the Dirichlet Problem (1.1) - (1.2) at any point of the region V.

The function determined on S, satisfying (5.3) for the arbitrary point x lying outside the closed region V, will be called the solution to Equation (5.3). If we analyze the normal derivative of both sides of (5.3) by passing to the limit when $x \rightarrow M_0 \in S$ and considering Expression (2.24), we find

$$\varphi(M_0) + \frac{1}{2\pi} \iint_S \varphi(M) \frac{d}{dn} \frac{1}{r(M_0, M)} ds_x = \lim_{x \to \infty} \frac{d}{dn_x} \left[\frac{1}{2\pi} F(x) \right].$$
 (5.4)

For existence of the limit in the right-hand side of (5.4) it is sufficient to require the continuity of $\psi'(M)$ (as follows from the Lyapunov example [4], satisfaction of the Hölder condition for the function $\psi(M)$ is insufficient for existence of normal derivatives of the potential of the double layer). Equation (5.4) is an integral equation of the external Neumann problem and as we know [14], is uniquely resolvable. Let us show that the solution to Equation (5.4) also satisfies the functional Equation (5.3). For this let us substitute the solution to Equation (5.4) into (5.3) and denote by v(x) the function obtained

$$v(x) = \frac{1}{4\pi} \iint_{S} \frac{d}{dn} \left[\frac{1}{r(x,M)} \right] \psi(M) ds_{M} - \frac{1}{4\pi} \iint_{S} \frac{1}{r(x,M)} \varphi(M) ds_{M}.$$
 (5.5)

We must show that $v(x) \equiv 0$ when $x \in V_c$. In the right-hand side of Equation (5.5) we have the sum of potentials of the single and double layer, and therefore, v(x) is a harmonic function. From (5.4) it follows that at the boundary s of the region V the function v(x) takes zero values. If, furthermore, it is shown that

$$\lim_{|x| \to 0} v(x) = 0, \tag{5.6}$$

then from the uniqueness of the solution to the external Neumann problem we find $v(x)\equiv 0$. For the three-dimensional case Equation (5.6) follows from the very form of the right-hand side of (5.5). As far as the two-dimensional case is concerned, the Equations (5.4) and (5.5) take, respectively, the following form:

$$\varphi(M_{0}) + \frac{1}{2\pi} \int_{S} \varphi(M) \frac{d}{dn} \ln \frac{1}{r(M_{0}, M)} ds_{M} =$$

$$= \lim_{x \to M_{0}} \frac{d}{dn} \left\{ \frac{1}{\pi} \int_{S} \psi(M) \frac{d}{dn} \ln \frac{1}{r(x, M)} ds_{M} \right\},$$

$$v(x) = \frac{1}{2\pi} \int_{S} \frac{d}{dn} \left[\ln \frac{1}{r(x, M)} \right] \psi(M) ds_{M} - \frac{1}{2\pi} \int_{S} \ln \frac{1}{r(x, M)} \varphi(M) ds_{M},$$

and according to the known properties of the harmonic potentials

$$\int \varphi(M) \, ds_{_{\mathcal{M}}} = 0. \tag{5.7}$$

Hence, as we know [4], we must prove the property for v(x) also in the two-dimensional case, since Condition (5.7) is sufficient for equating the second integral (potential of the simple layer) to zero in the expression for v(x). We must show that the functional Equation (5.3) has a unique solution. For this let us look at the homogeneous functional equation

$$\iint_{S} \varphi(M) \frac{1}{r(x,M)} ds = 0, \quad x \in V_{e}, \tag{5.8}$$

and show that it has only a trivial solution. Differentiating with respect to the normal (5.8) passing to the limit when $x \rightarrow M_0 \in s$ and taking into acount the expressions in (2.24), we find

$$\varphi(M_0) + \frac{1}{2\pi} \iint_{S} \varphi(M) \frac{1}{r(M_0, M)} ds_{M} = 0.$$

This equation for the external Nenmann problem with homogeneous boundary values, as we know [14], also has only a zero solution.

Let us now proceed to writing the algorithm of the approximate method for solving the Dirichlet boundary value problem (1.1) - (1.2).

By Φ_i let us denote the Fourier coefficients for expanding the function $\varphi(M)$ in a series of functions $\varphi_i(M)$

$$\Phi_i = \iint_{S} (\varphi) M(\varphi_i) (M) ds,$$

where $\varphi_i(M)$ is determined from (4.5)

$$\varphi_l(M) = \sum_{k=1}^i A_{l,h} \omega_k(M).$$

Let us write (5.3) for the points $M_k \in S_1$ in the form

$$\iint_{S} \varphi(M) \omega_{h}(M) ds = F_{h}, \tag{5.9}$$

where

$$F_h = \iint\limits_{s} \psi(M) \frac{d}{dn} \omega_h(M) ds,$$

and the values of $\omega_{\mathbf{k}}$ are determined from (4.1).

Multiplying the first i in the equations by the coefficients $A_{k,i}(k=1,2,\ldots,i)$ and combining we find

$$\iint_{S} \varphi(M) \sum_{k=1}^{i} A_{k,i} \omega_{k}(M) ds = \iint_{S} \varphi(M) \varphi_{l}(M) ds = \Phi_{i} = \sum_{k=1}^{i} A_{k,i} F_{k}.$$

Since in the case of the Dirichlet problem the values of F_k are unknown, and those of $A_{k,i}$ are found in the process of orthonormalizing the system $\{\omega_i(M)\}$, then the Fourier coefficients of the unknown function $\phi(M)$ are computed. Let us introduce the symbols,

$$\varphi^{(N)}(M) = \sum_{i=1}^{N} \Phi_{i} \varphi_{i}(M),$$

$$u^{(N)}(x) = \frac{1}{4\pi} \iint_{S} \frac{1}{r(x, M)} \varphi^{(N)}(M) ds_{M} + \frac{1}{4\pi} \iint_{S} \frac{d}{dn} \left[\frac{1}{r(x, M)} \right] \psi(M) ds_{M}, \quad x \in V.$$

From Theorem 3.5 there directly follows the following asymptotic equation:

$$\lim_{N\to\infty} \left| \left| \varphi(M) - \sum_{i=1}^{N} \Phi_i \varphi_i(M) \right| \right|_{L_2} = 0.$$
 (5.10)

Futhermore, it can be easily proved that for any interior point x of the region V and for any $\epsilon > 0$ such a value of N₀ can be found that if $N_0 < N$, then $\frac{32}{2} |u(x) - u^{(N)}(x)| < \epsilon$. In fact it is clear that

$$|u(x)-u^{(N)}(x)| = \frac{1}{4\pi} \left| \iint_{S} \frac{1}{r(x,M)} \left[\varphi(M)-\varphi^{(N)}(M) \right] ds \right| <$$

$$< \frac{1}{4\pi} \iint_{S} \left| \frac{1}{r(x,M)} \left[\varphi(M)-\varphi^{(N)}(M) \right] \right| ds.$$
(5.11)

On the strength of Expression (5.10) we can select N such that the following inequality will be satisfied

$$\left\{ \iint_{\varepsilon} \left[\varphi(M) - \varphi^{(N)}(M) \right]^2 ds \right\}^{1/2} < \frac{4 \pi \varepsilon \sigma}{V|s|}, \qquad (5.12)$$

where σ is the minimal distance from point x to the boundary s, |s| is the area of the surface S. Substituting (5.12) into (5.11) and using the Buniakowski-Schwarz inequality, we obtain

$$|u(x)-u^{(N)}(x)| < \frac{1}{4\pi} \left\{ \iint_{c} \left[\frac{1}{r(x,M)} \right]^{2} ds \right\}^{1/2} \iint_{c} \left[\varphi(M)-\varphi^{(N)}(M) \right]^{2} ds \right\}^{\frac{1}{2}} < \varepsilon.$$

This method for approximate solution to the boundary value problems will be termed the method of V.D. Kupradze or the method of functional equations.

The completeness of the system of functions $\{\varphi_i(M)\}$ makes it possible to use the following algorithm for approximate solution of the Dirichlet Problem (1.1) - (1.2). For a given function $\psi(M)$ [the boundary condition of the unknown harmonic function u(x)], let us construct a Fourier series on the basis of $\{\varphi_i(M)\}$:

$$\psi(M) = \sum_{k=1}^{N} f_k \varphi_k(M), \quad f_k = \iint_{S} \psi(M) \varphi_k(M) ds.$$

Then on the strength of the completeness of the system $\{\varphi_i(M)\}$ in the sense of the metric of the space L_2 , we have

$$\lim_{N\to\infty}\iint_{S}\left[\psi(M)-\sum_{k=1}^{N}f_{k}\varphi_{k}(M)\right]^{2}ds=0.$$

The series

$$u(x) = \sum_{k=1}^{\infty} f_k \varphi_k(x)$$

for any $x \in V$ converges and represents a solution to the Problem (1.1) - (1.2). In fact let G(x,M) be a Green function of the Dirichlet problem for the region V. Then from the existence theorem it follows that the solution may be represented in the form

$$u(x) = \iint_{S} \psi(M) \frac{\partial G}{\partial n} ds.$$

Let us introduce the notation

$$u^{(N)}(x) = \sum_{k=1}^{N} f_k \varphi_k(M), \quad x \in V,$$

and look at the difference $|u(x)-u^{(N)}(x)|$. Using the Buniakowski-Schwarz inequality and considering the finiteness of the integral

$$\iint_{S} \left[\frac{\partial G}{\partial n} \right]^2 ds$$

when $x \in V$, we find just as above

$$u(x) = \lim_{N \to \infty} u^{(N)}(x).$$

Let us mention that unlike this method, the method of V.D. Kupradze permits finding a solution to the Dirichlet problem with the aid of the boundary values of the normal derivative of the unknown function which are obtained as a solution to the functional Equation (5.3). In this connection we must bear in mind that in practice problems are often encountered in which it is of interest to find namely the boundary values of the normal derivative. This also explains the compilation of special tables [15] for computing the boundary values of the normal derivative. For such problems the method of V.D. Kupradze has the advantage over the above-described method.

Let us make several comments [22-24] concerning use of the discussed approximate method for solving the boundary value problems.

/33

Following [16] the system of linearly independent functions will be termed reliable if

$$\lim_{n \to \infty} G_n = G > 0 \qquad (G_n = G(\varphi_1, \varphi_2, \dots, \varphi_n))$$

When G = 0 the system will be termed unreliable. Let us prove the theorem.

Theorem 5.1. The system of functions $\{\omega_l(M)\}$ is unreliable, i.e., for any $\epsilon > 0$ we find such a value for N that for any n > N the following inequality will be satisfied,

$$G_n < \varepsilon$$
.

We shall assume that the points x_i (i = 1,2,...,n) are renumbered in such a way that $r(x_i, x_{i+1}) < h$, where $h \to 0$ when $n \to \infty$. It is clear that on the strength of the everywhere dense distribution of points x_i this is always possible. From (3.8) we find for an even n = 2k

$$G_n < \prod_{i=1}^k G_2 \left(\omega_{2i-1}, \ \omega_{2i} \right)$$

and with odd n = 2k + 1.

$$G_n < \iint_c \omega_n^2 ds \prod_{i=1}^k G_2(\omega_{2i-1}, \omega_{2i}).$$
 (34)

For $G_2\left(\omega_{2i-1},\ \omega_{2i}\right)$ we obtain

$$G_2(\omega_{2i-1}, \omega_{2i}) = \iint_S \omega_{2i-1}^2 ds \iint_S \omega_{2i}^2 ds - \left(\iint_S \omega_{2i-1} \omega_{2i} ds\right)^2.$$

Taking into account that

$$\omega_{2i-1} = \frac{1}{r(x_{2i-1}, M)} = \frac{1}{r(x_{2i}, M) + \xi(M)},$$
(5.13)

where

$$|\xi(M)| = |r(x_{2i-1}, M) - r(x_{2i}, M)| < r(x_{2i-1}, x_{2i}) < h,$$

for $G_2(\omega_{2i-1}, \omega_{2i})$ we find with an accuracy up to terms of higher order of smallness with respect to h

$$G_2(\omega_{2i-1}, \ \omega_{2i}) \approx O(h)$$
 (5.14)

and for G_n we will have

$$G_n \approx O(h^k)$$
.

Since $h \to 0$ when $n \to \infty$, , then from the latter approximate equation there follows the reliability of the system $\{\omega_i(M)\}$.

The above statement can be directly carried over to any case of the potential system [17]. Thus, we can show that if S and S_1 are not tangent to one another, then any potential system is not reliable.

To check the rate at which the Gram determinant approaches zero, we carried out the following numerical experiments for the two-dimensional case. S is a circle with radius 1 on which we are required to orthonormalize the system of functions $\{\ln r(x_i,M)\}$ (i = 1,2,...,28), where $x \in S_1^{(1)}$ is a concentric circle with radius 2. The points $\mathbf{x_i}$ are distributed on $\mathbf{s_1}^{(1)}$ uniformly in $\frac{\pi}{14}$ intervals. We computed the elements of the Gram determinant of this system. Integration was carried out with an error that did not exceed 10^{-6} . The rank of the determinant with an accuracy up to 10^{-9} was found to be equal to 9, i.e., after sorting out all possible determinants of tenth and higher orders we were unable to detect any among them that were nonmachine-zero (the computations were carried out on a high-speed electronic computer BESM-2). Below we cite the maximal values of $\overline{G_i}$ of the determinant of i^{th} order for $i=1,2,\ldots,9$:

$$\begin{array}{lll} \overline{G}_1 = 3.8 & \overline{G}_2 = 9.7 & \overline{G}_3 = 9.5 & \overline{G}_4 = 5.9 & \overline{G}_5 = 0.4 \\ \overline{G}_6 = 2.7 \cdot 10^{-2} & \overline{G}_7 = 9.2 \cdot 10^{-4} & \overline{G}_8 = 2.8 \cdot 10^{-5} & \overline{G}_9 = 3.7 \cdot 10^{-8} \end{array}$$

Then the points x_i were taken uniformly on the concentric circle $S_1^{(2)}$ with radius 1.1 and interval $\frac{\pi}{12}$. The number of points n was equal to 24. Below we give the respective values for the Gram determinant G_i (i = 1,2, $\frac{\sqrt{35}}{12}$...,24) for this case

From comparison of the respective values of the Gram determinant it is obvious that in the second case the values of the determinant are much larger which, as will be shown below, makes it possible to orthonormalize the respective system more exactly.

Finally the points x were taken uniformly distributed on a concentric circle $s_1^{(3)}$ with a radius of 1.05 and the same interval $\frac{\pi}{12}$. The number of points is equal to 24. Let us derive the respective values of the Gram determinant G_i (i = 1,2,...,24):

The results of these numerical experiments show that with the approach of the auxiliary boundary S_1 to the fundamental boundary S, the corresponding Gram determinant is increased. Let us note that this proof of reliability of the systems of potential functions is substantially based on the constancy of the auxiliary boundary S_1 . Otherwise, from Equation (5.13) we can never derive (5.14), since for some points $M \in S$ of the functions, $r(x_{si}, M)$ and $\xi(M)$ may have one and the same order of smallness.

A second comment touches on the choice of algorithm for orthonormalization of the system $\{\omega_i(M)\}$. As was shown in §4, the orthonormalization may be accomplished both according to Formula (4.6) and according to Formula (4.10). It is clear that if the computations according to both formulas are carried out exactly (with a finite number of digits), then the results are also found to be identical. The results will be sufficiently similar also in the case when the system to be orthonormalized is reliable. But, as was shown above, the system $\{\varphi_i(M)\}$, just as any potential system, is not reliable. Therefore, for practical application of the approximation method for solving the boundary problems it is extremely important to choose, of the two procedures for orthonormalization, that which will give the more consistent procedure for the computation (will guarantee a larger number of reliable digits). Although the computations according to Formula (4.10) are easier to program on the computer, since for computation of the determinants there already exist prepared standard subprograms, nevertheless, as will be shown below the orthonormalization should be carried out according to Formula (4.6), because the respective algorithm is significantly more consistent relative to rounding off errors.

We shall analyze the normalized functions $\omega_i(M)$ as vectors (with origin at 0) in the space L₂ and denote by α_k the angle between the vector $\omega_k(M)$ and the hyperplane passing through the vectors $\omega_1, \ \omega_2, \ \dots, \ \omega_{k-1}$. It is known [16], that the determinant (4.11) is equal to the square of the volume of the parallelpiped constructed on the vectors $\omega_1, \ \omega_2, \ \dots, \ \omega_n$.

$$G_n = \prod_{i=1}^n \sin^2 \alpha_i.$$

Thus, for the denominator of Formula (4.10), we find

$$d_n = V \overline{G_{n-1} \cdot G_n} = \sin \alpha_n \prod_{i=1}^{n-1} \sin^2 \alpha_{i}.$$

As far as the following sum is concerned

$$\sum_{k=1}^{n-1} (\omega_n, \varphi_k) \varphi_k, \tag{5.15}$$

/36

it represents [16] the projection of the element ω_n on the subspace of the vectors ϕ_1 , ϕ_2 , ..., ϕ_{n-1} or on the strength of the equivalence of the subspaces of the vectors ϕ_1 , ϕ_2 , ..., ϕ_n and ω_1 , ω_2 , ..., ω_n , (5.15) represents the projection on the subspace of the vectors ω_1 , ω_2 , ..., ω_n . Hence, it is obvious that the denominator in Formula (4.6) is equal to

$$\sqrt{\iint\limits_{s} \overline{\varphi_{n}^{2} \, ds}} = \sin \alpha_{n}.$$

For othonormalization of n elements we find it necessary to divide by

$$\overline{d}_n = \prod_{i=1}^n \sin \alpha_i.$$

For the ratio $d_n : \overline{d}_n$ we find

$$d_n: \overline{d}_n = \prod_{i=1}^{n-1} \sin \alpha_i = \overline{d}_{n-1}.$$
 (5.16)

/37

From the latter expression it is clear that Formula (4.6) gives a significantly more consistent computational procedure than does Formula (4.10).

We attempted to orthonormalize the system $\{\ln r(x_i,M)\}$, $x \in S_1^{(t)}$ (i = 1, 2, ..., 28) with the aid of Formula (4.6); however, an emergency halt took place in the machine. It was found that this occurred when dividing by $\int \overline{\varphi}_{21}^2 ds$. This fact (taking into account that all the Gram determinants of tenth order are equal to zero) agrees well with Formula (5.16) from which it follows that Formula (4.6) can be used for the fixed number of digits with which the computations are carried out, to orthonormalize approximately twice the number of functions as with Formula (4.10). It is clear that if the orthonormalization of a sufficiently reliable system can be carried out both according to Formula (4.6) and to Formula (4.10), then this latter gives a significantly rougher result. To confirm this we carried out orthonormalization of the system $\{\ln r(x_l, M)\}$, $x \in S_1^{(2)}$ (i = 1, 2, ..., 24). Table 1 gives the coefficients of orthonormalization A_{22} , i for the function Φ_{22} obtained from Formula (4.10), and the same coefficients A_{22} , i obtained from (4.6).

In the third and fourth columns are given $\alpha_{22,\ i}^{(1)} = \int \varphi_{22}^{(1)} \varphi_i^{(1)} ds$ and $\alpha_{22,\ i}^{(2)} = \int \varphi_{22}^{(2)} \varphi_i^{(1)} ds$ and $\alpha_{22,\ i}^{(2)} = \int \varphi_{22}^{(2)} \varphi_i^{(2)} ds$, where $\varphi_i^{(1)}$ and $\varphi_i^{(2)}$ are orthonormalized functions obtained respectively with the aid of Formulas (4.10) and (4.6).

TABLE 1

i				
•	$A_{22,\ i}^{(1)}$	$A_{22,\ i}^{(2)}$	$\alpha_{22,\ i}^{(1)}$	$\alpha_{22,\ i}^{(2)}$
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22	1,5629 -1,7303 0,7977 -0,1783 0,1160 0,0325 0,0264 6,1276 -0,2289 0,7624 -0,9413 0,6365 0,1307 -0,3814 0,3762 -0,0596 0,0032 0,3059 -0,6559 1,0015 -0,4316 -0,1754	1.5747 -1.7267 0.7967 -0.1772 0.1195 0.0258 0.0541 0.0451 0.0477 0.0468 0.0471 0.0469 0.0470 0.0469 0.0472 0.0465 0.0492 0.0412 0.0685 -0.0156 0.2664 -0.3722	1.37 0.15 -0.02 -0.13 -0.20 -0.22 -0.25 -0.25 -0.36 0.13 -0.37 -0.17 0.06 -0.19 -0.07 -0.05 -0.10 0.05 -0.31 0.17 0.00 0.00 0.00	0.9993 0.0080 -0.0030 0.0009 -0.0007 -0.0005 -0.0005 -0.0005 -0.0003 -0.0003 -0.0003 -0.0003 -0.0003 -0.0003 -0.0003 -0.0003 -0.0003 -0.0003 -0.0003

We see the Formula (4.6) gives a significantly more exact orthonormalization than does Formula (4.10).

In Reference [16], the phenomenon of "stability" was first investigated for systems of functions, and the class of systems was indicated that are termed reliable for which the Ritz method remains stable. Leter [19] S. G. Mikhlin indicated a significantly wider class (strongly minimal systems), for which the Ritz method retains its stability. The system of functions $\{\omega_i\}$ is strongly minimal in H_A [20] if the least eigenvalue of the n^{th} order Ritz matrix is bounded below by a positive constant which is independent of n. Since the potential systems which we investigated may be

used as a coordinate system in the Ritz method, then it is interesting to know /38 if they are strongly minimal. Let S and S₁ be concentric circles and the points \mathbf{x}_i (i = 1, 2, ..., 2N), where N is even, be distributed uniformly on S₁. The following assumption is valid. The systems $\{\ln r(x_i, M)\}$ and $\left\{\frac{\partial}{\partial n} \ln r(x_i, M)\right\}$ are not strongly minimal in H_E if E is an identity operator. Since when H_E (H_E coincides with L₂), the Ritz matrix coincides with the Gram determinant, then it is confirmed that for any $\epsilon > 0$ we find a value of N such that the eigenvalue (with the smallest modulus) of the Gram determinant of 2Nth order is less than ϵ . In view of the identify of the proofs, we can give a proof for the system $\{\ln r(x_i, M)\}$. We must prove that the least eigenvalue of matrix (4.11) is as near to zero as desired.

It is easy to prove that for the given case [S and S_1 are concentric circles, x_i (i = 1, 2, ..., 2N) is distributed unifromly on S_1)] the following equations are valid:

$$\int \omega_i \, \omega_{<\,i+k>} \, ds = \int \omega_i \, \omega_{i-k} \, ds,$$

$$\int \omega_j \, \omega_r \, ds = \int \omega_\xi \, \omega_\eta \, ds \qquad \text{for } |j-r| = |\xi-\eta|,$$

$$k=0, 1, ..., 23; i, j, r, \xi, \eta=1, 2, ..., 24; k < i; < i+k> = i+k \mod (n-1)$$

and therefore the Matrix (4.11) has the following form:

$$\begin{bmatrix} a_1, & a_2, & \dots, & a_n \\ a_n, & a_1, & \dots, & a_{n-1} \\ & \ddots & \ddots & \ddots & \ddots \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ a_2, & a_3, & \dots, & a_1 \end{bmatrix}$$

where $a_s = a_{n+2} - x$ (s = 2, 3, ..., N),

$$a_s = \int \ln r(x_j, M) \ln r(x_{j+s-1}, M) \, ds_M. \tag{5.17}$$

The eigenvalues of this matrix are equal [18] to

$$\lambda_k = \sum_{i=1}^n a_i \, \varepsilon_k^{i-1} \ (k=0, 1, \dots, n-1), \tag{5.18}$$

where $\varepsilon_k = \cos \frac{2k\pi}{n} + i \sin \frac{2k\pi}{n}$. When k = N we find

$$\lambda_N = \sum_{i=1}^n (-1)^{i-1} a_i. \tag{5.19}$$

Taking (5.17) into account, we find

$$a_{i+1} - a_i = \int \ln r(x_j, M) \left[\ln r(x_{j+i}, M) - \ln r(x_{j+i-1}, M) \right] ds =$$

$$= \frac{2\pi R}{n} \int \ln r(x_j, M) \left[\frac{\partial}{\partial s_1} \ln r(x_{j+i}, M) + O\left(\frac{1}{n}\right) \right] ds, \qquad (5.20)$$

where R is the radius of the circle S_1 , $\frac{\partial}{\partial S_1}$ is the derivative along the $\frac{\sqrt{39}}{\sqrt{39}}$ tangent to the circle S_1 . The left-hand side of (5.20) does not depend on j; therefore, we will assume that j = 1

 $a_{i+1} - a_i = \frac{2\pi R}{n} \int \ln r(x_1, M) \frac{\partial}{\partial S_1} \ln r(x_{i+1}, M) + O\left(\frac{1}{n^2}\right)$ or

 $a_{2} - a_{1} = \frac{2\pi R}{n} \int \ln r(x_{1}, M) \frac{\partial}{\partial S_{1}} \ln r(x_{2}, M) ds + O\left(\frac{1}{n^{2}}\right)$

 $a_4 - a_3 = \frac{2\pi R}{n} \int \ln r(x_1, M) \frac{\partial}{\partial S_1} \ln r(x_4, M) ds + O\left(\frac{1}{n^2}\right)$

$$a_{2N-2} - a_{2N-3} = \frac{2\pi R}{n} \int \ln r(x_1, M) \frac{\partial}{\partial S_1} \ln r(x_{2N-2}, M) ds + O\left(\frac{1}{n^2}\right)$$

$$a_{2N} - a_{2N-1} = \frac{2\pi R}{n} \int \ln r(x_1, M) \frac{\partial}{\partial S_1} \ln r(x_{2N}, M) ds + O\left(\frac{1}{n^2}\right).$$

Substituting these latter equations into (5.19), taking the evenness of N into account and the trivial equations

$$\int \ln r(x_1, M) \frac{\partial}{\partial S_1} \ln r(x_{2s}, M) ds = -\int \ln r(x_1, M) \frac{\partial}{\partial s_1} \ln r(x_{n+2-2s}, M) ds$$

$$\left(s = 1, 2, \dots, \frac{N}{2}\right);$$

we find the asymptotic equations

$$\lambda_N = O\left(\frac{1}{n}\right). \tag{5.21}$$

We can show that for even N/2 the absolute value of the characteristic number $\frac{\lambda_{N}}{2}$ will be as small as desired. In fact

$$\lambda_{\frac{N}{2}} = \sum_{k=1}^{n} (i)^k a_k = \sum_{k=1}^{\frac{N}{2}} [(i a_{4k-3} - a_{4k-1}) - (a_{4k} - a_{4k-2})].$$

The real part of the complex number $\frac{\lambda_N}{2}$ is equal to zero because of the accuracy of N/2 and of the trivial equations

$$a_{4k-2} = a_{4(\frac{N}{2}+1-k)}; \ a_{4k} = a_{4(\frac{N}{2}+1-k)-2} \ \left(k=1, 2, \ldots, \frac{N}{2}\right),$$

and the imaginary part

$$I_m\left(\lambda_{\frac{N}{2}}\right) = \sum_{k=1}^{N} (-1)^{k+1} a_{2k-1}.$$

Proof of the asymptotic equations (6)

$$I_m\left(\lambda_{\frac{N}{2}}\right) = O\left(\frac{1}{n}\right) \tag{40}$$

is completely analogous to the proof of (5.21).

The potential systems will be called discontinuous potential systems, if S_1 is consistent with S, i.e., if the points \mathbf{x}_i are distributed on the fundamental boundary S. The following assumptions are valid. The system of functions $\{\ln r(x_i, M)\}$, where the points \mathbf{x}_i are distributed everywhere densely on S, are linearly independent and complete in the space $L^2(s)$.

The system of functions $\{\omega_i(M)\}$, where ω_0 is a nonzero constant,

⁽b) From the constructions of the potential systems it is clear that they are not minimal and consequently not strongly minimal. The proved assumption is interesting in that it gives to the asymptotics the least eigenvalue of the Gram matrix.

 $\omega_i(M) = \frac{\partial}{\partial n_{,i}} \ln r(x_i, M)$ $(i=1, 2, ...), x_i$ distributed everywhere densely on S, are linearly independent and complete in L²(s).

The linear independence of these systems is obvious and is proved analogously to the linear independence of the potential systems. For proof of the completeness it is sufficient to prove that the operators

$$\int_{S} \varphi(M) \ln r(x, M) ds_{M}, \int_{S} \varphi(M) \frac{\partial}{\partial n} \ln r(x, M) ds_{M}$$
 (5.22)

transform $(\varphi \in L^2(s))$ to space $L^2(s)$ in C.

Further arguments are completely analogous to the discussions in proving completeness of the potential systems (see the proof of Theorem 4.4).

Let us analyze the integral operation

$$y(x) = \int_{S} \varphi(M) k(x, M) ds_{\mathcal{H}}, \qquad (5.23)$$

and assume that all singularities of the kernel k(x, M) are concentrated on the diagonal, i.e., when x = M. We know [12] that if the kernel of Operation (5.23) satisfies the conditions

$$\left\{ \int_{S} [|\operatorname{grad}_{x} k(x, M)| [r(x, M)]^{1-\mu}]^{p} ds_{M} \right\}^{\frac{1}{p}} \leq E,$$
(5.24)

$$\left\{ \iint_{\mathbb{R}} \left[\frac{|k(x, M)|}{[r(x, M)]^{\mu}} \right]^{p} ds_{\mu} \right\}^{\frac{1}{p}} \leqslant F, \tag{5.25}$$

where by grad we denote the gradient computed according to the variable x, then the integral Operation (5.23) maps the space $L^{p'}$ (and any L^q when $q \ge p'$) /41 into the Lipschitz space Lip μ with the index μ , where p' is the adjoint index (1/p + 1/p' = 1).

It is easy to see that for the kernels of the integral operations (5.22), Conditions (5.24) - (5.25) are satisfied in the case of piecewise-smooth contours when p=p'=2 and $\mu<\frac{1}{2}$.

The system of functions $\left\{\frac{\partial}{\partial n} \ln r(x_i, M)\right\}$ is used [1-3] for solving the Neumann problem

$$\Delta u = 0$$
 B G,
 $\frac{\partial u}{\partial n} \Big|_{s} = \psi(y).$ (5.26)

The approximate solution to Problem (5.26) can be obtained from the expansion of the function

$$\varphi(y) = \int_{y_0}^{y} \psi(y) \, ds_y$$

for the system $\{\ln r(x_i, y)\}$

$$\varphi(y) \approx \sum_{k=1}^{N} a_k \ln r(x_k, y).$$

In fact, the approximate solution to Problem (5.26) has the form

$$u \approx \sum_{k=1}^{N} a_k \operatorname{Arg}(z - z_k) = \sum_{k=1}^{N} a_k \operatorname{arctg} \frac{y^{(2)} - x_k^{(2)}}{y^{(1)} - x_k^{(1)}},$$

where $\mathbf{x}_k^{(1)}$, $\mathbf{s}_k^{(2)}$ and $\mathbf{y}^{(1)}$, $\mathbf{y}^{(2)}$ are the coordinates of the points \mathbf{x}_k and \mathbf{y} , respectively,

$$z = y^{(1)} + i y^{(2)}, \quad z_h = x_k^{(1)} + i x_k^{(2)}.$$

Let us analyze the system of three-dimensional discontinuous functions

$$\left\{\frac{1}{r(x,M)}\right\},\tag{5.27}$$

where x_i are distributed on the surface S. The following assumption is valid. The system of Functions (5.27) is complete in L^p for $p' = \frac{2-\alpha}{1-\alpha}$ for any

 $\alpha>0$, and consequently, on the strength of Theorem 3.8, is closed in L^p $(p=2-\alpha)$. For proof let us mention that Conditions (5.24), (5.25) are satisfied for $k(x,M)=\frac{1}{r(x,M)}$ when $p=2-\alpha$, $\mu<\frac{\alpha}{2-\alpha}$ and any $\alpha>0$. Therefore, the integral operation

$$\int \frac{1}{r(x, M)} \varphi(M) ds_{M}$$
 (5.28)

transforms the space $L^{p'}$ $p'=\frac{2-\alpha}{1-\alpha}$ for any $\alpha>0$ to a Lipschitz space Lip μ , $\mu<\frac{\alpha}{2-\alpha}$.

Let the function $\varphi(M) \in L^{p'}$ be orthogonal to all functions of System (5.27). Let us prove that $\varphi(M) = 0$. We analyze the continuous Function (5.28). On the set of points \mathbf{x}_1 — which is everywhere dense on \mathbf{s} , this function takes zero values, and therefore, it is equal to absolute zero on \mathbf{s} and consequently (on the strength of the harmonicity) in all three-dimensional space. But, from Reference [12, it follows then that the density $\varphi(M) = 0$. Taking into account Theorem 3.8, we find that System (5.27) is closed in $\mathbf{L}_{\mathbf{p}}$ when $\mathbf{L}_{\mathbf{p}} = 2 - \alpha$.

§6. Solution to Boundary Value Problems with the Aid of Nonorthogonal Series

References [25, 26] give one method for determining the expansion coefficients for a system of nonorthogonal functions. The idea of this method involves the following (it is described in detail in the next section). Let us seek the expansion $\sum e_k g_k(s)$ of the functions F(s) according to the normalized system $\{g_k(s)\}$ (k=1, 2, ...). Let us introduce the symbols

$$F_n(s) = -\sum_{i=0}^n e_i g_i(s), \ F_0(s) = g_0(s) = F(s), \ e_0 = -1.$$
 (6.1)

To compute e_k in Reference [25, 26] it is proposed to use the formulas

$$e_h = \int_{S} F_{h-1} g_h ds. \tag{6.2}$$

This method of computing the expansion coefficients directly may be used in the method of generalized Fourier series, since in this latter case the function to be expanded is known. The numerical experiments showed, however, a significantly slower convergence of the method of generalized series when Formula (6.2) is used in comparison with the method of generalized orthogonal Fourier series.

In the present section we shall show [33] such a modification of the method of functional equations on the basis of Formulas (6.1), (6.2), the application of which will not encounter the difficulties mentioned in References [22, 24].

For concreteness let us analyze the method of functional equations for the two-dimensional internal Dirichlet boundary value problem.

$$\Delta u = 0 \text{ in } G,$$

$$u \Big|_{S} = f(s),$$
(6.3)

where s is the boundary of the region G; f(s) is a given function. The essence of the method of V. D. Kupradze involves the following. In the sense of the metric $L_2(s)$ the best expansion is constructed for the normal derivative $\frac{\partial u}{\partial n} \Big|_{s} \varphi(s)$ of the unknown function according to the functions of the complete $\frac{/43}{s}$ and linearly independent system $\{\ln r(x_h, s)\} = \{\omega_h(s)\}$, where $r(\mathbf{x}_k, s)$ is the distance between points \mathbf{x}_k and \mathbf{s} ; $\{x_h\}$ is a set of points distributed everywhere densely on the auxiliary boundary \mathbf{s} , which completely includes the region G. If we have such an expansion, the solution to Problem (6.3) can be found from the fundamental integral equation of the theory of harmonic functions

$$u(x) = \int_{S} \varphi(s) \ln r(x, s) ds + \int_{S} f(s) \frac{\partial}{\partial n} \ln r(x, s) ds, \quad x \in G.$$
 (6.4)

We know [10] that for minimality of the expression $|| \varphi(s) - \sum_{k=1}^n a_k \omega_k(s) ||_{L_2}$ with respect to the coefficients a_k it is necessary and sufficient that a_k be solutions to the system

$$\sum_{k=1}^{n} a_k \int_{s} \omega_k(s) \omega_i(s) ds = \int_{s} \varphi(s) \omega_i(s) ds \quad (i=1, 2, ..., n),$$

$$(6.5)$$

but on the strength of the Green identity

$$\int_{S} \varphi(s) \, \omega_{i}(s) \, ds = \int_{S} f(s) \, \frac{\partial}{\partial n} \, \omega_{i}(s) \, ds \tag{6.6}$$

and System (6.5) takes the form

$$\sum_{k=1}^{n} a_{k} \int_{s} \omega_{k}(s) \, \omega_{i}(s) \, ds = \int_{s} f(s) \, \frac{\partial}{\partial n} \, \omega_{i}(s) \, ds. \tag{6.7}$$

If we first obtain the orthonormalized system $\{\varphi_k(s)\} = \{\sum_{i=1}^R A_h, i \omega_t(s)\}$, where $A_{k,i}$ are the coefficients of orthonormalization, then in the sense of L_2 the best expansion of the function $\varphi(s)$ will be, as we know, expansion in the Fourier series

$$\sum_{k=1}^{n} b_{k} \varphi_{k}(s) = \sum_{k=1}^{n} b_{k} \sum_{i=1}^{k} A_{k, i} \omega_{i}(s) = \sum_{k=1}^{n} c_{k} \omega_{k}(s),$$

where b_k are the Fourier coefficients of the function $\phi(s)$, and

$$c_{h} = \sum_{i=k}^{n} A_{i,h} b_{i}. \tag{6.8}$$

On the strength of the strict normalization [10] of the space L_2 and consequently the uniqueness of the generalized polynomial of the best approximation, the solutions a_k of the System (6.7) and c_k from (6.8) must be identical to $a_k = c_k$ (k = 1,2,...,n).

Thus, the method of functional equations may be analyzed as a combination of the variational method (for the normal derivative of the unknown function) $\frac{1}{44}$ by using the Green Formula (6.4).

It is clear that if we find the expansion $\sum_{k=1}^{\infty} d_k \, \omega_k(s)$ not of the normal derivative of the unknown function, but of its boundary value f(s), then the

approximate solution at any point M of the region G may be found directly from the expression (method of generalized Fourier series)

$$u(M) = \sum_{k=1}^{n} d_k \ln r(x_k, M),$$

and the necessity of carrying out the quadratures associated with the use of Formula (6.4) is eliminated.

However, numerous numerical experiments $^{(7)}$ have shown that for one and the same number of functions which participate in the expansion, the method of V. D. Kupradze gives significantly more accurate results than the method of generalized Fourier series. Therefore, the supplemental computation associated with using the Green formula is completely justified. For illustration, below we cite the errors in solving the Dirichlet problem for the function $u = \arctan y-2/x-2$ in the case of an ellipse with semiaxes a = 1, b = 0.75. Table 2 gives these errors for $x_k \in s_k^{(2)}$ and n = 24 at the mesh points with an interval of h = 0.1. The upper left number in each point corresponds to the error in V. D. Kuproadze's method. Following this is the error in the method of generalized Fourier series, and below is the error in the method of finite differences obtained with the standard program [31, 32] (the simplest approximation of the Laplace operator and the Kollats deflection) with an interval of h = 0.1.

However, with an increase in the number of orthonormalizable functions or when the auxiliary boundary S_1 moves away from the fundamental boundary s, the corresponding Gram determinant for the unreliable system $\{\omega_h(s)\}$ approaches zero, which makes it practically impossible to carry out orthonormalization. As noted in §5 with concentric circles S and S_1 having radii r=1 and $r_1=2$, use of the matrix method of orthonormalization will not allow orthonormalizing

⁽⁷⁾ The numerical experiments were carried out with the aid of standard programs [27,28] compiled in the Department of Numerical Methods of the Computer Center, Academy of Sciences, Georgian SSR.

10 of the 28 functions $\ln r(x_i, s)$ ($i = 1, 2, \ldots, 28$), where x_i are equidistant points of s_1 . Schmidt's method of orthonormalization made it possible to orthonormalize only 20 functions. It was found to be still more difficult to orthonormalize these same functions with a circle having a radius of $r_1 = 5$. In this case Schmidt's method makes it possible (all computations were made on the BESM-2 computer) to orthonormalize 9 functions, and the matrix method - 5.

At first glance it may seem that Formula (6.2) is impossible to use in the method of V. D. Kupradze, since in this case the coefficients e_k will depend on the unknown function $\phi(s)$ [the normal derivative, the solution to Problem (6.3)]. However, the symmetry of the operator of differentiation with respect to the normal, i.e., the Green identity (6.6), makes it possible to apply Formula (6.2) for the normal derivative of the solution to Problem (6.3) /46 to the method of V. D. Kupradze. In fact, if we take into account (6.2), (6.6) and the definitions (6.1) for the coefficients a_k of the expansion of the normal derivative $\phi(s)$ of the solution to the Problem (6.3), we obtain

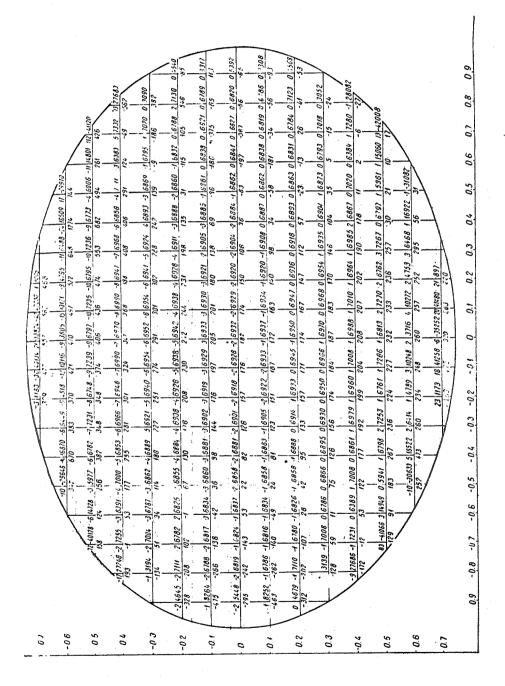
$$a_{1} = \int_{s} f(s) \frac{\partial}{\partial n} \omega_{1}(s) ds,$$

$$a_{2} = \int_{s} f(s) \frac{\partial}{\partial n} \omega_{2}(s) ds - a_{1}(\omega_{1}, \omega_{2}),$$

$$\vdots$$

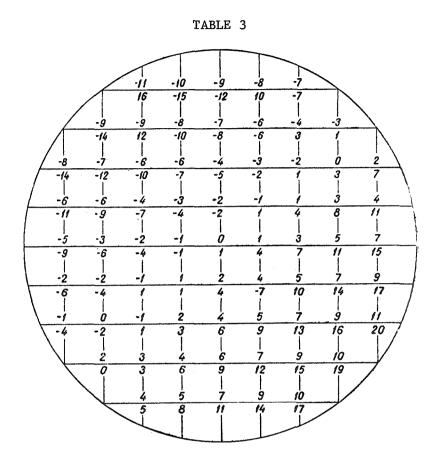
$$a_{k} = \int_{s} f(s) \frac{\partial}{\partial n} \omega_{k}(s) ds - \sum_{i=1}^{k-1} a_{i}(\omega_{i}, \omega_{k}).$$

Using these values of the expansion coefficients in the Green Formula (6.4) we obtain the modification mentioned above for the method of V. D. Kupradze. Table 3 gives, at the mesh points with an interval of h=0.2, the errors in the method of the generalized series multiplied by 100 (the first number at each point) using Formula (6.2) and the modified method of



TABLE

/46



functional equations (the second number) for solving the Dirichlet problem in $\frac{/47}{1}$ the case u = arc tan y-2/x-3 and the circle with radius r = 1. In both cases we used the functions $\ln r(x_k,s)$ (k = 1,2,...,32), where x_k are distributed on the confocal circle with radius r_1 = 5. Let us note that of these functions we were able to orthonormalize only 5 using the matrix method.

From Table 3, it is clear that the modified method of functional equations gives more exact results.

Thus, if the auxiliary contour s_1 for any reason must be taken sufficiently far from the fundamental contour s (for example, this may

happen if the necessity arises for harmonically continuing the solution to Problem (6.1) sufficiently far from s), then in this case it is feasible to use the modified method of functional equations.

Analogously we can modify the method of functional equations also for other boundary value problems.

Let us indicate one possible reason for the high degree of accuracy in the method of functional equations in comparison with the method of generalized Fourier series.

The error $\epsilon(x)$ of the approximate solution to Problem (6.3) at point x in the method of generalized Fourier series is equal to

$$\varepsilon(x) = \int_{S} \left(f(s) - \sum_{k=1}^{n} a_k \, \omega_k(s) \right) \frac{\partial G(x, s)}{\partial n} \, ds,$$

where G(x,s) is the Green function, and for its computation by using the Buniakowski-Schwarz inequality, we obtain

$$|\varepsilon(x)| < \left\{ \int_{s} \left[f(s) - \sum_{k=1}^{n} d_k \, \omega_k(s) \right]^2 ds \right\}^{\frac{1}{2}} \left\{ \int_{s} \left[\frac{\partial G(x,s)}{\partial n} \right]^2 ds \right\}^{\frac{1}{2}}. \tag{6.9}$$

For computation of the error $\epsilon_1\left(x\right)$ in the method of functional equations

$$|\varepsilon_1(x)| < \left\{ \int_{S} \left[\varphi(s) - \sum_{k=1}^{n} a_k \omega_k(s) \right]^2 ds \right\}^{\frac{1}{2}} \left\{ \int_{S} \left[\ln r(x, s) \right]^2 ds \right\}^{\frac{1}{2}}$$
 (6.10)

We know that the Green function G(x,s) has a logarithmic singularity, and therefore, in the equation

$$\left| \left| f(s) - \sum_{k=1}^{n} d_k \, \omega_k(s) \, \right| \right|_{L_2} = \left| \left| \varphi(s) - \sum_{k=1}^{n} a_k \, \omega_k(s) \, \right| \right|_{L_2}$$

computation of (6.9) allows a larger value than computation of (6.10).

In conclusion let us say a few words about computation of the error in the method of functional equations. We know [34] that fundamental problems in the theory of approximate methods are encountered in the following sequence:

- 1. Construction of an algorithm.
- 2. Establishment of a convergence.
- 3. Computation of the rapidity of convergence.

As shown above, the first two problems for V. D. Kupradze's method are solved.

For the error $\varepsilon^{(N)}(x) = u(x) - u^{(N)}(x)$ of the approximate solution to the Dirichlet problem, we find the following expression:

$$\varepsilon_{u}^{(N)}(x) = \frac{1}{4\pi} \iint \frac{1}{r(x, y)} [\varphi(y) - \varphi^{(N)}(y)] ds, \qquad (6.11)$$

where $\varphi(N)$ is the finite generalized Fourier sum for the function $\varphi(y)$ according to a certain complete orthonormalized system of functions. Computation of the difference

$$| | \varphi(y) - \varphi^{(N)}(y) | |$$

is a problem of general harmonic analysis and for its solution we must generalize the theorem of D. Jackson [10] (see, for example, the generalized theorem of Stone-Weierstrass [35]). We know [34] that a real <u>a priori</u> computation can be obtained only in a quite limited number of problems, and therefore the <u>a posteriori</u> computations are of no less significance, all the more since such a computation can be obtained by machine methods and it may be [34] used for automatically changing future computational programs.

/48

If we assume that $\phi(s)$ has a finite derivative with respect to the normal (the corresponding sufficient conditions are given in [36]) from the boundary conditions and the Taylor expansion, we find

$$\varphi(y) = \frac{-\psi(y) + u^{(N)}[x(y)]}{\delta} + \frac{\varepsilon_u^{(N)}[x(y)]}{\delta} + 0 (\delta), \tag{6.12}$$

where $\mathbf{x}(y)$ is the point of region $B_{\mathbf{i}}$ which is at a distance δ from the point y along the normal

$$u^{(N)}(x) = -\frac{1}{4\pi} \iint_{c} \frac{1}{r(x, y)} \varphi^{(N)}(y) ds + F(x),$$

where

$$F(x) = \frac{1}{4\pi} \iint_{S} \frac{\partial}{\partial n_{y}} \left[\frac{1}{r(x, y)} \right] \psi(y) ds.$$

Substituting (6.12) into (6.11), we obtain

$$\varepsilon_{u}^{(N)}(x_{0}) = \frac{1}{4\pi} \iint_{S} \frac{1}{r(x_{0}, y)} \left[\frac{-\psi(y) + u^{(N)}[x(y)]}{\delta} + \frac{\varepsilon_{u}^{(N)}[x(y)]}{\delta} + \frac{\varepsilon_{u$$

It is easy to see that for a wide class of surfaces (for example, if $s \in \Lambda_1$ /49 [36]) and for a sufficiently small $\delta > 0$, we can take σ constant and in such case $x(y) \in B_i$. Then (6.13) assumes the following form:

$$\sigma \, \varepsilon_u^{(N)}(x_0) = \frac{1}{4\pi} \left[\iint_{S} \frac{u^{(N)} \left[x(y) \right] - \psi(y)}{r(x_0 \, y)} \, ds_y + 4\pi \, \sigma \, u^{(N)}(x_0) - \right. \\ \left. - \sigma \, F(x_0) + \iint_{S} \frac{\varepsilon_u^{(N)} \left[x(y) \right]}{r(x_0, \, y)} \, ds + O(\delta^2) \right].$$
 (6.14)

Let us analyze the space $\mathfrak M$ of all integrable functions $\omega(x)$, determined in the region B_0 with the boundary s_0 . The norm of the element of this space is introduced as

$$\left|\left| \omega \left(x \in B_0 \right) \right| \right|_{\mathfrak{M}} = \left| \iint_{s_0} \frac{\omega \left(y \right)}{r \left(x_0, y \right)} \, ds_y \right|,$$

where $\omega(y) = \omega(x) \mid_s, x_0$ is a certain strictly interior point of the region B_i .

From (6.14) it is easy to obtain an approximate computation of the error $\epsilon_u^{(N)}(x)$ from the norm of the space $\mathfrak M$. In fact we have

$$\left|\left|\mathfrak{s}_{u}^{(N)}\left(x\in B\right)\right|\right|\mathfrak{M}=\left|\iint\limits_{S}\frac{\mathfrak{s}_{u}^{(N)}\left[x\left(y\right)\right]}{r\left(x_{0},y\right)}.ds_{y}\right|<\left|\iint\limits_{S}\frac{u^{(N)}\left[x\left(y\right)\right]-\psi\left(y\right)}{r\left(x_{0},y\right)}ds_{y}\right|+$$

$$+O\left(\delta\right)+O\left(\delta^{2}\right),$$

where

$$O(\delta) = \delta [| \varepsilon_u^{(N)}(x_0) | + 4\pi | u^{(N)}(x_0) | + | F(x_0) |]$$

$$O(\delta^2) = \delta^2 \frac{M_1}{2},$$

 M_1 is the maximum of the absolute value of the first derivative of the unknown function ϕ in the closed region \overline{B} . After taking δ sufficiently small, we find the approximate value

$$\left|\left| \varepsilon_{u}^{(N)}(x \in B) \right| \left| \underset{\infty}{\overset{<}{\mathfrak{M}}} \right| \iint_{S} \frac{u^{(N)}[x(y)] - \psi(y)}{r(x_{0}, y)} ds_{y} \right|. \tag{6.15}$$

The norm of the space $\mathfrak M$ does not give the possibility for computing the maximum of the modulus of error $\mathfrak E_u^{(N)}$. If the right-hand side of the computation (6.15) is small, then this still does not indicate smallness of $\mathfrak E_u^{(N)}$, but, if the right-hand side of Expression (6.15) is large then the error $\mathfrak E_u^{(N)}$, at least near the boundary, will be sufficiently large. This is the meaning of Expression (6.15).

It is also easy to obtain an approximate <u>a posteriori</u> computation for the error $\varepsilon_u^{(N)}(y)$ in the sense of the metric of the space C^u . In fact, if we take (6.12) into account, we find

$$\varepsilon_{\psi}^{(N)}(y) = \frac{u^{(N)}[x(y)] - \psi(y)}{\delta} - \varphi^{(N)}(y) + \frac{\varepsilon_{u}^{(N)}[x(y)]}{\delta} + O(\delta)$$
 /50

or

$$| \varepsilon_u^{(N)} [x(y)] | < |u^{(N)} [x(y)] - \psi(y)| + O(\delta) + O(\delta^2),$$

where

$$\varepsilon_{\varphi}^{(N)}(y) = \varphi(y) - \varphi^{(N)}(y)$$

$$O(\delta) = \varepsilon_{\psi}^{(N)}(y) \delta,$$

$$O(\delta^2) = \delta^2 \frac{M_1}{2},$$

The order "0" we obtain from the convergence of the first procedure, i.e., from the condition $\epsilon_{\phi}^{(N)}(y) \to 0$. With a sufficiently small δ we find the following simple approximate computation:

$$|\varepsilon_{u}^{(N)}[x(y)]| < |u^{(N)}[x(y)] - \psi(y)|.$$

The estimate of (6.16) is derived for the points $x \in B_i$, distributed on the surface \overline{S} , which remains at a distance δ from the boundary s.

Let us denote the region bounded by the surfaces S and \overline{S} as B'. From (6.11) it is clear that $u^{(N)}(x)$ is a harmonic function, and therefore on the strength of the maximum principle, we obtain

$$\max_{x \in B_i - B'} |\varepsilon_u^{(N)}(x)| < \max_{x \in \overline{S}} |u^{(N)}[x(y)] - \psi(y)|.$$

$$(6.16)$$

Let us note that for the points distributed at a sufficient distance from the boundary s, computation of (6.16) may give overly large values. Passing to the limit when $\delta \rightarrow 0$, the approximate computations of (6.14) - (6.16) become completely strict. However, for their use we must compute the integrals of the unbounded functions [37].

§7. Series of Nonorthogonal Systems of Functions

Many problems of applied mathematics are reduced to obtaining expansion of the functions $\varphi(x) \in L_2(G)$, where G is the region for determining the variable x, in a series of functions of the complete system $\{\varphi_i(x)\}$. For convergence in $L_2(G)$ of the series

$$\sum_{i=1}^{N} a_i^{(N)} \varphi_i(x) \tag{7.1}$$

to $\varphi(x)$ it is sufficient to obtain, from the given system, a linearly independent system (after excluding the "extra" functions), then the orthonormalized system $\{\omega_l(x)\}$

$$\omega_{i}(x) = \sum_{k=1}^{i} A_{k,i} \varphi_{k}(x)$$

and to take the Fourier series of functions $\varphi(x)$ according to the system $\{\omega_i(x)\}$,

$$\sum_{i=1}^{N} b_i \omega_i(x), \quad b_i = \int_{G} \varphi(x) \omega_i(x) dx.$$
 /51

For the coefficients $a_i^{(N)}$ of Series (7.1) we obtain

$$a_i^{(N)} = \sum_{k=i}^N A_k, \, i \, b_k.$$

In practice, orthonormalization of a large $^{(8)}$ number of linearly independent functions involves significant difficulties. First with orthonormalization of n-functions we are required to compute with a high degree of accuracy the elements of the Gram determinant, i.e., if we take into account the symmetry of this determinant, and n(n+1)/2 integrals of the types

⁽⁸⁾ On the numerical examples [22, 23], carried out with the aid of standard programs [27, 28], we were convinced that in a number of cases the method of the Fourier series with a low degree of accuracy (2 digits) requires a small number of expansion terms. However, a further increase in accuracy significantly increases the required number of expansion terms, and therefore a large number of functions must be orthonormalized.

$$\int_{G} \varphi_{i}(x) \varphi_{j}(x) dx.$$

This requires a large amount of machine time. Thus, for example [22, 23], orthonormalization of the system

$$\{\ln r(M_i, M)\}\ (i=1, 2, 3, ..., 28),$$
 (7.2)

where $r(M_i, m)$ is the distance between the fixed point M_i and the variable M, $M_i \in s_1$, $M \in s_1$, s_1 are concentric circles with radii of 1 and 1.05 requires about two and a half hours of machine time on the BESM-2 (the accuracy of computing the integrals is 10^{-6}).

The second difficulty is more substantial and involves the smallness of the Gram determinant for unreliable linearly independent systems [16, 24] (which are not a Barry basis [38]). Thus, for the unreliable [22, 23] System (7.2) in the case of concentric circles S and S_1 with radii 1 and 2 (the points M_i were distributed uniformly on the circle s_1) we were unable [22] from the respective Gram determinant to obtain a tenth-order determinant that is nonmachine zero (computations were carried out on the BESM-2 computer), although we know [1] that the system (7.2) is linearly independent. Thus, to orthonormalize ten functions from System (7.2) on the BESM-2 (39 digits, of which 32 are for the mantissa) is impossible. We must also bear in mind that the ordinary summation of the Fourier series is not stable, and the problem of approximate determination of the functions at a certain point according to the approximate values of the Fourier coefficients in the metric function 1_2 is an improper problem [39].

From the above it becomes clear that it is important to construct algorithms for obtaining the coefficients $a_i^{(N)}$ of series (7.1) with respect to $\frac{/52}{1}$ nonorthogonal systems of functions. It is clear that taking the Fourier coefficients as $a_i^{(N)}$ in (7.1) generally speaking, will not guarantee convergence. Thus, we know [1, 3] that if the points M_i are distributed everywhere densely on S_1 , then System (7.2) is complete in $L_2(s)$. However, if we expand the constant C over S in a Fourier series according to System (7.1), we obtain

$$C \sim \sum_{i=1}^{N} a_i^{(N)} \ln r(M_i, M) = a \sum_{i=1}^{N} \ln r(M_i, M),$$

where

$$a = C \int_{S} \ln r (M_i, M) ds_M$$

(the integral in the right-hand side of the last expression does not depend on the location of the point M_i on S_1).

In the present section we discuss a new method [25] for expanding the functions in a series of nonorthogonal systems of functions. In the theorem discussed below we give sufficient conditions for convergence of the respective series. As will be shown below, the proposed series give a slightly better approximation in comparison with the Fourier series for the approximately orthonormalized functions.

Let us seek the expansion $\sum_i a_i \varphi_i$ of the function $\varphi(x)$ with respect to the system $\{\varphi_i(x)\}\ (i=1,\ 2,\dots)$, the functions of which will be assumed normalized. The essence of the proposed method is as follows:

The first coefficient \mathbf{a}_1 coincides with the Fourier coefficient for the functions

$$a_1 = \int_G \varphi \varphi_1 \ dx.$$

The difference $\varphi - a_1 \varphi_1$ is termed the first remainder. The second coefficient is the Fourier coefficient for the first remainder

$$a_2 = \int_C (\varphi - a_1 \varphi_1) \varphi_2 dx.$$

The difference $\varphi - \sum_{i=1}^k a_i \varphi_i$ is termed the kth remainder. The $(k+1)^{th}$ coefficient is the Fourier coefficient for the kth remainder

$$a_{h+1} = \int_G \left(\varphi - \sum_{i=1}^k a_i \varphi_i \right) \varphi_{h+1} dx.$$

Let us introduce the following definitions:

$$\varphi^{(n)}(x) = -\sum_{i=0}^{n} a_i \, \varphi_i(x), \ \varphi_0(x) = \varphi(x), \ a_0 = -1,$$
 (7.3)

$$a_{i} = \int_{G} \varphi^{(i-1)}(x) \, \varphi_{i}(x) \, dx \quad (i=1, 2, \ldots), \quad \varphi^{(0)}(x) = \varphi(x). \tag{7.4}$$

The proof that $\left|\left|\begin{array}{cc} \varphi^{(n)}(x) \end{array}\right|\right|_{L_2} \to 0$ when $n \to \infty$ will be equivalent to proof of the convergence of the Series (7.1) in the sense of the metric $L_2(G)$.

It is obvious from Formulas (7.3), (7.4) that with an increase in the $\frac{/53}{}$ number of expansion terms in the Series (7.1) the previous coefficients do not change, and we must compute only the coefficients for the new expansion terms. This significant advantage (from the computational view point) is simultaneously a substantial disadvantage of the proposed method. In fact in many cases it is certainly known that the function $\varphi(x)$ is not represented in the form of an infinite series $\sum_{k=1}^{\infty} a_k \varphi_k(x)$, and therefore, in these cases the proposed method of contstructing the series will not be convergent.

The sequence of positive numbers $\|\varphi^{(n)}(x)\|_{L_2} = \sqrt{(\varphi^{(n)}(x)\varphi^{(n)}(x))}$ (n=1, 2, ...) is monotonically decreasing and consequently has a limit which we can denote by R. In fact [10],

$$\left\| \varphi^{(n)}(x) \right\|_{L_{2}}^{2} = \min_{a_{n}} \left\| \varphi^{(n-1)}(x) - a_{n} \varphi_{n}(x) \right\|_{L_{2}}^{2} = \frac{G(\varphi^{(n-1)} \varphi_{n})}{G(\varphi_{n})} =$$

$$= \left\| \varphi^{(n-1)}(x) \right\|_{L_{2}}^{2} - \left[\int_{c} \varphi^{(n-1)}(x) \varphi_{n}(x) dx \right]^{2},$$

where $G(\varphi_1, \varphi_2, \ldots, \varphi_n)$ is the Gram determinant of the function $|\varphi_1, \varphi_2, \ldots, \varphi_n|$.

We can also show that for any $\epsilon > 0$ we find a finite N $_0$ such that the following inequality will be satisfied

$$\sum_{k=-N_0}^{\infty} (\varphi^{(k)}, \varphi_{k-1})^2 < \varepsilon,$$

where $(\phi,\,\psi)$ is the scalar product of the functions ϕ and $\,\psi.\,\,$ In fact, for any $\epsilon\!>\!0$, we find an N $_0$ such that

$$\varepsilon > \left\| \varphi^{(N_0)}(x) \right\|_{L_2}^2 - R = \sum_{k=N_0}^{\infty} (\varphi^{(k)}, \varphi_{k+1})^2.$$
 (7.5)

Taking into account the notation of (7.3) and (7.4) and the normalization of the system $\{\varphi_i(x)\}$, for any $\epsilon > 0$ we find an N₀ such that when $S > N_0$ we will have

$$\varepsilon > \left| \left\| \varphi^{(s)}(x) \right\|_{L_{0}}^{2} - \left\| \varphi^{(s+1)}(x) \right\|_{L_{2}}^{2} \right| = \left| \int_{G} \left[\sum_{i=0}^{s} a_{i} \varphi_{i}(x) \right]^{2} dx - \int_{G} \left[\sum_{i=0}^{s+1} a_{i} \varphi_{i}(x) \right]^{2} dx \right| = \left| -2a_{s+1} \int_{G} \varphi^{(s)}(x) \varphi_{s+1}(x) dx - a_{s+1}^{2} \int_{G} \varphi^{2}_{s+1}(x) dx \right| = a_{s+1}^{2}.$$

Thus, we find that for any $\epsilon > 0$ and a whole(finite) N we find an N₀ such that

$$\varphi^{(s)}(x) = \varphi^{(r)}(x) + \gamma_r^{(s)}(x) \quad (N_0 < S, \quad r < N_0 + N), \tag{7.6}$$

where

$$\| \gamma_r^{(s)}(x) \|_{L_2} < \varepsilon_1.$$
 (7.7)

Substituting (7.6) into (7.5) we find

$$\varepsilon > \sum_{k=N_0}^{\infty} (\varphi^{(k)} \varphi_{k+1})^2 > \sum_{k=N_0}^{N_0+N} (\varphi^{(k)} \varphi_{k+1})^2 = \sum_{k=N_0}^{N_0+N} (\varphi^{(r)} \varphi_{k+1})^2 + \sum_{k=N_0}^{N_0+N} (\gamma_r^{(k)} \varphi_{k+1})^2 + 2 \sum_{k=N_0}^{N_0+N} (\varphi^{(r)} \varphi_{k+1}) (\gamma_r^{(k)} \varphi_{k+1}).$$

$$(7.8)$$

Using the Buniakowski-Schwarz inequality and taking (7.7) into account, the second and third terms in the right-hand side of Expression (7.8) for any finite N can be made as small as desired and therefore, we ultimately find that for any $\epsilon_2 > 0$ and N we find an N $_0$ such that

$$\sum_{k=N_0}^{N_0+N} (\varphi^{(r)}, \varphi_{k+1})^2 < \varepsilon_2 \ (N_0 < r < N_0 + N).$$
 (7.9)

Thus, the difference between the expanded function $\varphi(x)$ and its series $\sum_{i=1}^{r} a_i \varphi_i(x)$ is "almost" orthogonal to as large a number of functions of the system $\{\varphi_i(x)\}$ as desired.

We shall assume that the function $\varphi(x)$ and the system $\{\varphi_i(x)\}(i=1,2,\ldots)$ satisfy the following conditions: for any $\epsilon>0$ and N_0 we find coefficients $b_k(k=N_0,N_0+1,\ldots,N_0+N)$, such that

$$\int_{s} \left\| \varphi^{(r)}(x) - \sum_{k=N_{0}}^{N_{0}+N} b_{k} \varphi_{k}(x) \right\|_{L_{2}} < \varepsilon, \tag{7.10}$$

$$\sum_{k=N_0}^{N_0+N} b_k^2 < M, \tag{7.11}$$

where M is independent of N₀ and N is constant, and r is any whole number satisfying the inequalities $N_0 < r < N_0 + N$.

According to the familiar Muntz theorem [10], Condition (7.10) for a fixed r is satisfied by the system $\{x^{k_l}\}$ $(i=1,\,2,\ldots)$ when $k_l>-\frac{1}{2}$, $\lim_{i\to\infty}k_l=\infty$, $\sum_{i=1}^{\infty}\frac{1}{k_l}=\infty$, where the prime denotes omission of possible $k_i=0$. The same condition for a fixed r is satisfied by the so-called potential system [1,23]. In other words, both the potential systems and the system $\{x^{k_l}\}$ possess the property that, after eliminating any finite number of functions, they again become complete in L_2 . We must however, mention that in inequality (7.10) r depends /55 on N. In fact, after increasing N, as follows from (7.9) we must increase N_0 . Therefore, we can never state that for these systems inequality (7.10) is satisified. Satisfaction of inequality (7.10) depends both on the system $\{\varphi_l(x)\}$, and on the expanded function $\varphi(x)$.

Condition (7.11) when $N_0 = 1$ is satisfied by the Fourier coefficients according to the complete orthonormalized system (the equation of closure).

The following theorem is valid. The series $\sum_{i=1}^{N} a_i \, \varphi_i(x)$, where the $a_{\underline{i}}$ are computed from (7.4), of functions $\phi(\mathbf{x})$ with respect to the system $\{\phi_{\underline{i}}(\mathbf{x})\}$, which satisfy Conditions (7.10) and (7.11), converges when $N \to \infty$ to this function in the sense of the metric of the space $L_2(G)$.

In fact from (7.9), (7.11) and the Buniakowski-Schwarz inequality we obtain

$$\sum_{k=N_0}^{N_0+N} b_k(\varphi^{(r)}, \ \varphi_{k+1}) < \sqrt{M\varepsilon} < \varepsilon_3, \tag{7.12}$$

where the $\boldsymbol{b}_{\boldsymbol{k}}$ satisfy the condition

$$\left\| \varphi^{(r)}(x) - \sum_{k=N_0}^{N_0+N} b_k \varphi_k(x) \right\| < \varepsilon_4,$$
 (7.13)

 $\boldsymbol{\epsilon}_3$ and $\boldsymbol{\epsilon}_4$ are numbers as small as desired.

From (7.12) and (7.13) we obtain

$$(\varphi^{(r)}, \varphi^{(r)}) = \sqrt{\|\varphi^{(r)}\|_{L_2}} < \epsilon_5,$$

where ϵ_5 is a number as small as desired.

Condition (7.10) of the proven theorem contains the function $\phi^{(r)}(x)$ and consequently it is difficult to prove. Therefore, the following assumption is of interest. If the function $\phi(x)$ and the system $\{\phi_i(x)\}$ (i = 1, 2, ...) satisfy the conditions: for any whole finite N_0 and any $u(x) \in L_2$ we find coefficients $b_k(k = N_0, N_0 + 1, \ldots)$, such that

$$\lim_{n \to \infty} \left\| u(x) - \sum_{k=N_0}^{n} b_k \varphi_k(x) \right\|_{L_2} = 0, \tag{7.10}_1$$

$$\sum_{k=N_0}^{\infty} b_k^2 < M, \tag{7.11_1}$$

where M is a constant independent of N_0 ; for any $\epsilon>0$ we find an n_0 such that

$$\sum_{k=n_0+1}^{\infty} A_k < \varepsilon, \tag{7.14}$$

where

$$A_{k} = \sum_{i=n_{0}+1}^{k} a_{i}(\varphi_{i}, \varphi_{k+1}) (2\varphi^{(n_{0})} + \sum_{j=n_{0}+1}^{k} a_{j} (\varphi_{j}, \varphi_{k+1}),$$

then the series

/56

$$\sum_{j=1}^{n} a_{j} \varphi_{j}(x),$$

where a are computed from (7.4), converges on the average when $n \to \infty$ to the function $\varphi(x)$.

In fact from (7.5) we find that for any $\epsilon > 0$ we can find an n_0 such that

$$\epsilon > \sum_{k=n_0}^{\infty} (\varphi^{(k)}, \varphi_{k+1})^2 = \sum_{k=n_0}^{\infty} (\varphi^{(n_0)}, \varphi_{k+1})^2 + \sum_{k=n_0}^{\infty} (\varphi^{(k)} - \varphi^{(n_0)}, \varphi_{k+1})^2 + \sum_{k=n_0}^{\infty} (\varphi^{(k)}, \varphi^{(k)}, \varphi_{k+1})^2 + \sum_{k=n_0}^{\infty} (\varphi^{(k)}, \varphi^{(k)}, \varphi^{(k)}) + \sum_{k=n_0}^{\infty} (\varphi^{(k)}, \varphi^{(k)}, \varphi^{(k)})^2 + \sum_{k=n_0}^{\infty} (\varphi^{(k)}, \varphi^{(k)}, \varphi^{(k)}) + \sum_{k=n_0}^{\infty} (\varphi^{(k)}, \varphi^{(k)}) + \sum_{k=n_0}^$$

$$+2\sum_{k=n_0}^{\infty} (\varphi^{(n_0)}, \varphi_{k+1}) (\varphi^{(k)} - \varphi^{(n_0)}, \varphi_{k+1}) = \sum_{k=n_0}^{\infty} (\varphi^{(n_0)}, \varphi_{k+1})^2 +$$

$$+\sum_{k=n_0+1}^{\infty} \left(\sum_{i=n_0+1}^{k} a_i \varphi_i, \varphi_{k+1}\right)^2 + 2\sum_{k=n_0+1}^{\infty} \left(\varphi^{(n_0)}, \varphi_{k+1}\right) \left(\sum_{i=n_0+1}^{k} a_i \varphi_i, \varphi_{k+1}\right).$$

From (7.14) and the last inequality we find that for any $\epsilon>0$ we find an n_0 such that

$$\sum_{k=n_0}^{\infty} \left(\varphi^{(n_0)}, \ \varphi_{k+1} \right) < \varepsilon.$$

Using (7.10₁) and (7.11₁) for the function $\varphi^{(n_0)} \in L_2$ when N₀ = n₀ we obtain

$$\lim_{n\to\infty} \left\| \varphi^{(n_0)}(x) - \sum_{k=n_0}^n b_k \varphi_k(x) \right\|_{L_2} = 0,$$

$$\sum_{k=n_0}^{\infty} b_k^2 < M$$

or using the Buniakowski-Schwarz inequality and the theorem on continuity of the scalar product

$$\sum_{k=n_0}^{\infty} b_k (\varphi^{(n_0)}, \varphi_{k+1}) = (\varphi^{(n_0)}, \varphi^{(n_0)}) = \left| \left| \varphi^{(n_0)} \right| \right|_{L_2}^2 < V \overline{M \varepsilon} < \overline{\varepsilon},$$

where $\bar{\epsilon}$ is a quantity that is as small as desired.

Condition (7.10_1) , unlike Condition (7.10), has a simple meaning: the system $\{\varphi_l(x)\}$ (i = N₀,N₀ + 1,...), where N₀ is any finite whole number, must remain complete in L₂. Let us prove that the system $\{\ln r(M_i, M)\}$ of discontinuous potential functions [22, 24] where $M \in S$ and $M_l \in S$ satisfies Conditions (7.10_1) and (7.11_1) for the space L₂(s). Let the function $\gamma(M_1) \in L_2(s)$ be orthogonal to all functions of this system. We must prove that $\gamma(M) = 0$. Let us analyze the integral operator

$$\int_{c} \ln r (M_1, M) \gamma (M_1) ds_{M_1} = \Phi (M)$$

which transforms the space $L_2(s)$ ($\gamma(M_i) \in L_2(s)$) into the space $\operatorname{Lip} \alpha$ ($\alpha < \frac{1}{2}$), $(\Phi(M) \in \operatorname{Lip} \alpha)$. The continuous function $\Phi(M)$ takes zero values on the set of points M_i that is everywhere dense on S (in view of the orthogonality of $\gamma(M_i)$ to all functions of the examined system), and consequently it is equal to absolute zero on s, and on the strength of its harmonicity, everywhere outside s also. But, the potential of the single layer $\int_s^s \ln r(M_1, M) \gamma(M_1) \, ds_{w_1}$ is then identically equal to zero, when its density $\gamma(M_1)$ identically equals zero. Let us now show that for any $\epsilon > 0$, $u(M) \in L_2(s)$ and N_0 we find coefficients $b_k(k = N_0, N_0 + 1, \dots, N_0 + N)$, such that

$$\|u(M) - \sum_{k=N_0}^{N_0+N} b_k \ln r(M_k, M)\|_{L_2(s)} < \varepsilon.$$

/57

We bear in mind the known theorem that if $\forall n \to \gamma$ and $\psi_n \to \psi$, then $(\forall n, \psi_n) \to (\gamma, \psi)$.

On the strength of the proven completeness of the system being analyzed, we find coefficients C_k (k = 1, 2, ..., N_1), such that

$$\left\| u(M) - \sum_{j=1}^{N_1} C_j \ln r(M_j, M) \right\|_{L_2(s)} < \frac{\varepsilon}{2}.$$

Since the points M_k are distributed everywhere densely on s, then from any point M_j (j = 1,2,..., N_1) we find a point M_{r_i} such that $r_j > N_0$ and

$$\left\| \ln r(M_j, M) - \ln r(M_{r_j}M) \right\|_{L_2(s)} < \frac{\varepsilon}{2N_1C},$$

where $C = \max_{j} |C_{j}|$. Taking this latter inequality and the Minkowski inequality into account, we find

$$\left\| u(M) - \sum_{k=N_0}^{N_0 + N} b_k \ln r(M_k, M) \right\|_{L_2(s)} < \left\| u(M) - \sum_{j=1}^{N_1} C_j \ln r(M_j, M) \right\|_{L_2(s)} + \left\| \sum_{j=1}^{N_1} C_j \ln r(M_j, M) - \sum_{k=N_0}^{N_0 + N} b_k \ln r(M_k, M) \right\|_{L_2(s)}$$

After taking for N and $b_k(k = N_0, ..., N_0 + N)$ the following values:

$$N = \max_{j} r_{j} - N_{0}, \quad b_{k} = \begin{cases} C_{j} & \text{when } M_{k} = M_{r_{j}} \\ 0 & \text{when } M_{k} \neq M_{r_{j}} \end{cases}$$

/58

we find

$$\left| \left| u\left(M\right) - \sum_{k=N_0}^{N_0 + N} b_k \ln r\left(M_k, M\right) \right| \right| < \frac{\varepsilon}{2} + \left| \left| \sum_{j=1}^{N_1} C_j \left[\ln r\left(M_j, M\right) - \ln r\left(M_{r_j}, M\right) \right] \right| \right|_{L_2(s)} < \varepsilon.$$

Now let us proceed to proving (7.11₁). For the system $\{\ln r(M_k, M) \text{ we can prove a significantly stronger assumption: for any function } u(M) \in L_2(s), \text{ any } N_0 \text{ and any } \epsilon > 0, \text{ we find such coefficients } b_k (k = N_0, ..., N_0 + N), \text{ that}$

$$\left| \left| u(M) - \sum_{k=N_0}^{N_0 + N} b_k \ln r(M_{kr} M) \right| \right|_{L_2(s)} < \varepsilon$$
 (7.10₂)

and

$$\sum_{k=N_0}^{N_0+N} b_k^2 < \varepsilon. \tag{7.11_2}$$

Let us represent u(M) in the form of a potential of the single layer

$$u(M) = \int_{S} v(\overline{M}) \ln r(M, \overline{M}) ds_{\overline{M}},$$

and substitute the integral in the right-hand side by the Riemann sum and prove that for any $\epsilon \! > \! 0$ we find an N such that

$$\Delta = \int_{\mathcal{S}} \left[\int_{\mathcal{S}} v(\overline{M}) \ln r(M, \overline{M}) ds_{\overline{M}} - \sum_{k=1}^{N} h_{k} v(M_{k}) \ln r(M, M_{k}) \right]^{2} ds_{\underline{M}} < \varepsilon,$$

where h_k is the length of the k^{th} segment dividing the boundary s, in which we take the point M_k . Taking into account that the points M_k are distributed everywhere densely on s, and $\nu_k(s)$ is a continuous function, we obtain

$$\Delta = \int_{S} \left[\int_{S} \mathbf{v} \left(\overline{M} \right) \ln r(M, \overline{M}) \, ds_{\overline{M}} \right]^{2} ds_{\overline{M}} -$$

$$-2 \sum_{k=1}^{N} h_{k} \mathbf{v} \left(M_{k} \right) \int_{S} \ln r(M, M_{k}) \int_{S} \mathbf{v} \left(\overline{M} \right) \ln r(M, \overline{M}) \, ds_{\overline{M}} \, ds_{\underline{M}} +$$

$$+ \sum_{k=1}^{N} \sum_{j=1}^{N} h_{k} \mathbf{v} \left(M_{k} \right) h_{j} \mathbf{v} \left(M_{j} \right) \int_{S} \ln r(M, M_{k}) \ln r(M, M_{j}) \, ds_{\underline{M}} =$$

$$= \int_{S} \left[\int_{S} \mathbf{v} \left(\overline{M} \right) \ln r(M, \overline{M}) \, ds_{\underline{M}} \right]^{2} ds_{\overline{M}} -$$

$$-2 \int_{S} \mathbf{v} \left(\overline{M} \right) \int_{S} \ln r(M, \overline{M}) \int_{S} \mathbf{v} \left(\overline{M} \right) \ln r(M, \overline{M}) \, ds_{\underline{M}} \, ds_{\underline{M}} \, ds_{\underline{M}} \, ds_{\underline{M}} +$$

$$+ \varepsilon_{1} + \int_{S} \mathbf{v} \left(\overline{M} \right) \mathbf{v} \left(\overline{M} \right) \mathbf{v} \left(\overline{M} \right) \int_{S} \ln r(M, \overline{M}) \ln r(M, \overline{M}) \, ds_{\underline{M}} \, ds_{\underline{M}} \, ds_{\underline{M}} +$$

$$+ \varepsilon_{1} + \int_{S} \mathbf{v} \left(\overline{M} \right) \mathbf{v} \left(\overline{M} \right) \int_{S} \ln r(M, \overline{M}) \ln r(M, \overline{M}) \, ds_{\underline{M}} \, ds_{\underline{M}} \, ds_{\underline{M}} +$$

$$+ \varepsilon_{2} = \varepsilon_{1} + \varepsilon_{2},$$

where ϵ_1 and ϵ_2 are numbers as small as desired. Thus, as the coefficients b_k we can take the numbers $h_k \vee (M_k)$ and therefore,

$$\sum_{k=N_0}^{N_0+N} b^2 = \sum_{k=N_0}^{N_0+N} h_k^2 v^2 (M_k) < h^{(N)} \sum_{k=N_0}^{N_0+N} h_k v^2 (M_k) = h^{(N)} \left[\int_{s}^{v^2} (M) ds_{\kappa} + \varepsilon_3 \right]$$

where ε_3 is a number as small as desired and $h^{(N)} = \max_{k \le N} h_k$. Since when $N \to \infty$ $h^{(N)} \to 0$, then from the latter expression there directly follows (7.11_2) . Satisfaction of Conditions (7.10_2) , (7.11_2) makes it possible to prove the following assumption for the system $\{\ln r(M_h, M)\}$. If for any $\varepsilon > 0$ we find such an N that

$$h^{(N)} \sum_{k=n_0+1}^{N} A_k < \varepsilon,$$
 (7.14₁)

then the series

$$\sum_{j=1}^{n} a_{j} \ln r (M_{j}, M),$$

where a_j are computed from (7.4), converges on the average when $n\to\infty$ to the function $\varphi(x)$. In fact, from Condition (7.14₁) we find

$$\overline{C} \, \mathcal{V}_{\overline{\varepsilon}} > \overline{C} \, h^{(N)} \sum_{k=n_0+1}^{N} A_k > \sum_{k=n_0+1}^{N} b_k \, (\varphi^{(n_0)}, \varphi_{k+1}) = \left| \left| \varphi^{(n_0)} \right| \right|_{L_2}^2 + \varepsilon \,,$$

where $\widetilde{\epsilon}$ is a quantity as small as desired and

$$\widetilde{c} = \sqrt{\int_{s}^{v^{2}(s)} ds}.$$

Thus, we find that the norm of the functions $\varphi(n_0)$ can be made as small as desired.

Conditions (7.10), (7.11) are sufficient but not necessary conditions for convergence of the proposed series. Thus, for complete orthonormalized systems, Condition (7.10) is not satisfied. However, for these systems the

given series (in this case they coincide with the Fourier series) converge. Let us also mention that the difficulties in orthonormalization arise namely for systems which satisfy Condition (7.10) (not minimal systems [40]), and therefore, for such systems construction of these series has an advantage over the Fourier series (in the sense of practical application).

A trivial example of the system which satisfies Conditions (7.10), (7.11) $\underline{/60}$ can be constructed in the following manner. Let P_1 , P_2 ... be an arbitrary infinite sequence of increasing whole numbers, $\lim_{i\to\infty} P_i = \infty$. From the orthonormalized complete system $\{\varphi_i(x)\}$ we can formulate the following normalized system $\{\psi_i(x)\}$, where $\psi_i(x) = \varphi_i(x)$, $j = i - \sum_{k=1}^r P_k$, r is the greatest whole number for which $\sum_{k=1}^r P_k < i$.

The system $\{\psi_i(x)\}\$ has the following form:

$$\{\varphi_1, \varphi_2, \dots, \varphi_{p_1}, \varphi_1, \varphi_2, \dots, \varphi_{p_2}, \varphi_1, \varphi_2, \dots, \varphi_{p_3}, \varphi_1, \varphi_2, \dots\}.$$
 (7.15)

It is easy to see that when $\lim_{i\to\infty}P_i=\infty$, it satisfies Conditions (7.10), and (7.11). Let us analyze the system $\{\Phi_i\}$

$$\{\varphi_1, \varphi_2, \dots, \varphi_{p_1}, \varphi_{n_1}, \varphi_{n_1+1}, \dots, \varphi_{p_1}, \varphi_{n_2}, \varphi_{n_2+1}, \dots, \varphi_{p_3}, \dots\},$$
 (7.16)

where n_i , P_i are whole numbers, and the system $\{\phi_i\}$ is orthonormalized. We can show that the coefficient of the series computed from (7.4) for the function Φ_s (s is an arbitrary whole number) of the Series (7.16) coincides with the Fourier coefficient for the function Φ_s , if Φ_s was first encountered in Series (7.16); and is equal to zero is Φ_s prior to this was encountered in Series (7.16). In fact from (7.4) for the first case we have

$$a_s = \int_G (\varphi - \sum_{k=1}^{s-1} a_k \, \Phi_k) \, \Phi_s \, dx = \int_G \varphi \Phi_s \, dx,$$

and for the second case ($\Phi_s = \Phi_r$, where r is a whole number smaller than S)

$$a_s = \int_G (\varphi - \sum_{k=1}^{s-1} a_k \Phi_k) \Phi_s dx = \int_S \varphi \Phi_s dx - a_r \int_S \Phi_r \Phi_s dx = 0.$$

Thus, Procedure (7.4) for computing the coefficients automatically discards for Systems (7.16) and consequently for Systems (6.15) those functions which previously already participated in the expansion. Therefore, the proposed series for Systems (7.15) and (7.16) coincide with the Fourier series for the orthonormalized system $\{\varphi_i\}$. Let System (7.15) have the form $\{\varphi_i, \varphi_2, \ldots, \varphi_{\rho_1}, \varphi_1, \varphi_2, \ldots, \varphi_{\rho_2}, \varphi_1, \ldots, \varphi_{\rho_{l-1}}, \varphi_1, \varphi_2, \ldots\}$ i.e., the sequence P_i is finite $P_1, P_2, \ldots, P_{\tilde{l}}$ and $P_l = \infty$. Then this system will not satisfy Condition (7.10), but nevertheless for it the proposed series will be convergent to the expanded function $\varphi(x)$, because it will be consistent with the Fourier series for the orthonormalized system $\{\varphi_i\}$. Thus, as mentioned above, the conditions of the above theorem are not necessary conditions for convergence of these series.

We arrive at the above algorithm for constructing the series according to the nonorthogonal functions by the following reasoning: on the strength of /61 Theorem 3.11, if in a certain subspace G of the Hilbert space H a point y exists which is least distant from $\varphi \in H$, then the vector $(\varphi - y)$ is orthogonal to each vector of G. Taking the span of the set of normalized functions $\{\varphi_1,\ldots,\varphi_n\}$ as G, the element $y = \sum\limits_{k=1}^n \lambda_k \varphi_k$, and for finding the coefficients λ_k of the best (in the sense of the metric of H) approximation, we find the system

$$(\varphi - y, \varphi_k) = 0$$
 $(k = 1, ', ..., n)$

or in expanded form

$$\lambda_{1} + \lambda_{2} (\varphi_{2}, \varphi_{1}) + \cdots + \lambda_{n} (\varphi_{n}, \varphi_{1}) = (\varphi, \varphi_{1})$$

$$\lambda_{1} (\varphi_{1}, \varphi_{2}) + \lambda_{2} + \cdots + \lambda_{n} (\varphi_{n}, \varphi_{2}) = (\varphi, \varphi_{2})$$

$$\vdots \qquad \vdots \qquad \vdots \qquad \vdots \qquad \vdots$$

$$\vdots \qquad \vdots \qquad \vdots \qquad \vdots \qquad \vdots$$

$$\lambda_{1} (\varphi_{1}, \varphi_{n}) + \lambda_{2} (\varphi_{2}, \varphi_{n}) + \cdots + \lambda_{n} = (\varphi, \varphi_{n}).$$

$$(7.17)$$

This latter system can be solved by iteration methods. Computation of the coefficients of the Fourier series with respect to the system $\{\varphi_i\}$ corresponds

to one single iteration for System (7.17), when as the initial approximation for the vector $(\lambda_1, ..., \lambda_n)$ we take the null vector $\lambda^{(0)}$ (0, ..., 0), i.e.,

$$a_1^{(\Phi)} = \lambda^{(1)} + B \lambda^{(0)} + R,$$

where $a_1^{(\Phi)}$ is a vector whose components are Fourier coefficients, B is a matrix which corresponds to the following description of System (7.17)

$$\lambda = B \lambda + R,$$

$$\lambda^{(1)} = (\lambda_1^{(1)}, \dots, \lambda_n^{(1)}), \ \lambda^{(0)} = (0, \dots, 0), \ R = ((\varphi, \varphi_1), \dots, (\varphi, \varphi_n)).$$
(7.18)

Let us write (7.18) in the following form:

$$\lambda = (B_1 + B_2) \lambda + R$$

where

$$B_{1} = \begin{pmatrix} 0 & 0 & \dots & \dots & 0 & 0 \\ -(\varphi_{1}, \varphi_{2}) & 0 & \dots & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ -(\varphi_{1}, \varphi_{n}) & -(\varphi_{2}, \varphi_{n}) & \dots & -(\varphi_{n-1}, \varphi_{n}) & 0 \end{pmatrix}$$

$$B_{2} = \begin{pmatrix} 0 & -(\varphi_{2}, \varphi_{1}) & -(\varphi_{3}, \varphi_{1}) & \dots & -(\varphi_{n}, \varphi_{1}) \\ 0 & 0 & -(\varphi_{3}, \varphi_{2}) & \dots & -(\varphi_{n}, \varphi_{2}) \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

Computation of the Coefficients of (7.4) with respect to the system $\{\varphi_t\}$ corresponds to one iteration according to Seidel's method for System (7.18) or to one single iteration for the system

$$\lambda = (I - B_1)^{-1} B_2 \lambda + (I - B_1)^{-1} R,$$
(7.19)

where I is the unit matrix when as the initial approximation we take the null $\frac{62}{100}$ vector $\lambda^{(0)} = (0, ..., 0)$, i.e.,

$$a^{(A)} = \overline{\lambda}_1^{(1)} = (I - B_1)^{-1} B_2 \lambda^{(0)} + (I - B_1)^{-1} R,$$

where $a^{(A)}$ is a vector whose components are coefficients of the proposed series. Let us mention that all the eigenvalues of the matrix $(I-B_1)^{-1}$ B_2 are less than unity. In fact, since the quatratic form corresponding to the Gram matrix is positive-definite, then Seidel's method for System (7.18) or, what amounts to the same thing, the method of single iteration for System (7.19) converges $^{(10)}$ for any initial approximation and right-hand side. For such an approach the above theorem is equivalent to the following statement. For an approximate solution to System (7.17) for sufficiently large n, only one iteration is sufficient [it is assumed that the system $\{\phi_i\}$ and the function $\phi(x)$ satisfy Conditions (7.10) and (7.11)] according to Seidel's method.

Since computation of the elements of the Gram matrix (scalar products), and naturally the process of orthonormalization, are accomplished with a finite number of digits, then it is clear that the matrix corresponding to System (7.17) will not be a unit matrix. It will somehow be "perturbed". The coefficients of the best approximation here will be found from the system

$$(1 - \varepsilon_{jj}) \lambda_j + \sum_{\substack{k=1\\k \neq j}}^n \varepsilon_{k,j} \lambda_k = (\varphi, \varphi_j) \quad (j = 1, 2, ..., n),$$
 (7.20)

where ϵ_i , are small perturbations produced by round-off errors and errors in computing the scalar products (in the case of the L_2 space — by errors in integrating). Naturally here we assume that $\max_k \sum_{j=1}^n |\epsilon_k, j| < 1$. It is interesting which series is more feasible to use in such cases — the Fourier series or the proposed series? More precisely, what relationship exists between the numbers $||\lambda - a^{(\Phi)}||$ and $||\lambda - a^{(A)}||$, where the vector λ is an exact solution to System (7.20).

⁽¹⁰⁾ Since the diagonal elements of the Gram matrix of the linearly independent system are positive, then the positive determinancy of the respective quadratic form is not only a sufficient but also a necessary condition for convergence of Seidel's iteration process (E. Reich, see [42]).

Since in this case Seidel's iteration process converges more rapidly [42] than the single iteration process and the norm of the matrix $\max_{k} \sum_{j=1}^{n} |\varepsilon_{k},_{j}|$ is subordinate to the first norm of the vectors, then it is clear that the first norm [42] of the vector $(\lambda - a^{(\Phi)})$ will be no less than the first norm of the vector $(\lambda - a^{(A)})$, i.e.,

$$\max_{i} \left| \lambda_{i} - a_{i}^{(\Phi)} \right| = \left\| \lambda - a^{(\Phi)} \right\|_{I} > \left\| \lambda - a^{(A)} \right\|_{I} = \max_{i} \left| \lambda_{i} - a_{i}^{(A)} \right|.$$

Let us note that both the method of the Fourier series and the method of $\frac{63}{}$ the proposed series require carrying out one approximate integration for computing the coefficient of each new expansion term.

$$a_k^{(\Phi)} = \int_G \varphi \varphi_k \, dx,$$

$$a_k^{(A)} = \int_G \varphi^{(k-1)} \varphi_k \, dx.$$

The factor $\phi^{(k-1)}$ is involved in the computation of $a_k^{(A)}$. Therefore it is natural that its values at individual points would be taken for checking accuracy of the expansion since

$$\varphi^{(k-1)}(x) = \varphi(x) - \sum_{i=1}^{k-1} a_i^{(A)} \varphi_i(x).$$

Numerical Example. In a number of cases for several regions G there are tabulated coefficients of orthonormalization, and the expansion of the function $\varphi(x)$ must be carried out in the region G', in a certain sense near to G. Thus, for example in [43] there are tables of coefficients of orthonormalization for the harmonic polynomials which are orthonormal on an ellipse. In [43] 230 ellipses were analyzed with various ratios of the semiaxis p = b/a. The tables are used for solving the internal Dirichlet problem for the analyzed ellipses. Let us solve the Dirichlet problem for such an ellipse which was not analyzed in [43]. In this case it is natural to use the orthonormalized harmonic polynomials for the ellipse analyzed in [43] with the value $p = \frac{b}{a}$ that is nearest to the given ellipse. Here the question arises as to which series are used?

When G and G' are sufficiently close, this question is analogous to the question analyzed above (for approximate orthonormalization). Here we analyze one numerical example. Let us look at System (7.2) for the ellipses s and s₁, with semiaxes 1 and 0.5, 2 and 1, respectively.

$$\left\{\frac{1}{2}\ln\left[\left(2\cos\alpha_{i}-\cos\alpha\right)^{2}+\left(\sin\alpha_{i}-\frac{1}{2}\sin\alpha\right)^{2}\right]\right\} \ (i=1,2,...,),$$

where

$$\alpha_1 = 90^{\circ}$$
, $\alpha_2 = 270^{\circ}$, $\alpha_3 = 0^{\circ}$, $\alpha_4 = 180^{\circ}$, $\alpha_5 = 225^{\circ}$, $\alpha_6 = 45^{\circ}$, $\alpha_7 = 315^{\circ}$, $\alpha_8 = 135^{\circ}$, $\alpha_9 = 330^{\circ}$, $\alpha_{10} = 150^{\circ}$, $\alpha_{11} = 120^{\circ}$, $\alpha_{12} = 300^{\circ}$.

Table 4 gives the coefficients of orthonormalization A $_{k,i}$ of this system for the interval $0 < \alpha < 2\pi$. Let us seek the solution to the internal Dirichlet problem

$$\Delta u = 0,$$

$$\begin{vmatrix} u \\ s \end{vmatrix} = \arctan \frac{y-2}{x-2} = \psi(\alpha),$$

for the ellipse s_1 , with semiaxes 1 and 0.45. The coefficients of orthonormali- $\frac{/64}{2}$ zation of the System (7.2) on this ellipse will no longer coincide with those above, since it takes the following form:

$$\left\{\frac{1}{2} \ln \left[(2\cos \alpha_t - \cos \alpha)^2 + (\sin \alpha_t - 0.45 \sin \alpha)^2 \right] \right\} = \left\{ \varphi_t \right\}$$

However, the functions

$$\left\{ \psi_{t} \right\} = \left\{ \sum_{k=1}^{i} A_{k, i} \varphi_{t} \right\}$$

will be roughly orthonormalized as Table 5 shows in which the Gram matrix is given $\{(\psi_i, \psi_j)\}$ for the system $\{\psi_i\}$. Table 6 gives the Fourier coefficients $a_i^{(\Phi)}$ of the function $\psi(s)$ for the system $\{\psi_i\}$, , the coefficients (7.4) of the proposed series a_i of the function $\psi(s)$ for the system $\{\psi_i\}$ and the

coefficients λ of the best approximation in the sense of the metric L $_2$ of the function $\Psi(s)$ as functions of the system $\{\psi_\ell\}$. λ_ℓ can be found either from the system

$$\sum_{i=1}^{n} (\psi_i, \ \psi_j) \ \lambda_i = (\psi, \ \psi_j) \quad (j=1, \ 2, \dots),$$
 (7.21)

or an orthornormalized system can be obtained on s for $\mathbf{w}_i = \sum_{k=1}^i C_k$, the Fourier series of the function ψ for the system $\{\mathbf{w}_i\}$ can be taken

$$\sum_{i=1}^{n} b_i \omega_i$$

and then we can use the equations

$$\lambda_i = \sum_{k=i} C_k, i b_k. \tag{7.22}$$

It is clear that both methods must give coefficients of the best approximation and on the strength of the uniqueness of the generalized polynomial of the best approximation for the strictly normalized space L_2 , the two systems obtained by these methods for the coefficients must coincide. Table 6 shows the coefficients λ_i , computed by the second method from (7.22). A few words should be said about computation of the coefficients a_i . We know [4.2] that Seidel's method gives the greatest advantage in rate of convergence in comparison with ordinary iteration in the case when the equations are arranged in order of increasing $\sum_i a_{i:i}$, by taking for the first equation that in which this sum is the smallest. Therefore [see Table 5 which gives the coefficients of System (7.21)] the coefficients a_i were determined in the following sequence:

$$a_9$$
, a_7 , a_4 , a_8 , a_{10} , a_{11} , a_{12} , a_1 , a_2 , a_5 , a_5 , a_8 .

From the table it is clear that both the first and the second and third norms [42] of the vector λ - a are less than the respective norms of the vector

$$\|\lambda - a\|_{\mathbf{I}} = \max_{k} |\lambda_{k} - a_{k}| = 0,45 < 1,31 = \max_{k} |\lambda_{k} - a_{k}^{(\Phi)}| = \|\lambda - a^{(\Phi)}\|_{\mathbf{I}}$$

$$\|\lambda - a\|_{\mathbf{II}} = \sum_{k=1}^{12} |\lambda_{k} - a_{k}| = 2,3 < 5,9 = \sum_{k=1}^{12} |\lambda_{k} - a_{k}^{(\Phi)}| = \|\lambda - a^{(\Phi)}\|_{\mathbf{II}}$$

$$\|\lambda - a\|_{\mathbf{III}} = \sum_{k=1}^{12} (\lambda_{k} - a_{k})^{2} = 0,63 < 5,6 = \sum_{k=1}^{12} (\lambda_{k} - a_{k}^{(\Phi)})^{2} = \|\lambda - a^{(\Phi)}\|_{\mathbf{III}}$$

$$\frac{/65}{}$$

The next four columns of Table 6 give the values of the functions

where M_i is the point with coordinates $x_i = \cos \alpha_i$, $y_i = \sin \alpha_i$ (i = 1, 2, ..., 12) at 12 interior points M^(k) of the ellipse s, with coordinates

$$M^{(1)}(0, -0.9), M^{(2)}(0, -0.8), M^{(3)}(0, -0.7), M^{(4)}(0, -0.6),$$

 $M^{(5)}(0, -0.5), M^{(6)}(0, -0.4), M^{(7)}(0, -0.3), M^{(8)}(0, -0.2),$
 $M^{(9)}(0, -0.1), M^{(10)}(0, 0), M^{(11)}(0, 0.1), M^{(12)}(0, 0.2).$

From Table 6, it is clear that the approximate solution to the Dirichlet problem analyzed above according to the method of the analyzed series $\overline{\psi}_2(M)$ gives more exact values than the approximate solution of this same problem by the method of Fourier series $\overline{\psi}_3(M)$. Let us mention that $\psi(M)$ is an exact

solution to this problem and $\widetilde{\psi}_1(M)$ is its approximate solution obtained with the aid of the best approximation in the sense of the metric L_2 of the boundary function $\psi(s)$.

As noted above, obtaining coefficients (7.4) corresponds to one iteration according to Seidel's method for System (7.2). In this case it is remarkable that we are not required to compute the coeffficients of this system -- the scalar products (φ_i, φ_i) . This fact, in certain instances, may strongly decrease the number of required quadratures in finding the coefficients of the best approximation, i.e., in solving System (7.21). In fact, let us be required to find the first n coefficients λ_i in the best approximation of the function ψ with respect to the system $\{\phi_l\}$. Let us take the new system $\{\psi_i\}$ $(i=1,\ 2,\ldots,\ N;\ N>n)$, where $\psi_k=\varphi_j,\ k=j\ (\mathrm{mod}\, n)$ and find the coefficients of the proposed series according to this system. It is easy to see that this will correspond to Seidel's iteration process for Ssytem (7.21). Here the number of iterations will be equal to N/n, when N = mn, where m is a whole /66 number. A noninteger N/n means that Seidel's last iteration has not been carried to the end. Since computation of the coefficients of System (7.1) requires n^2 + n/2 quatratures, and computation of N coefficients (7.4) requires N quatratures, we may find that use of the method of the proposed series is more convenient than computation of the coefficients of System (7.21) and its further solution [properly, solution to System (7.21) by one of the modifications of the Gauss method still requires on the order of ${\tt n}^3$ arithmetic operations]. The last column of Table 3 gives the values of the coefficients $\overline{a_{k}}$ obtained when N = 36, i.e., three iterations were made for System (7.21) by the method of the examined series. The coefficients a were computed from the formula $\overline{a_k} = a_k + a_{12+k} + a_{24+k}$. The coefficients λ_k and $\overline{a_k}$ concide with the five decimal digits. Further increase in the number of iterations made no sense because the scalar products were computed with ${ t six}$ Computation of the coefficients $\overline{a_k}$ required 36 reliable decimal digits. quatratures, whereas computation of the coefficients in System (7.21) would require 78 quadratures.

Let us denote the spectral norm of the operator $(I - B_1)^{-1}B_2$ by \bar{b} . Then the number of iterations by the Seidel method for System (7.21) required for decreasing the errors of zeroth approximation by 10^k times [or what amounts to the same thing, the number of single iterations for System (7.19)] will be equal to $\frac{k}{\log_{10}\bar{b}}$ and if this number is less than n, then the iteration process with the aid of the method of the proposed series requires a smaller number of quatratures than computation of the coefficients in System (7.21) and its further solution.

TABLE 4

/67

i	j	$A_{i,j}$	i	j	$A_{i,j}$	i	<i>j</i>	$A_{i,j}$
1	<u>'</u>	1,0407	5	4	- 4,6057	7	6	9,5446
2	ı	0,3462	5	5	4,6118	7	7	10,8815
2	2	1,0968	6	1	- 0,9654	8	1	0,8797
3	ı	- 0,5365	6	2	1,1276	8	2	1,2645
3	2	- 0,5365	6	3	- 4,3658	8	3	- 11,0209
3	3	0,6252	6	4	1,9865	8	4	- 20,4241
4	1	- 0,3853	6	5	- 1,1420	8	5	13,6851
4	2	- 0,3853	6	6	4,7511	8	6	9,8651
4	3	- 0,2108	7	1	0,9101	8	7	9,6222
4	4	0,6598	7	2	0,0561	8	8	14,5257
5 .	1	0,9226	7	3	- 17,5184	9	1	3,8971
5	2	- 0,7153	7	4	3,3486	9	2	4,5145
5	3	0,9654	7	5	1,0676	9	3	— 135,2959
9	4	- 1,1330	10	8	- 64,2106	11	11	40,7688
9	5	5,7030	10	9	- 58,6615	12	1	5,9396
9	6	33,4046	10	10	177,6990	12	2	2,8762
9	7	— 57,8352	11	i	0,9583	12	3	- 246,1864
. 9	8	8,3734	11	2	5,2864	12	4	- 95,7584
9	9	167,6996	11	3	— 14,7569	12	5	30,2315
10	1	3,4206	11	4	— 227,479 6	12	6	50,5909
10	2	2,5505	11	5	43,0299	12	7	- 225,8198
10	3	46,1256	11	6	14,2266	12	8	-65,1761
16	4	— 142,9701	11	7	10,4574	12	9	398,9135
10	5	33,0538	11	8	- 216,6044	12	10	139,3438
10	6	- 4,5184	11	9	7,1679	12	11	14,3462
10	7	29,1042	11	10	374,1380	12	12	43,1996
	1	I		i	ı	1	ı	l .

TABLE 5

i	j	$(\psi_i, \ \psi_j)$	i	j	(ψ_i, ψ_i)	i	j	$(\psi_i, \ \psi_j)$
1	1	0,8607	7	6	0,0243	10	8	0,0338
2	1	0,0905	7	7	0,8804	10	9	-0,0126
2	2	0,9209	8	1	0,0702	10	10	0,7923
3	1	0,0260	8	2	0,0878	11	1	0,0036
3	2	0,0360	8	3	- 0,0031	11	2	-0,0031
3	3	0,9422	8	4	0,0450	11	3	-0,0147
4	1	0,0186	8	5	0,0119	11	4	0,0201
4	2	0,0259	8	6	- 0,0074	11	5	— 0 .0313
4	3	0,0463	8	7	- 0,0041	11	6	0,0150
4	4	0,9735	8	8	0,8732	11	7	0,0315
5	1	- 0,0129	9	1	 0 ,0536	11	8	— 0 ,0186
5	2	0,0227	9	2	- 0,0016	11	9	0,0418
5	3	0,0085	9	3	0,0003	11	10	0,6536
5	4	— 0,0166	9	4	0,0073	11	11	0,7044
5	5	0,8166	9	5	— 0,0077	12	1	— 0 ,0306
6	1	0,0295	9	6	- 0,0666	12	2	0,0014
6	2	0,0108	9	7	0,0373	12	3	0,1002
6.	3	- 0,0155	9	8	0,0113	12	4	- 0 ,0146
6	4	0,0178	9	9	0,7831	12	5	— 0 ,0036
6	5	0,0109	10	1	0,0020	12	6	— 0 ,0307
6	6	0,8112	10	2	- 0,0054	12	7	0,0054
7	1	0,0196	10	3	0,0074	12	8	0,0054
7	2	0,0483	10	4	- 0,0047	12	9	0,0564
7	3	- 0,0555	10	5	— 0,0678	12	10	0,0047
7	4.	0.0551	10	6	0,0323	12	11	- 0,0169
7	5	-0,0163	10	7	- 0,0304	12	12	0,6917

TABLE 6

k	$a_k^{(\Phi)}$	$a_k^{(A)}$	λ _h	$\psi(M^{(k)})$	$\overline{\psi_1} (M^{(k)})$	$\overline{\psi}_2 (M^{(k)})$	$\overline{\psi}_3 (M^{(k)})$	\widetilde{a}_k
1.	0,558600	0,423157	0,632909	0,603749	0,518301	0,543001	0,598301	0,632311
. 2	0,532666	0,681348	0,792195	0,620249	0,562604	0,584391	C,613430	0,792186
3	- 0,855595	- 0,134128	0,485213	0,637549	0,597411	0,601432	0,630724	0,485224
4	2,638250	- 3,828113	3,946620	0,655696	0,604510	0,621368	0,648858	3,946624
5	1,971488	2,004124	1,801310	0,674741	0,624014	0,641498	0,667883	1,801316
6	2,131344	1,013516	1,163211	0,694738	0,655201	0,664653	0,687857	1,163217
7	4,621686	4,511926	4,613214	0,715944	0,710185	0,709261	0,708842	4,613221
8	0,494495	0,915716	1,121345	0,737815	0,711613	0,713405	0,730897	1,121351
9	— 3,7 67565	- 3,811601	— 4,267911	0,761013	0,724653	0,734501	0,754085	- 4,267930
10	2,022020	2,561700	2,881903	0,785393	0,734623	0,751008	0,778466	2,881911
11	0,383068	0,981601	1,146823	6,811034	0,754218	0,791423	0,804104	1,146831
12	0,428553	.— 0,410116	- 0,495131	0,837981	0,800146	0,814609	0,831062	- 0,495140

§8. Nonorthogonal Series in Variational Methods

The method proposed in the previous section for solving System (7.17) may be used in variational methods. In essence, expansion of the function $\varphi(x)$ in a series of functions of the system $\{\varphi_i(x)\}$ may be regarded as the Ritz method for solving the functional equation $E\varphi(x)=\varphi(x)$, which is the identity operator with the coordinate functions $\{\varphi_i(x)\}$.

The variational methods of determining the coefficients a_j of the expansion for solving the functional equations for a certain system $\{\phi_j\}$ lead [44] to the following infinite system of equations:

$$\sum_{j=1}^{\infty} (A_1 \varphi_j, A_2 \varphi_k) a_j = (A_3 \varphi_k, A_4 \varphi) \quad (k=1, 1, ...),$$
(8.1)

where A_i (i = 1,2,3,4) are positive or positive definite [44] operators, and φ is a certain known function. If the sequences $\{A_1\varphi_i\}^i$ and $\{A_2\varphi_i\}$ are biorthonormalized or, when $A_1 \equiv A_2$, the sequence $\{A_1\varphi_i\}$ is orthonormalized, then for the coefficients a_i we obtain

$$a_j = (A_3 \varphi, A_4 \varphi_k). \tag{8.2}$$

In certain instances [22], however, the system $\{A, \varphi_i\}$ is not strongly minimal and its preliminary orthonormalization involves great difficulties [23]. Therefore, the question arises of approximation solution of System (8.1). By approximate solution of System (8.1) we shall mean the vector $\bar{\mathbf{a}}^{(N)}$ ($\bar{\mathbf{a}}_1^{(N)}$, ..., $\bar{\mathbf{a}}_N^{(N)}$), which satisfies the system

$$A^{(N)} \bar{a}^{(N)} = B^{(N)} + \varepsilon \tag{8.3}$$

or

$$\sum_{j=1}^{N} (A_1 \varphi_j, A_2 \varphi_h) \, \bar{a}_j^{(N)} = (A_3 \varphi, A_4 \varphi_h) + \varepsilon_h \quad (k = 1, 2, ..., N),$$

/69

where $\varepsilon(\varepsilon_1,\ldots,\varepsilon_N)$ is the discrepancy vector. For smallness of the vector $(a^{(N)}-\bar{a}^{(N)})$, where $a^{(N)}$ is the solution to system (8.3) when $\varepsilon\equiv 0$, $a_i^{(N)}$ are coefficients of the best, in a certain sense, expansion of the solution to the functional equation for the system $\{\varphi_j\}$, it is necessary that the expression $||(A^{(N)})^{-1}\varepsilon||$ be small. However, in the case of unreliable systems (which are not a Barry basis [39]) the norm of the vector $(a^{(N)}-\bar{a}^{(N)})$ may be as large as desired but nevertheless the difference between the expanded function and its approximation $\sum_{i=1}^N a_i^{(N)} \varphi_i$ may be in a certain metric less than the small number $\varepsilon>0$ as much as is desired

$$\left\| \psi - \sum_{i=1}^{N} a_i^{(N)} \varphi_i \right\| < \varepsilon. \tag{8.4}$$

In the latter case the respective matrix is poorly defined and in its vicinity we find a degenerate matrix. As shown in [45] without regularization here we can obtain greatly differing solutions which differ from the normal solution [45].

Therefore, we shall term the vector $\overline{a}^{(N)}$, which satisfies inequality (8.4)/70 the ε -approximate solution to System (8.1).

In the present section we can indicate one new method for obtaining the approximate solution to System (8.1). The essence of this new method involves the fact that in the case of certain systems $\{\varphi_i\}$ (the respective conditions for the systems will be formulated below) for obtaining the approximate solution to (8.1) with a large N it is sufficient to make only one Seidel iteration, taking as the initial approximation the null vector.

In the Hilbert space H, in which the scalar product [u, v] is determined in the following manner:

$$[u, v] = (A_1 u, A_2 v) = (A_1 v, A_2 u),$$

let us seek the best, in the sense of the metric H, approximate functions ψ with the generalized polynomial $\sum\limits_{j=1}^n a_j \varphi_j$. From the orthogonality of the difference $(\psi-\sum\limits_{j=1}^n a_j \varphi_j)$ to any function φ_j we obtain for determination of the coefficients a_j the following system:

$$\left[\psi - \sum_{j=1}^{N} \alpha_{j} \varphi_{j}, \varphi_{k} \right] = 0 \qquad (k=1, 2, ..., N),$$

or

$$\sum_{j=1}^{N} a_{j} (A_{1} \varphi_{j}, A_{2} \varphi_{k}) = (A_{1} \psi, A_{2} \varphi_{k}).$$

If the operator A_1 is the product $A_1 = A_5 A_4 A_6$, where A_5 satisfies the condition

$$(A_5A_4\varphi, A_2\varphi_i) = (A_4\varphi, A_5A_2\varphi_i),$$

and the functional equation

$$A_6 \psi = \varphi$$

is given, then by denoting $A_5A_2 = A_3$, for determining the coefficients a we find the system

$$\sum_{i=1}^{N} a_i (A_1 \varphi_i, A_2 \varphi_k) = (A_3 \varphi_k, A_4 \varphi).$$

We shall determine the approximate values \bar{a}_j of the coefficients a_j using Seidel's iteration process after taking the vector $a^0 = (0, ..., 0)$ as the initial approximation $(A_3\varphi_1, A_4\varphi)$

$$\bar{a} = \frac{(A_3 \varphi_1, A_4 \varphi)}{(A_1 \varphi_1, A_2 \varphi_1)},$$

$$\bar{a}_2 = \frac{(A_3 \varphi_2, A_4 \varphi) - \bar{a}_1 (A_1 \varphi_1, A_2 \varphi_2)}{(A_1 \varphi_2, A_2 \varphi_2)},$$

$$\bar{a}_{h} = \frac{(A_{3}\varphi_{h}, A_{4}\varphi) - \sum_{j=1}^{k-1} \bar{a}_{j} (A_{1}\varphi_{j}, A_{2}\varphi_{h})}{(A_{1}\varphi_{h}, A_{2}\varphi_{h})} \cdot \frac{/71}{}$$

Let us note that if the systems $\{A_1\varphi_j\}$, $\{A_2\varphi_j\}$ are biorthonormalized, then the coefficients \bar{a}_j coincide with the coefficients (8.2) of the function ψ .

Since

$$(A_1\psi, A_2\varphi_h) = (A_3\varphi_h, A_4\varphi),$$

then for \bar{a}_k we obtain

$$\bar{a}_{k} = \frac{\left(A_{1} \left(\psi - \sum_{j=1}^{k-1} \bar{a}_{j} \varphi_{j}\right), A_{2} \varphi_{k}\right)}{\left(A_{1} \varphi_{k}, A_{2} \varphi_{k}\right)}.$$

Thus, \bar{a}_k is a coefficient of the best approximation (in the sense of the examined Hilbert space H), of the difference

$$(\psi - \sum_{j=1}^{k-1} \bar{a}_{j} \varphi_{j}) = \varphi^{(k-1)} \text{ function } C_{h} \varphi_{k} \text{ [10]}$$
of
$$\min_{c_{k}} \left\| \psi - \sum_{j=1}^{k-1} \bar{a}_{j} \varphi_{j} - c_{h} \varphi_{k} \right\| = \left\| \varphi - \sum_{j=1}^{k} \bar{a}_{j} \varphi_{j} \right\| = \frac{G(\varphi^{(k-1)}, \varphi_{k})}{G(\varphi_{k})},$$
(8.5)

where $G(u_1, \ldots, u_n)$ is the Gram determinant of the function u_1, \ldots, u_n . Since

$$\frac{G(\varphi^{(k-1)}, \varphi_h)}{G(\varphi_h)} = (\|\varphi^{(k-1)}\|)^2 = \frac{(A_1 \varphi^{(k-1)}, A_2 \varphi_h)^2}{\|\varphi_h\|^2},$$

then from Expression (8.5) we obtain

$$(\|\varphi^{(k)}\|)^2 = (\|\varphi^{(k-1)}\|)^2 - \frac{(A_1 \varphi^{(k-1)}, A_2 \varphi_k)^2}{\|\varphi_k\|^2}.$$
 (8.6)

Thus, the sequence of positive numbers $\{\|\phi^{(k)}\|\}$ is monotonically decreasing and consequently has a limit. If we assume that the norm of the

functions φ_i are bounded in the set both from both above and from below, from (8.6) we find that for any $\epsilon > 0$ we find an N_O such that

$$\sum_{k=N_0}^{\infty} (A_1 \varphi^{(k-1)}, A_2 \varphi_k)^2 < \varepsilon.$$
 (8.7)

But then when $S > N_0$

$$\varepsilon > |(||\varphi^{(s)}||)^{2} - (||\varphi^{(s+1)}||)^{2}| = |(A_{1}(\psi - \sum_{j=1}^{s} a_{j}\varphi_{j}), A_{2}(\psi - \sum_{j=1}^{s} a_{j}\varphi_{j})) - (A_{1}(\psi - \sum_{j=1}^{s+1} a_{j}\varphi_{j}), A_{2}(\psi - \sum_{j=1}^{s+1} a_{j}\varphi_{j}))| = |(A_{1}(\psi - \sum_{j=1}^{s} a_{j}\varphi_{j}), A_{2}(\psi - \sum_{j=1}^{s} a_{j}\varphi_{j})) - a_{s+1}(A_{1}\varphi_{s+1}, A_{2}(\psi - \sum_{j=1}^{s} a_{j}\varphi_{j})) - a_{s+1}^{2}(A_{1}\varphi_{s+1}, A_{2}\varphi_{s+1}) - (A_{1}(\psi - \sum_{j=1}^{s} a_{j}\varphi_{j}), A_{2}(\psi - \sum_{j=1}^{s} a_{j}\varphi_{j}))| = |-3a_{s+1}^{2}(A_{1}\varphi_{s+1}, A_{2}\varphi_{s+1})|,$$

and on the strength of the boundedness of the norm of the functions ϕ_I from /72 below we have

$$|a_{s+1}| < \varepsilon$$
.

From the latter inequality we find that for any $\epsilon\!>\!0$ and any N we find an N such that

$$\varphi^{(s)} = \varphi^{(r)} + \gamma_r^{(s)} \quad (N < s, \ r < N_0 + N),$$
 (8.8)

where

$$||\gamma_r^{(s)}|| < \varepsilon.$$
 (8.9)

Substituting (8.8) into (8.7) we obtain

But taking (8.9) into account,we find that for any $\epsilon\!>\!0$ and a whole N we find an N $_0$ such that

$$\sum_{k=N_0}^{N_0+N} (A_1 \varphi^{(r)}, A_2 \varphi_{k-1})^2 < \varepsilon \quad (N_0 < r < N_0 + N).$$
 (8.10)

We shall assume that the system $\{\varphi_i\}$ satisfies the condition: for any $\epsilon>0$ of a whole N and $\psi\in H$ we find coefficients \mathbf{b}_k $(\mathbf{k}=\mathbf{N}_0,\ldots,\mathbf{N}_0+\mathbf{N})$ such that at least for one value of r

$$\|\varphi^{(r)} - \sum_{k=N_0}^{N_0+N} b_k \varphi_k \| < \varepsilon \quad (N_0 < r < N_0 + N)$$
(8.11)

and

$$\sum_{k=N_0}^{N_0+N} b_k^2 < M, \tag{8.12}$$

where M is a constant, independent of N_0 and N.

On the strength of (8.10), (8.11), (8.12) and the Schwarz-Buniakowski inequality, we obtain

$$\left| \sum_{k=N_{k}}^{N_{n}+N} b_{k-1} (A_{1} \varphi^{(r)}, A_{2} \varphi_{k-1}) \right| < \varepsilon_{1}.$$

Taking into account the last two inequalitites and the fact that $||\varphi^{(r)}|| < ||\psi||^{r}$ we obtain

$$\begin{split} \|\psi - \sum_{j=1}^{r} \bar{a}_{j} \varphi_{j} \|^{2} &= \|\varphi^{(r)}\|^{2} = (A_{1} \varphi^{(r)}, \ A_{2} \sum_{k=N_{0}}^{N_{0}+N} b_{k} \varphi_{k}) - \\ &- \left(A_{1} \varphi^{(r)}, A_{2} \left(\sum_{k=N_{0}}^{N_{0}+N} b_{k} \varphi_{k} - \varphi^{(r)} \right) \right) < \varepsilon_{1} + \|\varphi^{(r)}\| \|\varphi^{(r)} - \\ &- \sum_{k=N_{0}}^{N_{0}+N} b_{k} \varphi_{k} \| < \varepsilon_{1} + \|\psi \| \varepsilon < \varepsilon_{2}, \end{split}$$

where ϵ_2 is a number as small as desired.

Thus, we have proved the following theorem.

If the norms of the function φ_i in Hilbert space H are bounded both from above and below the system $\{\varphi_i\}$ and the function ψ satisfy Conditions (8.11) and (8.12), then for the ε -approximate solution to System (8.1) it is sufficient to carry out a single Seidel iteration for the system

$$\sum_{i=1}^{N(\epsilon)} (A_1 \varphi_i, A_2 \varphi_k) \alpha_i = (A_3 \varphi_k, A_4 \varphi) \quad (k=1, 2, ..., N(\epsilon)),$$

taking as the initial approximation the null vector $\mathbf{a}^0(0,0,\ldots,0)$.

9. Approximate Solution to One Mixed Boundary Value Problem in the Theory of Harmonic Functions

Let us analyze the boundary value problem

$$\Delta u = 0 \quad \text{B} \quad G,$$

$$u \Big|_{\Gamma_t} = \omega(s) + c_i,$$

$$\int \frac{\partial u}{\partial n} ds = 0 \quad (i = 1, 2, ..., m),$$

$$\Gamma_t$$
(9.1)

where G is a multiply connected two-dimensional (three-dimensional) region (Figure 1), bounded by the contour (surface) $\Gamma = \sum\limits_{i=1}^m \Gamma_i$, and G are hitherto unspecified constants. If for the holomorphic function g(z) = u + iv, the Cauchy-Riemann expresseion is valid

$$\frac{\partial v}{\partial s} = \frac{\partial u}{\partial n} \tag{9.2}$$

also on the boundary of the region G, then Problem (9.1) in the two-dimensional case coincides with the so-called modified Dirichlet problem [46], i.e., to find the function u(x,y) which is harmonic in G and continuous in G+1 under the following conditions: (1) u(x,y) is the real part of the function g(z) which is holomorphic in G; (2) it satisfies the boundary condition

 $u=|\omega|(s)+c_i$, where $\omega(s)$ is a continous function, and c_i are real constants, hitherto not given (11).

<u>/74</u>

This problem is a rather wide-spread one. It is encountered in the approximate solution to boundary value problems in the theory of analytical functions [42], in the conformal mapping of multiply connected regions [48], in computing fields of charged filaments located near conducting cylinders [49], etc.

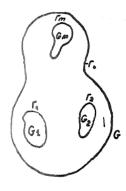


Figure 1

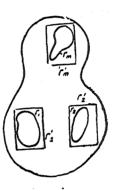


Figure 2

In [46], it was proven that the modified Dirichlet problem with one of the arbitrary constants c specified has a unique solution which can be represented in the form of a double layer (12) potential. The integral equation for the density in this case can be assigned such a form that the

⁽¹¹⁾ In order that the Problem (9.1) coicide with the modified Dirichlet problem [46], instead of Condition (9.2) it is sufficient to require satisfaction of the condition $\int \frac{\partial v}{\partial s} \ ds = \int \frac{\partial u}{\partial n} \ ds \ .$

This solution satisfies Condition (9.2) in the closed region $\overline{G} = G + S$. Hence, as a result of the uniqueness of the adjoint function v(x,y) we have $\int \frac{\partial u}{\partial n} ds = 0$. On the strength of the uniqueness theorem for Problem (9.1), this means that in the two-dimensional case Problem (9.1) is equivalent to the modified Dirichlet problem.

respective homogenous equation will not have a nonzero solution. However, practical solution to these integral equations, in spite of their Fredholm character (in the case of regions bounded by Lyapunov curves) is made more difficult, since the kernel has a variable indeterminancy of the type 0:0 and this limits the accuracy of computing coefficients of the linear system by which the integral equation is replaced in the approximate solution.

In [47] for the approximate solution to Problem (9.1) (when $c_m=0$) it is proposed to use the method of finite differences. The integral conditions at the boundary are replaced by the finite-difference approximation, and instead of the contours Γ_i , we consider the rectangular contours Γ_i' (Figure 2) and the conditions

$$\int_{0}^{\infty} \frac{\partial u}{\partial n} ds = 0.$$
 \tag{75}

Hence, from the harmonicity of u there follow the integral conditions (9.1). Such a replacement of the contours represents definite convenience from the viewpoint of programming the solution to the respective finite-difference system. However, we must mention that the matrix of this system may be singular in this case (in [47] the question was not investigated as to the solvability and uniqueness of the solution to the obtained finite-difference system). Therefore, these integral conditions are more feasible to analyze namely in the form of (9.1), i.e., on Γ_i . For this from all the interior points of the region, the distances from which to the boundary Γ_i are less than $\forall h$, where h is the grid-point spacing and \forall is a certain constant (for example, $\forall \forall \forall \forall 1$), we must drop the normal on Γ_i and the points of intersection of this normal with Γ_i must be analyzed as points of the quadratic formula for the integrals (1) (13). It is easy to prove that

⁽¹³⁾ The other terms in these formulas will be one order of magnitude rougher than in the formulas from Reference [47]. However, it does not follow from this that the error in solving the proposed system will be greater than the error in solving the system used in [47].

the matrix thus obtained of the finite-difference system on the strength of its indivisibility (with a sufficiently small h) will satisfy the conditions of the familiar theorem of Olga Tausski [50] on the nonsingularity of the matrices (it is assumed that at the interior and boundary points, regular finite- difference approximations are used), namely the diagonal term in each row in absolute value will be no less than the sum of the absolute values of all the nondiagonal terms and in some rows (for the points near the contour Γ_m) the diagonal term will be, in absolute value, strictly greater than the sum of the absolute values of all the nondiagonal terms.

For practical solution of this system it is necessary to indicate (if possible) the converging iteration process, because the elliptical finite-difference systems as a rule are solved by iteration methods. Reference [49] gives an algorithm for solving Problem (9.1) when m=2 and $c_2=0$ (doubly connected region), which assumes knowledge of the function $\Lambda\left(z\right)$, which is infinitely sheeted, and conformal mapping of the given doubly connected region onto a strip. This algorithm is quite complex and is feasible to be used only in those cases when $\Omega\left(z\right)$ is written explicitly (for example, when the doubly connected region is a ring [49]).

We can show that the solution to Problem (9.1) can be constructed with comparative simplicity by the methods analyzed above.

Let $u_{\hat{1}}$ (i = 1,...,m) be the solutions to the following boundary value problems::

$$\Delta u_{i} = 0 \quad \text{B} \quad G, \quad u_{i} \Big|_{\Gamma_{j}} = \delta_{i}, \quad (i = 1, ..., m),$$

$$\Delta u_{m+1} = 0 \quad \text{B} \quad G, \quad u_{m+1} \Big|_{\Gamma} = \omega (s), \tag{9.3}$$

where δ_{i} , is the Kronecker symbol. Solution to Problem (1) will be sought in the following form:

$$u = \sum_{i=1}^{m+1} c_i u_i,$$
 /76

where $c_{m+1} = 1$. Then to determine the constants c_i (i = 1, ..., m) from the integral Conditions (1) we obtain a system of equations

$$\sum_{i=1}^{m} c_{i} r_{i}, j = \int_{\Gamma_{j}} \frac{\partial u_{m+1}}{\partial n} ds \quad (j = 1, 2, ..., m),$$
(9.4)

where

$$-\int_{\Gamma_{1}} \frac{\partial u_{1}}{\partial n} ds, \quad -\int_{\Gamma_{1}} \frac{\partial u_{2}}{\partial n} ds, \dots, \quad -\int_{\Gamma_{1}} \frac{\partial u_{m}}{\partial n} ds$$

$$-\int_{\Gamma_{2}} \frac{\partial u_{1}}{\partial n} ds, \quad -\int_{\Gamma_{2}} \frac{\partial u_{2}}{\partial n} ds, \dots, \quad -\int_{\Gamma_{2}} \frac{\partial u_{m}}{\partial n} ds$$

$$-\int_{\Gamma_{2}} \frac{\partial u_{1}}{\partial n} ds, \quad -\int_{\Gamma_{m}} \frac{\partial u_{2}}{\partial n} ds, \dots, \quad -\int_{\Gamma_{m}} \frac{\partial u_{m}}{\partial n} ds$$

$$-\int_{\Gamma_{m}} \frac{\partial u_{1}}{\partial n} ds, \quad -\int_{\Gamma_{m}} \frac{\partial u_{2}}{\partial n} ds, \dots, \quad -\int_{\Gamma_{m}} \frac{\partial u_{m}}{\partial n} ds$$

$$-\int_{\Gamma_{m}} \frac{\partial u_{1}}{\partial n} ds, \quad -\int_{\Gamma_{m}} \frac{\partial u_{2}}{\partial n} ds, \dots, \quad -\int_{\Gamma_{m}} \frac{\partial u_{m}}{\partial n} ds$$

From the principle of the maximum it follows that for the inner normal we will have

$$\frac{\partial u_i}{\partial n} \bigg|_{\Gamma_i} < 0, \quad \frac{\partial u_i}{\partial n} \bigg|_{\Gamma_j} > 0 \quad (i, j = 1, 2, ..., m).$$

We know (see [52], page 20) that with sufficiently smooth contours (surfaces) $\operatorname{grad} u_i \Big|_{\Gamma_j} \neq 0 \ (i, j=1, 2, ..., m)$. But since $u_i \Big|_{\Gamma_j} = 0 \ (i \neq j)$, then $\operatorname{grad} u_i \Big|_{\Gamma_j} = \frac{\partial u_i}{\partial n} \Big|_{\Gamma_j} > 0 \ (i \neq j)$.

From the latter inequalities and relationships

$$\int_{\Gamma} \frac{\partial u_i}{\partial n} ds = 0 \quad (i = 1, 2, ..., m)$$

we find

$$r_{i, j} = \sum_{\substack{i=1\\i\neq j}}^{m} |r_{i, j}| = -\sum_{\substack{i=1\\i\neq j}}^{m} r_{i, j},$$

which indicates the singularity of the matrix $(r_{i,j})$. However, after arbitrarily stipulating one of the constants c_i and eliminating the corresponding equation from System (9.4), it is easy to see that the respective matrix R will satisfy the familiar Adamar condition relative to nonsingularity of the matrices (the diagonal term in any column is greater in absolute value than the sum of the absolute values of all the other terms [50]). Since for the Adamar type matrix R the conditions $r_{l}, l > 0$ (i = 1, 2, ..., m), are also valid, then the determinant of the matrix is positive (see [50], page 26).

$$\max_{i, j} \left| \varepsilon_{i, j} \right| = \max_{i, j} \left| \int_{\Gamma_{j}} \frac{\partial}{\partial n} \left(u_{i} - \overline{u}_{i} \right) ds \right| = \varepsilon < \frac{1}{\sigma} < \frac{1}{(m-1)^{2} \alpha},$$

where $\alpha = \max_{i, j} |\alpha_{i, j}|$. Let us also note that the matrix R depends only on the geometry of the given region and does not depend on the boundary conditions. Therefore, for the specific region we can once and forever compute α .

Thus, to obtain an approximate solution to Problem (9.1) we must specify one of the constants c_i , to approximately solve Problem (9.3) and use the system obtained from (9.4) by discarding one equation. Here the approximate solutions of Problems (9.3) must satisfy the following conditions: (1) for any $\epsilon > 0$ we can construct an approximate solution which satisfies the condition:

$$\max_{i, j} \left| \int_{\Gamma_j} \frac{\partial}{\partial n} (u_i - \bar{u}_i) ds \right| < \varepsilon$$

(obviously for this it is sufficient that the normal derivative $\frac{\partial \overline{u}_i}{\partial n}$ of the approximate solution approximate $\frac{\partial \overline{u}}{\partial n}$ in the sense of the metric L_2); (2) furthermore, it is desirable that the approximate method for solving Problems (9.3) be such that, after obtaining the solution to one of the Problems in (9.3), the solutions to the other problems will be obtained automatically, without considerable computation. These requirements are satisfied by the method of solving the boundary value problems described above. Let us analyze the following linearly independent system of functions [3], complete in L_2 at Γ :

$$\{\ln r(x_i, y)\},\tag{9.5}$$

where x_i are the elements of the denumberable set of points distributed everywhere densely on the auxiliary contour $s = \sum_{i=0}^{m} s_i$ (Figure 3). Below we analyze Problem

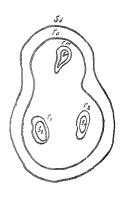
(9.1) for the two-dimensional case although all the arguments obviously are $\frac{78}{100}$ valid also for the case of three dimensions; here System (9.5) must be replaced by the system $\{[\ln r(x_i, y)]^{-1}\}$, where x_i are distributed on a certain surface [6].

Let us consider the system $\{\varphi^{(i)}(y)\}$;

$$\varphi^{(i)}(y) = \sum_{j=1}^{i} A_j, \lim_{t \to \infty} r(x_j, y),$$

where $A_{i,i}$ are the coefficients of orthonormalization of System (9.5)

Using for u_{m+1} the Green formula at the points x_i , we find



$$\int_{\Gamma} \ln r(x_i, y) \varphi_{m+1}(y) ds_y = F_i =$$

$$= \int_{\Gamma} u_{m+1}(s) \frac{\partial}{\partial n_y} \ln r(x_i, y) ds_y,$$
(9.6)

Figure 3

where

$$\varphi_{m+1}(y) = \frac{\partial u_{m+1}}{\partial n} \bigg|_{\Gamma} .$$

After multiplying the first i in Equation (9.6) by $A_{j,i}(j = 1,2,..., i)$ and combining, we find

$$\int_{\Gamma} \varphi_{m+1}(y) \, \varphi^{(l)}(y) \, ds_y = \Phi_{l}^{(m+1)} = \sum_{j=1}^{l} A_j, \, {}_{l}F_j, \qquad (9.7)$$

where $\Phi_i^{(m+1)}$ are the Fourier coefficients of the unknown function $\varphi_{m+1}(y)$. Assuming that $\varphi_{m+1}(y) \in L_2$ and taking into account the completeness of the system $\{\varphi^{(i)}(y)\}$, we will have

$$\lim_{N \to \infty} \left| \varphi_{m+1}(y) - \sum_{i=1}^{N} \Phi_{i}^{(m+1)} \varphi^{(i)}(y) \right|_{L_{2}} = 0,$$

Let us note that the approximate values of the right-hand sides of System (9.4) have been found (even before Problem (9.3) was solved for u_{m+1}).

Let us analyze (m) classes W_i (i = 1,2,...,m) of numbers according to absolute value (m). We shall assume that the points x_i are distributed such that if $k \in W_i$, then $x_k \in s_i$.

Let us use the Green formula for u_i (i = 1,2,..., m) at the points x_k :

$$\int_{\Gamma} \ln r(x_k, y) \varphi_i(y) ds_y = 2\pi \text{ when } k \in W_i,$$

$$\int_{\Gamma} \ln r(x_k, y) \varphi_i(y) ds_y = 0 \text{ when } k \in W_j (j \neq i),$$

where

$$\varphi_i(y) = \frac{\partial u_i}{\partial n} - \bigg|_{\Gamma}$$

For the coefficients of the generalized Fourier series of the function $\varphi_i(y)$ we obtain

$$\Phi_k^{(i)} = 2\pi \sum_{j=1}^r A_{jm+i,k}, \qquad (9.8)$$

where r is the greatest whole number which satisfies the condition rm+i < k .

Expressions (9.7) and (9.8) make it possible to obtain the right-hand sides and coefficients of System (9.4), the solutions c_i of which (for one specified constant), are introduced into the Green formula for solving Problem (9.1):

$$u(x) = \frac{1}{2\pi} \sum_{k=1}^{m} \int_{\Gamma_k} \left[\omega(s) + c_k \right] \frac{\partial}{\partial n} \ln r(x, y) \, ds_y - \frac{1}{2\pi} \int_{\Gamma} \ln r(x, y) \, \varphi(y) \, ds_y, \quad x \in G,$$

$$(9.9)$$

where

$$\varphi(y) = \frac{\partial u}{\partial n} \Big|_{\Gamma} = \sum_{i=1}^{m+1} c_i \sum_{j=1}^{i} \Phi_j^{(i)} \varphi^{(j)}, c_{m+1} = 1,$$

give values of the solution to Problem (9.1) at the arbitrary point $x \in G$.

In the two-dimensional case, after computing u(x,y), it is often required [44], [48] to also compute the imaginary part v(x,y) of the holomorphic function g(z) = u + iv. For this we can use the algorithm from Reference [51], which assumes computation of the values v at the points at the limit by recurrence relationships (difference analog of the Cauchy Riemann relationships) and at the interior points by solving the system of difference equations. However, knowledge of the functions $u \mid_{\Gamma} \frac{\partial u}{\partial n} \mid_{\Gamma}$ makes it possible to compute the functions

$$\begin{vmatrix} v(y) \\ \Gamma \end{vmatrix} = v_0 + \int_0^y \frac{\partial v}{\partial s} ds = v_0 + \int_0^y \frac{\partial u}{\partial n} ds,$$
$$\frac{\partial v}{\partial n} \Big|_{\Gamma} = \frac{\partial u}{\partial s} = \omega'_s(s),$$

and then for computation of v(x) $x \in G$, the Green Formula (9.9) is used.

§10. Approximate Solution to the Reimann-Hilbert Problem

The Riemann-Hilbert problem for a multiply connected region is the following. In the region G_i (Figure 1), bounded by the contour $\Gamma = \Gamma_0 + \Gamma_1 + \dots + \Gamma_m$, we seek the holomorphic function F(s) = u + iv, which satisfies at the contour Γ of the region G_i the condition

$$\alpha$$
 (s) $u + \beta$ (s) $v = \gamma$ (s).

Assuming that $\alpha(s)$, $\beta(s)$, $\gamma(s)$ are continuous Hölder functions with an arc /80 length S on the boundary Γ and $\alpha^2+\beta^2=1$, and F(z) is a continuous holomorphic. Hölder function in the closed region $G(F(z)-H_0$ [47]), the solution to the formulated problem when n+1>m, where n is the index of the analyzed problem [53] (the case n+1< m can [47] be reduced to the problem when n=m, is reduced [47] to solving the following boundary value problems (we

104

know [53], that when $n+1 \ge m$ the analyzed problem is always solvable, and the respective homogeneous problem has (2n + 1-m) linearly independent solutions.

I. We seek ${\rm H}_0$ - the holomorphic function g(z) assuming the following conditions at the boundary:

Re
$$g(z) \mid_{\Gamma_0} = \omega(s)$$
,
Re $g(z) \mid_{\Gamma_0} = \omega(s) + C_k \quad (k=1, 2, ..., m)$,

where $\omega(s)$ is a known function, and C_k are arbitrary constants. Here we shall assume for generality that $p(p \leq m)$ of them (numeration of the contours is done in such a manner that they are the first p) are equal to zero. This problem, as noted above, is also encountered [48] in conformal mapping of multiply connected regions and in computing [49] the field of charged filaments distributed near conducting cylinders.

II. We seek the function which is harmonic in ${\bf G}_1$ assuming the following boundary values:

$$u(s)\Big|_{\Gamma_h} = \psi(s) \qquad (k=0, 1, ..., p),$$

$$\left(\frac{\partial u}{\partial n} + \gamma_h \frac{\partial u}{\partial s}\right)\Big|_{\Gamma_h} = \varphi(s) \quad (k=p+1, ..., m),$$

where $\psi(s)$ and $\varphi(s) = \frac{\partial \psi}{\partial s}$ are known functions, and γ_k are nonzero constants.

III. We seek the function v which is harmonic in \mathcal{G}_{i} with the following boundary values:

$$\frac{\partial u}{\partial n}\Big|_{\Gamma_h} = -\varphi(s) \qquad (k=0, 1, ..., p),$$

$$\left(\gamma_h \frac{\partial u}{\partial n} - \frac{\partial u}{\partial s}\right)\Big|_{\Gamma_h} = -\varphi(s) \qquad (k=p+1, ..., m).$$

The general solution to the Riemann-Hilbert problem with (2n + 1-m) arbitrary coefficients (their number may be equal to zero for the region of odd connectedness) is constructed [47] from a solution to these boundary value problems. To obtain some partial solution, it is necessary to have additional information relative to the unknown function (see [53], Chapter 4, §6).

Let us analyze Problem I. It was analyzed in the previous section and therefore we shall not touch upon the details of the cited algorithm. We know [53] that for uniqueness of H_0 - the holomorphic function, g(z) = u + iv, where

$$\Delta u = 0 \text{ in region } G_i,$$

$$\begin{bmatrix} u \\ \Gamma_0 \end{bmatrix} = \omega(s),$$

$$\begin{bmatrix} 1 \\ \Gamma_k \end{bmatrix} = \omega(s) + G_k \quad (k = 1, 2, ..., m),$$

$$\begin{bmatrix} 1 \\ \Gamma_k \end{bmatrix} = \omega(s) + G_k \quad (k = 1, 2, ..., m),$$

it is necessary and sufficient that the constants $\boldsymbol{\mathsf{G}}_k$ be selected in such a way that

$$\int_{\Gamma_b} \frac{\partial v}{\partial s} ds = 0 \quad (k = 1, 2, ..., m)$$

or taking into account the Cauchy-Riemann relationships we find for determination of ${\tt G}_{\tt L}$ the following conditions:

$$\int_{\Gamma_{b}} \frac{\partial u}{\partial n} ds = 0 \quad (k = 0, 1, ..., m).$$
 (10.2)

Equation (10.2) when k = 0 is a simple corollary of the harmonicity of u and Equation (10.2) when k = 1, 2, ..., m.

In the preceding section for solving problem (10.1) - (10.2) we solved m boundary value Problems (9.3). In the present section we give formulas for solving Problem (10.1) - (10.2), which do not require preliminary solution to all problems in (9.3).

For solution to Problem (10.1) - (10.2) the methods developed above are well suited because in the course of solving the problems by these methods the function $\frac{\partial u}{\partial n}$ is computed automatically.

Using the Green formula for solving Problem (10.1), we find (below we will use the notations in Reference [3])

$$u(x) = \frac{1}{2\pi} \sum_{k=0}^{m} \int_{\Gamma_k} \left[\omega(s) + C_k \right] \frac{\partial}{\partial n_y} \ln r(x, y) ds_y - \frac{1}{2\pi} \int_{\Gamma} \ln r(x, y) \varphi(y) ds_y, \quad x \in G_t,$$

$$(10.3)$$

$$0 = \frac{1}{2\pi} \sum_{k=0}^{m} \int_{\Gamma_k} \left[\omega(s) + C_k \right] \frac{\partial}{\partial n_y} \ln r(x, y) ds_y - \frac{1}{2\pi} \int_{\Gamma} \ln r(x, y) \varphi(y) ds_y, \quad x \in G_e,$$

$$(10.4)$$

where

$$G_e = \sum_{k=0}^{m} G_k \text{ (Fig. 3) } \varphi(y) = \frac{\partial u}{\partial n} \bigg|_{\Gamma}, \quad c_0 = 0.$$
 (10.5)

Taking into account the notation

$$\int_{\Gamma} \omega(s) \frac{\partial}{\partial n_y} \ln r(x, y) ds_y = F(x_y), \qquad (82)$$

and the equation

$$\int_{\Gamma_{-}} \frac{\partial}{\partial n_{y}} \ln r(x, y) ds_{y} = \begin{cases} 2\pi & \text{for } x \in G_{k} \\ 0 & \text{for } x \in G_{e} - G_{k}, \end{cases}$$

Equation (10.4) takes the form

$$\int_{\Gamma} \ln r(x, y) \varphi(y) ds_y = F(x) + 2\pi G, \quad x \in G_h.$$
 (10.6)

Let us analyze the system $\{\varphi_i(y)\}[3]$, obtained by orthonormalization of the linearly independent and complete (14) system $\{\ln r(x_i, y)\}$, where \mathbf{x}_i are elements of the denumerable set, distributed everywhere dense on the auxiliary [3] boundary $\mathbf{s} = \mathbf{s}_0 + \mathbf{s}_1 + \mathbf{s}_2 + \ldots + \mathbf{s}_m$ (Figure 3)

$$\varphi_{l}(y) = \sum_{j=1}^{l} A_{j, l} \ln r(x_{j}, y),$$

where $A_{i,i}$ are the coefficients of orthonormalization.

Let us write (10.6) for the points x_i

$$\int_{\Gamma} \ln r(x_i, y) \varphi(y) ds_y = F_i + 2\pi C^{(i)}, \quad x_i \in G,$$
(10.7)

where $F_i = F(x_i)$, $C^{(i)} = C_k$, if $x_i \in S_k$. Multiplying the first i in the equation by $A_{j,i}$ (j = 1,2,..., i) and combining them

$$\int_{\Gamma} \varphi(y) \, \varphi_i(y) \, ds_y = \Phi_i = \sum_{j=1}^i A_{j,i} \, F_j + \sum_{j=1}^i C^{(i)} A_{j,i} = \overline{\Phi}_i + \sum_{j=1}^i C^{(i)} A_{j,i}, \qquad (10.8)$$

where Φ_i are Fourier coefficients of the unknown function $\varphi(y)$.

$$\overline{\Phi}_i = \sum_{j=1}^i A_{j,i} F_j.$$

It is well known that for an arbitrary ϵ there is an N₀ such that when $N > N_0$, for any k < m, the following inequality will be satisfied

Proof of linear independence and completeness of this system is analogous to that in the case of a singly connected region [3].

$$\int_{\Gamma_{K}} \left| \varphi(y) - \sum_{i=1}^{N} \Phi_{i} \varphi_{i}(y) \right|^{2} ds_{y} < \varepsilon \quad (k=1, 2, ..., m),$$

and a fortiori the approximate equation

$$\int_{\Gamma_k} \varphi(y) ds_y = \int_{\Gamma_k} \sum_{i=1}^N \Phi_i \varphi_i(y) ds_y \quad (k=1, 2, ..., m).$$

Therefore, taking into account (10.2) and (10.8) we find the following system for determining the constants C_k :

$$B_k = \sum_{i=1}^{N} \overline{\Phi}_i f_{i,k} = \sum_{i=1}^{N} 2\pi \sum_{j=1}^{i} C^{(j)} A_{j,i} f_{i,k} \quad (k=1, 2, ...),$$
 (10.9)

where

$$\int_{\Gamma_h} \varphi_i(y) \, ds_y = f_i, \, _h.$$

Grouping in the right-hand side of the k^{th} equation (k = 1, 2, ..., m) (10.9) the terms with identical coefficient C_s (s = 1, 2, ..., m) and denoting their sum by $A_{k,s}$, we find the system

$$B_k = \sum_{s=1}^{m} \overline{A}_{k,s} C_s \quad (k=1, 2, ..., m).$$
 (10.10)

Determining from (10.10) the coefficients C_k ($k=1,2,\ldots,m$) and substituting them into (10.8) we find the Fourier coefficients of the unknown function $\varphi(y)$. Instead of $\varphi(y)$ in (10.3) if we use the corresponding generalized Fourier series

$$\varphi^{(N)}(y) = \sum_{i=1}^{N} \Phi_i \varphi_i(y),$$

we find the approximate value of $u^{(N)}(x)$ of the unknown solution to problem I at the arbitrary point x inside the region G. From the convergence of $\phi^{(N)}(y)$ to $\phi^{(y)}$, in the sense of the metric L_2 , there directly follows the uniform convergence of $u^{(N)}(x)$ to u(x).

Substituting into (10.6) the integral of any quadrature formula and assigning to the parameter x different values of the auxiliary contour s, we find the following system:

$$\sum_{i=1}^{N} a_{i,j} \varphi_{i} = \sum_{i=1}^{N} \alpha_{i} \ln r (x_{j}, y_{i}) \varphi_{i} = F_{j} + 2\pi C^{(j)}, \qquad (10.11)$$

where $C^{(j)} = C_k$, if $x_j \in s_k$. Let us write (10.11) in vector form

$$A\varphi = F + 2\pi C. \tag{10.12}$$

For the analyzed system we can prove the theorems which are analogous to Theorems 5 - 7 in Reference [4] (in Reference [4] in the formulation of Theorem 7 there is a misprint; instead of the asymptotic inequalities $\lambda_1 \leq \mathrm{O(N}^{-1/2})$, $\frac{/84}{\lambda_1} \leq \mathrm{O(N}^{-1})$, $\mu_1 \leq \mathrm{O(N}^{-1})$ and $||\mathbf{L}^{-1}||$ $R_N \geq \mathrm{O(\sqrt{N})}$, respectively). Thus, for example, in complete analogy with the arguments cited in [3] we can prove that for any N there are N values \mathbf{x}_k of the parameter x such that System (10.12) will be solvable, and the solution may be found by the method of successive approximations, beginning from the aribtrary vector $\boldsymbol{\phi}^{(0)}$. In this case the norm in the sense of the space \mathbf{m}_N of the inverse operator \mathbf{A}^{-1} can be made as near to 1 as desired. From (10.12) we obtain

$$\varphi = A^{-1} F + 2\pi A^{-1} C. \tag{10.13}$$

Replacing the integral in (10.2) by the quadrature formula and using (10.13), we find a system of m equations for determining the coefficients C_k (k = 1, 2, ..., m). The values obtained for C_k are substituted into (10.13) and the vector ϕ is determined, thus making it possible to compute the solution to the problem from Equation (10.3) by first replacing the integrals in it with quadrature sums.

For computation of the function v, we can use the algorithm from Reference [51], which assumes computation of the values v in the points at the limit by recurrence relationships (difference analog of the Cauchy-Riemann relationships), and in the interior points by solution of the system of difference equations. However, knowledge of the functions $\left| \Gamma \right|_{\Gamma}$ and $\left| \frac{\partial u}{\partial n} \right|_{\Gamma}$ makes it possible for computation of v to use the Green formula

$$v(x) = \frac{1}{2\pi} \int_{\Gamma} v(y) \frac{\partial}{\partial n_y} \ln r(x, y) ds_y - \frac{1}{2\pi} \int_{\Gamma} \ln r(x, y) \frac{\partial v}{\partial n} ds_y,$$

where

$$v(y) = v_0 + \int_0^y \frac{\partial v}{\partial s} ds = v_0 + \int_0^y \frac{\partial u}{\partial n} ds = v_0 + \int_0^y \varphi(t) dt,$$
$$\frac{\partial v}{\partial n} = \frac{\partial u}{\partial s} = \omega'_s(s).$$

As far as Problems II and III are concerned, for their solution we can use the method of finite differences as described in [47] (15) or use the methods in References [1,3]. For the latter case we will give the formulas without discussing convergence of the respective computational algorithms.

Let us analyze Problem II. From its boundary values we determine

$$\frac{\partial u}{\partial n} \Big|_{\Gamma_h} = \varphi(s) - \gamma_h \left(\frac{\partial u}{\partial s} \right) \Big|_{\Gamma_h} \quad (k = p + 1, \dots, m). \tag{10.14}$$

⁽¹⁵⁾ However, we must note that the accuracy of the formulas in Reference ([47] for the points of the contours Γ_k (k=1, 2, ..., m) in the case of Problem II, and for the points of the boundary Γ in the case of Problem III, is by a whole order of magnitude inferior to the formulas in Reference [54]. Proofs of the convergence of this net-point method for Problems II and III in [47] are not vigorous, and the final computations are rather rough (compare with the computations in Reference [55]).

Using the Green formulas for Problem II and (10.14), we find

/85

$$u(x) = \frac{1}{2\pi} \sum_{i=1}^{p} \int_{\Gamma_{i}} \psi(s) \frac{\partial}{\partial n_{y}} \ln r(x, y) ds - \frac{1}{2\pi} \sum_{k=p+1}^{m} \int_{\Gamma_{k}} \ln r(x, y) \left[\varphi(s) - \gamma_{k} \frac{\partial u}{\partial s} \right] ds_{y} + \frac{1}{2\pi} \sum_{k=p+1}^{m} \int_{\Gamma_{k}} \overline{\psi}(s) \frac{\partial}{\partial n_{y}} \ln r(x, y) ds_{y} - \frac{1}{2\pi} \sum_{i=0}^{p} \int_{\Gamma_{i}} \ln r(x, y) \varphi(s) ds_{y}, \quad x \in G_{i},$$

$$(10.15)$$

$$0 = \sum_{i=0}^{p} \int_{\Gamma_{i}} \psi(s) \frac{\partial}{\partial n_{y}} \ln r(x, y) ds_{y} - \sum_{k=p+1}^{m} \int_{\Gamma_{k}} \ln r(x, y) \left[\varphi(s) - \frac{\partial u}{\partial s} \right] ds_{y} + \sum_{k=p+1}^{m} \int_{\Gamma_{k}} \overline{\psi}(s) \frac{\partial}{\partial n_{y}} \ln r(x, y) ds_{y} - \sum_{i=0}^{p} \int_{\Gamma_{i}} \ln r(x, y) \overline{\psi}(s) ds_{y}, \quad x \in G_{e},$$

$$(10.16)$$

where

$$\overline{\varphi}(s) = \frac{\partial u}{\partial n} \Big|_{\Gamma_t} \qquad (i = 0, 1, ..., p),$$

$$\overline{\psi}(s) = u \Big|_{\Gamma_k} \qquad (k = p + 1, ..., m).$$

Let us analyze the expression

$$\int_{\Gamma_k} \ln r(x, y) \frac{\partial u}{\partial s} ds \qquad (k = p+1, \dots, m).$$

Applying to it the formula of integration by parts and taking into account the periodicity of the function $\ln r(x,y)$ for variable y, we obtain

$$\int_{\Gamma_k} \ln r(x, y) \frac{\partial u}{\partial s} ds_y = - \int_{\Gamma_k} \overline{\psi}(s) \frac{\partial}{\partial s_y} \ln r(x, y) ds_y.$$

Taking this latter equation into account, (10.15) and (10.16) take the form

$$u(x) = \overline{F}(x) + \frac{1}{2\pi} \sum_{k=p+1}^{m} \int_{\Gamma_{k}} \overline{\psi}(s) \left[\frac{\partial}{\partial n_{y}} \ln r(x, y) - \gamma_{k} \frac{\partial}{\partial s_{y}} \ln r(x, y) \right] ds_{y} -$$

$$-\frac{1}{2\pi} \sum_{i=0}^{p} \int_{\Gamma_{L}} \ln r(x, y) \,\overline{\varphi}(s) \, ds_{y}, \quad x \in G_{L},$$

$$0 = 2\pi \,\overline{F}(x) + \sum_{k=p+1}^{m} \int_{\Gamma_{k}} \overline{\psi}(s) \left[\frac{\partial}{\partial n_{y}} \ln r(x, y) - \frac{\partial}{\partial s_{y}} \ln r(x, y) \right] \, ds_{y} - \sum_{k=0}^{p} \int_{\Gamma_{k}} \ln r(x, y) \, \overline{\varphi}(s) \, ds_{y}, \quad x \in G_{e},$$

$$(10.17)$$

where

$$\overline{F}(x) = \frac{1}{2\pi} \sum_{i=0}^{p} \int_{\Gamma_{i}} \psi(s) \frac{\partial}{\partial n_{y}} \ln r(x, y) ds_{y} - \frac{1}{2\pi} \sum_{k=p+1}^{m} \int_{\Gamma_{k}} \ln r(x, y) \varphi(s) ds_{y}$$

is a known function.

From the boundary conditions of Problem III we determine

$$\frac{\partial u}{\partial n} \Big|_{\Gamma_h} = \frac{1}{\gamma_h} \frac{\partial u}{\partial s} \Big|_{\Gamma_h} - \frac{\tau}{\gamma_h} \qquad (k = p+1, \dots, m). \tag{10.19}$$

Applying the Green formula and (10.19) to solution of Problem III, we obtain

$$u(x) = \frac{1}{2\pi} \int_{\Gamma} \psi(s) \frac{\partial}{\partial n_{y}} \ln r(x, y) ds_{y} +$$

$$+ \frac{1}{2\pi} \sum_{k=0}^{p} \int_{\Gamma_{k}} \ln r(x, y) \varphi(y) ds_{y} - \frac{1}{2\pi\gamma_{k}} \sum_{k=p+1}^{m} \int_{\Gamma_{k}} \left[\frac{\partial u}{\partial s} - \varphi(y) \right] r(x, y) ds_{y}, \quad x \in G_{i},$$

$$(10.20)$$

$$0 = \frac{1}{2\pi} \int_{\Gamma} \psi(s) \frac{\partial}{\partial n_{y}} \ln r(x, y) ds_{y} + \frac{1}{2\pi} \sum_{k=0}^{p} \int_{\Gamma_{k}} \ln r(x, y) \varphi(y) ds_{y} - \frac{1}{2\pi \gamma_{k}} \sum_{k=p+1}^{m} \int_{\Gamma_{k}} \left[\frac{\partial u}{\partial s} - \varphi(y) \right] r(x, y) ds_{y}, \quad x \in G_{e},$$

$$(10.21)$$

where

$$\psi(s) = u \mid \Gamma.$$

Using the formula of integration by parts, Expressions (10.20) and (10.21) assume the following form:

$$u(x) = \frac{1}{2\pi} \sum_{k=0}^{p} \int_{\Gamma_{k}} \Phi(s) \frac{\partial}{\partial n_{y}} \ln r(x, y) ds_{y} + \frac{1}{2\pi} \int_{\Gamma} \ln r(x, y) \varphi(y) ds_{y} + \frac{1}{2\pi} \sum_{k=p+1}^{m} \int_{\Gamma_{k}} \Phi(y) \left[\frac{\partial}{\partial n_{y}} \ln r(x, y) - \frac{1}{\gamma_{k}} \frac{\partial}{\partial s_{y}} \ln r(x, y) \right] ds_{y}, \quad x \in G_{t},$$

$$0 = \frac{1}{2\pi} \sum_{k=0}^{p} \int_{\Gamma_{k}} \Phi(y) \frac{\partial}{\partial n_{y}} \ln r(x, y) ds_{y} + \frac{1}{2\pi} \int_{\Gamma} \ln r(x, y) \varphi(y) ds_{y} + \frac{1}{2\pi} \sum_{k=p+1}^{m} \int_{\Gamma_{k}} \Phi(y) \left[\frac{\partial}{\partial n_{y}} \ln r(x, y) - \frac{\partial}{\partial s_{y}} \ln r(x, y) \right] ds_{y}, \quad x \in G.$$

$$(10.22)$$

Formulas (10.17) -(10.18) and (10.22) - (10.23) make it possible to use the methods described above for solving Problems II and III.

Let us indicate still one other method for solving the modified Dirichlet problem.

Let $\{\varphi_i(x)\}\ [x\ (x_1,\ x_2)]$ be an orthonormalized system of functions harmonic in \mathbb{G}_i . Furthermore, we shall assume that the system $\{\varphi_i(x)\}$ is complete on Γ in

the sense of the metric $L_2(\Gamma)$, i.e., for any function $\gamma(y) \in L_2(\Gamma)$ $(y \in \Gamma)$ and for any $\epsilon > 0$, we find N of the coefficients \mathbf{b}_i such that the following inequality will be satisfied

$$\left\{ \int_{\Gamma} \left[\gamma(y) - \sum_{i=1}^{N} b_{i} \varphi_{i}(y) \right]^{2} ds_{y} \right\}^{1/2} < \varepsilon.$$

Let us look at the boundary value problem (Figure 1)

$$\Delta u = 0$$
 in G_i
 $u \mid_{\Gamma} = \gamma(y)$.

With the aid of the Schwarz inequality (and in the case of completeness in the sense of the metric C using the principle of the maximum) it is easy to show that in any interior point of the region G_i and uniformly in any region completely lying in the open region G_i , the difference

$$u(x) - \sum_{i=1}^{N} b_i \varphi_i(y)$$

can be made as small as desired. This method for solving the boundary value problems (the Piconet method [6]) may be quite effective with proper selection of the system $\{\varphi(x)\}$).

Let us look at the following problems:

$$\Delta u_0 = 0 \quad \text{in } G,$$

$$u_0 \mid_{\Gamma} = \omega \text{ (s)},$$

$$\Delta u_i = 0 \quad \text{in } G_i,$$

$$(10.23_1)$$

$$\begin{vmatrix} u_i \\ \Gamma - \Gamma_i \end{vmatrix} = 0 \qquad k = (1, 2, ..., m),$$

$$\begin{vmatrix} u_i \\ \Gamma_i = 1. \end{vmatrix}$$

Let the approximate solutions to these problems be represented in the form of the following series:

$$u_i \approx \sum_{j=1}^{N_i} A_{j,i} \varphi_i = \bar{u}_i \quad (i = 0, 1, 2, ..., m).$$

Let us introduce the following notations

$$\int_{\Gamma_k} \frac{\partial \overline{u}_i}{\partial n} ds = e_{k,i} \qquad (i=0, 1, 2, ..., m; k=1, ..., m).$$

To determine the coefficients c_i (i = 1,...,m) of Problem (10.1) - (10.2), we obtain the following system:

$$\sum_{i=1}^{m} c_i e_{k, i} = e_{k, 0}, \quad k = 1, 2, ..., m.$$
 (10.3₂)

Determining c_i from this latter system, the approximate solution \bar{u} to Problem (10.1) - (10.2) takes the following form:

$$\bar{u} = \sum_{i=0}^{N} c_i \, \bar{u}_i,$$

where $c_0 = 0$.

Usually [6] in the case of a singly connected region, as such a system we take the system $\{p_i(x)\}$ of harmonic polynomials; we know that they are complete in $L_2(\Gamma)$, where Γ is a contour bounding a singly connected region (if this region has a stable solution of the Dirichlet problem with respect to deformation of the region, then the system of harmonic polynomials is complete on Γ in the sense of the metric C).

It is clear then in the case of a multiply connected region the system $\{p_t(x)\}$ can be complete neither in the sense of the metric C nor in the sense of the metric L_2 .

For any continuous function $\gamma(y)$ let

$$\max_{y \in \Gamma} \left| \gamma(y) - \sum_{i=1}^{N} b_i p_i(y) \right| < \varepsilon \qquad (y \in \Gamma).$$

From the principle of the maximum it directly follows that if for the function $\Upsilon(y)$ the following inequality is satisfied

$$\max_{y \in \Gamma} |\gamma(y)| > \max_{y \in \Gamma_0} |\gamma(y)|,$$

then such a function cannot be approximated sufficiently well by harmonic polynomials. However, this latter inequality may not be satisfied for the function $\gamma(y)$ either, and cannot be approximated by harmonic polynomals.

$$\gamma_1(y) = \gamma_2(y)$$
 on Γ_0 (Figure 1)
$$\max_{y \in \Gamma - \Gamma_0} |\gamma_1(y) - \gamma_2(y)| = 1.$$
(10.24)

On the strength of our assumption for any $\epsilon>0$ we find coefficients $b\,^{(1)}_{\ \lambda}$ and $b\,^{(2)}_{\ i}$ such that

$$\max_{y \in \Gamma} \left| \gamma_1 - \sum_{i=1}^{N_1} b_i^{(1)} p_i(y) \right| < \frac{\varepsilon}{4}, \quad \max_{x \in \Gamma} \left| \gamma_2 - \sum_{i=1}^{N_2} b_i^{(2)} p_i(y) \right| < \frac{\varepsilon}{4}.$$

From the principle of the maximum and the first of the equations in (10.24), we find that at any point of the region G bounded by the contour Γ_0 , the following inequality is valid

$$\left| \sum_{i=1}^{N_1} b_i^{(1)} p_i(y) - \sum_{i=1}^{N_2} b_i^{(2)} p_i(y) \right| < \frac{\varepsilon}{2},$$

and therefore,

$$\max_{y \in \Gamma - \Gamma_{0}} \left| \gamma_{1}(y) - \gamma_{2}(y) \right| \leq \max_{y \in \Gamma - \Gamma_{0}} \left| \gamma_{1}(y) - \sum_{i=1}^{N_{1}} b_{i}^{(1)} p_{i}(y) + \sum_{i=1}^{N_{2}} b_{i}^{(2)} p_{i}(y) - \gamma_{2}(y) \right| + \frac{\varepsilon}{2} < \varepsilon,$$

which contradicts the second equation in (10.24).

The system $\{p_i(x)\}$ may not be complete in the sense of $L_2(\Gamma)$ either. Let us look at the problem

$$\Delta u = 0$$
 on G' ,
 $u \Big|_{\Gamma_0} = \gamma_1(y)$,

and the function $\gamma(y)$, which satisfies the conditions

$$\gamma(y) = \gamma_1(y) \quad \text{на} \quad \Gamma_0,$$

$$\gamma(y) = u(y) + C_k \quad \text{на} \quad \Gamma_k \quad (k = 1, \dots, m),$$

where $u(y) = u(x^k)$ and at least one of the constants C_k is not zero.

From the respresentation of the solution to the Dirichlet problem for the region G with the aid of the Green function and from the Schwarz inequality, it becomes clear that it is impossible to approximate the function $\gamma(y)$ sufficiently well in the sense of the metric L_2 by harmonic polynomials. From these arguments it follows that the functions from the complete (either in the sense of the metric $L_2(\Gamma)$, or the sense of the metric $C(\Gamma)$) system cannot all be harmonic simultaneously at all points of the region G^{\dagger} .

As far as the author knows, the only system of harmonic functions complete /90 in the sense of the metric $L_2(\Gamma)$ is given in Reference [3].

$$\{\ln r(x_i, x)\},\tag{10.25}$$

where the points x_i are distributed everywhere densely on $s = s_0 + s_1 + \dots + s_m$ (Figure 3).

We must also mention that this system greatly facilitates computation of the coefficients $e_{k,i}$ (k = 1,22..., m; i = 0,1,..., m) of the system from which c_i (i = 1,2,..., m) are determined.

In fact it is easy to see that

$$e_h, l=2\pi \sum_{j=1}^{N_l} r_j A_j, l,$$

where

$$u_{i} = \sum_{j=1}^{N_{i}} A_{j, t} \ln r(x_{j}, x), r_{i} = \begin{cases} 1, & x_{j} \in G_{h} \\ 0, & x_{j} \in G_{e} - G_{h}. \end{cases}$$

Analogously the computations of the coefficients are simplified if instead of System (10.25) we analyze the corresponding orthonormalized system.

In conclusion let us prove the solvability of System (10.10) and (10.3 $_2$). It is easy to see that $\bar{A}_{k,s}$ and B_k (k,s = 1, 2, ..., m) in (10.10), when N $\rightarrow \infty$ approach the expressions

$$\int_{\Gamma_h} \frac{\partial u_s}{\partial n} ds, \qquad \int_{\Gamma_h} \frac{\partial u_0}{\partial n} ds,$$

respectively, where u_s are determined in (10.23₁).

The coefficients $\mathbf{e}_{k,i}$ and $\mathbf{e}_{k,0}$ in (10.32) approach these same expressions under the condition

$$\lim_{N\to\infty} \left| \left| \frac{\partial}{\partial n} \left(u_i - \overline{u}_i \right) \right| \right|_{L_2} = 0 \quad (i=0, 1, ..., m),$$

so that the limiting form of Systems (10.10) and (10.23₂) coincides. Therefore, further discussions on the solvability of these systems are completely analogous to those given on pages 98 and 100. We shall omit these and refer the reader to those pages.

§11. Solution to the External Dirichlet Problem for the Laplace Equation Using the Method of Functional Equations.

The program is intended for obtaining a harmonic function outside the ellipse

$$s: y_1 = \cos \alpha, \quad y_2 = b \sin \alpha$$

under the boundary condition $|u|_{s} = f(y), y \in s$.

The program consists of four parts:

- 1. An operational program for transferring from the third and fourth parts from the main memory to the drum, and also for transferring the initial data to the main memory and for transferring the third and fourth parts from the drum to the main memory.
- II. A program which converts the array of coordinate points outside the ellipse from the decimal notation system into a binary one and transfers them to the drum.
- III. A program which computes the axes of the auxiliary boundary s_1 , as well as the coordinates of the points on this boundary and prints out these coordinates. It also computes the scalar products (ω_k, ω_i) , and the coefficients of orthonormalization $A_{k,i}$; it computes the orthonormalized functions and verifies the orthonormalization.
- IV. A program for computing the values of the harmonic function at given points outside the ellipse. The program prints out the coordinates of these points and the solutions corresponding to them.

Computational Procedure

The computational process consists of the following stages:

- 1. Computation of the coordinates of the auxiliary points and scalar products.
 - 2. Computation of the coefficients of orthonormalization.
- 3. Computation of the orthonormalized functions and proof of orthonormalization.
- 4. Computation of the Fourier coefficients and the normal derivative of the unknown function.
 - 5. Computation of the values for solution to the problem.

 Computation of the Coordinates of the Auxiliary Points and Scalar Products.

The auxiliary points are taken on the confocal ellipse with semiaxes $\bar{a} = \frac{\bar{b}}{p}$ and $\bar{b} = b - (b - \bar{b})$, where $(b - \bar{b})$ is given in the initial data (cell 0622). The coordinates of the auxiliary points are computed from the formula

$$x_1^{(k)} = \bar{a} \cos \alpha_k, \quad x_2^{(k)} = \bar{b} \sin \alpha_k \quad (k = 1, 2, ..., 24).$$
 (1.1)

 α_h (k=1, 2, ..., 24) assume the values given in Table 7.

The scalar products

$$(\omega_h, \omega_l) = \int_0^{2\pi} \omega_h(\alpha) \, \omega_l(\alpha) \, d\alpha, \qquad (1.2)$$

where

/92

$$\omega_h(\alpha) = \frac{1}{2} \ln \left[(\cos \alpha - x_1^{(k)})^2 + (b \sin \alpha - x_2^{(k)})^2 \right]$$

are computed by Simpson's method.

2. Computation of the Coefficients of Orthonormalization.

The coefficients of orthonormalization $\mathbf{A}_{k,i}$ are computed from the following formulas:

$$A_k, k = \frac{1}{||g_k||} \quad (k = 1, 2, ..., 24),$$
 (2.1)

$$A_{k,h-i} = A_{k,h} \sum_{j=1}^{i} \alpha_{k,h-j} A_{k-j,h-i} \quad (k=2, 3, ..., 24; i=1, 2, ..., 23),$$
 (2.2)

where

$$= \sqrt{\sum_{j=0}^{k-1} B_{k, k-j}^{2\pi} \int_{0}^{2\pi} \omega_{k-j}^{2} d\alpha + 2 \sum_{j=0}^{k-2} B_{k, k-j} \sum_{i=1}^{k-j-1} B_{k, i} \int_{0}^{2\pi} \omega_{k-j} \omega_{i} d\alpha}, B_{k,k} = 1,$$
 (2.3)

$$\alpha_{k}, \, _{k-j} = -\sum_{i=1}^{k-j} A_{k-j}, \, _{i} \int_{0}^{2\pi} \omega_{k} \omega_{i} \, d\alpha \, (k=2, 3, ..., 24; \, j=k-1, k-2, ..., 1),$$
 (2.4)

$$B_{h,j} = \sum_{i=1}^{k-j} \alpha_{h,k-j} A_{h-i,j}, \quad (k=2, 3, ..., 24; \quad j=k-1, k-2, ..., 1).$$
(2.5)

Computation of the Orthonormalized Functions and Checking of Orthonormalization.

The value of the orthonormalized functions is computed at the points $\alpha_j = (j-1) - \frac{\pi}{125}$ by the formula

$$\varphi_h(\alpha_j) = \sum_{i=1}^k A_{h,i} \omega_i(\alpha_j), \quad (k=1, 2, ..., 24; j=1, 2, ..., 250).$$
 (3.1)

The correctness of the orthonormalization is checked by the formula

$$1 - (\varphi_k, \varphi_i) = 1 - \frac{\pi}{125} \sum_{j=1}^{250} \varphi_k(\alpha_j) \varphi_i(\alpha_j) < 10^{-4} \text{ when } k = i,$$

$$(\varphi_k, \varphi_i) = \frac{\pi}{125} \sum_{j=1}^{250} \varphi_k(\alpha_j) \varphi_i(\alpha_j) < 10^{-4}$$
 when $k \neq i$.

4. Computation of the Fourier Coefficients and the Normal Derivative of $\frac{93}{}$ the Unknown Function.

The Fourier coefficients of the unknown function $\varphi(y)$ are computed by the formula

$$\Phi_i = \sum_{k=1}^i A_k, {}_iF_k \quad (i=1, 2, ..., 24), \tag{4.1}$$

where

$$F_{k} = \int_{0}^{2\pi} f(\alpha) \frac{b - (b\cos\alpha x_{1}^{(k)} + \sin\alpha x_{2}^{(k)})}{(\cos\alpha - x_{1}^{(k)})^{2} + (b\sin\alpha - x_{2}^{(k)})^{2}} d\alpha, \ (k = 1, 2, ..., 24) \ (4.2)$$

 $\mathbb{A}_{k,j}$ are the coefficients of orthonormalization.

The normal derivative of the unknown function is computed at the points $\alpha_j = (j-1) \frac{\pi}{125}$ by the formula

$$\varphi(\alpha_{j}) = \sum_{i=1}^{24} \Phi_{i} \varphi_{i}(\alpha_{j}) \quad (j = 1, 2, ..., 250)$$
(4.3)

5. Computation of the Values for Solution to the Problem.

The value for the solution to the problem at points outside the ellipse is sought with the formula

$$u(\xi, \eta) = \frac{1}{250} \sum_{j=1}^{250} \left\{ -f(\alpha_j) \frac{b - (b\cos\alpha_j \cdot \xi + \sin\alpha_j \cdot \eta)}{(\cos\alpha_j - \xi)^2 + (b\sin\alpha_j - \eta^2)} + \frac{1}{2} \ln \left[(\cos\alpha_j - \xi)^2 + (b\sin\alpha_j - \eta)^2 \right] \varphi(\alpha_j) \right\}, \quad \alpha_j = (j-1) \frac{\pi}{125}, \quad (\xi, \eta) \in B_a. \quad (5.1)$$

FLOW DIAGRAM

Overall Flow Diagram

- A Operating program.
- B Standard subprogram block.
- C Computation of coordinates of points outside ellipse.
- D Computation of coordinates of auxiliary points and scalar products.
- E Computation of coefficients of orthonormalization.
- F Computation of orthonormalized functions and proof of orthonormalization.
- G Computation of Fourier coefficients and the normal derivative of the unknown function.
- H Computation of the value for solution to the problem.

Block A

/94

- A 1 Read in fundamental program.
- A 2 Transfer third and fourth parts of program to drum.
- A 3 Read in input card for initial data.
- A 4 Read in initial data.
- A 5 Refer to B 1.
- A 6 Refer to C.
- A 7 Transfer third part of program to main memory from drum and access \mathbb{D}_{\circ}
- A 8 Transfer fourth part of program to main memory from drum and access G.

Block B

- B 1 Block transfer array " $10 \rightarrow 2$ ".
- B 2 Compute $\sin x$ and $\cos x$.
- B 3 Compute log x.

- B 4 Block transfer "2 \rightarrow 10".
- B 5 Compute specified integral by Simpson's method with automatic calling sequence (Authors L. S. Tsyganova, I. L. Klimkina).
- B 6 Square root extraction.

Block C

- C 1 Transfer initial data to standard cells.
- C 2 Transfer programs for computing boundary function $f(\alpha)$ onto drum from main memory.
- C 3 Check the number of coordinates in the memory of the machine at the same time.
- C 4 Check how many points are given outside ellipse.
- C 5 Set up shaping constants.
- C 6 Shape commands for input of numerical data from reader to main memory.
- C 7 Read in numerical data.
- C 8 Shape commands for block transfer "10 \rightarrow 2".
- C 9 Refer to B 1.
- C 10 Shape commands for transfer to drum.
- C 11 Transfer numerical data to drum.
- C 12 Check if all numerical data have been fed into machine; if yes go to A 7, if no go to C 13.
- C 13 Readdress shaping constants and go to C 6.

Block D

- D 1 Compute \bar{a} and \bar{b} .
- D 2 Clear counter for k.
- D 3 Compute coordinates of auxiliary points from Formula (1.1).
- D 4 Refer to B 4.
- D 5 Print out $x_1^{(k)}$ and $x_2^{(k)}$.
- D 6 Readdress variable commands.
- D 7 Check if coordinates of all auxiliary points have been computed; if yes go to D 8, if no go to D 3.
- D 8 Set up variable commands for computation from Formula (1.2).

<u>/95</u>

- D 9 Refer to B 5.
- D 10 Transfer $(\omega_{\mathbf{k}}, \omega_{\mathbf{i}})$ to storage.
- D 11 Readdress variable commands.
- D 12 Check if all (ω_k, ω_i) have been computed; if yes go to E; if no go to D 9.

Block E

- E 1 Transfer $(\omega_1 \omega_1)$ to cell 0001.
- E 2 Refer to B 6.
- E 3 Compute $A_{1.1} = \frac{1}{\sqrt{(\omega_1 \omega_1)}}$.
- E 4 Transfer constants (00 0002 0000 0000) into counter for k.
- E 5 Retrieve variable commands and set up constants for shaping.
- E 6 Clear counter for j.
- E 7 Shape commands for computing products $A_{k-i,i}$ ($\omega_k \omega_i$).
- E 8 Compute products $A_{k-j,i}$ ($\omega_k^{\omega_i}$).
- E 9 Compute Formula (2.4).
- E 10 Check if all terms in Formula (2.4) have been computed; if yes go to E 11; if no go to E 14.
- E 11 Transfer values $\alpha_{k, k-i}$ to storage.
- E 12 Readdress variable commands and constants.
- E 13 Check if all α_k , k-j have been computed; if yes go to E 15; if no go to E 5.
- ${\tt E}$ 14 Set up shaper constants for computing the next term and go to ${\tt E}$ 7.
- E 15 Set up constants for shaping.
- E 16 Clear counter for j.
- E 17 Shape commands for computing the product $\alpha_{k,k-i}^{A_{k-i,j}}$.
- E 18 Compute product $\alpha_{k,k-i}^{A}_{k-i,j}$.
- E 19 Compute Formula (2.5).
- E 20 Check if all terms $B_{k,j}$ have been computed; if yes go to E 21; if no go to E 24.
- E 21 Transfer values $B_{k,i}$ to storage.
- E 22 Readdress variable commands and constants.

- E 23 Check if all B_{k,j} have been computed; if yes go to E 25, is no go to E 17.
- E 24 Set up shaping constants for computing the next term and go to E 17.
- E 25 Set up constants for shaping.
- E 26 Shape commands for computing the formula

$$\sum_{j=0}^{k-1} B_{k, k-j}^2 \int_0^{2\pi} \omega_{k-j}^2 d\alpha.$$
 (6)

/96

- E 27 Compute product B_k^2 , k-j $\int\limits_0^{2\pi} \omega_{k-j}^2 \,d\alpha$.
- E 28 Compute Formula (6).
- E 29 Check if all terms in Formula (6) have been computed; if yes go to E 31; if no go to E 30.
- E 30 Readdress variable commands for computing next term and go to E 27.
- E 31 Shape commands for computing the formula

$$2\sum_{j=0}^{k-2} B_{k,k-j} \sum_{i=1}^{k-j-1} B_{k,i} \int_{0}^{2\pi} \omega_{k-j} \omega_{i} d\alpha.$$
 (7)

- E 32 Compute product B_k , A_{k-j} , B_k , A_{k-j} , ω_{k-j} , ω_i $d\alpha$.
- E 33 Compute Formula (7).
- E 34 Check if all terms in Formula (7) have been computed; if yes go to E 36; if no go to E 35.
- ${\tt E}$ 35 Readdress variable commands for computing next term and go to ${\tt E}$ 32.
- E 36 Compute radicand.
- E 37 Refer to B 6.
- E 38 Shape commands for computing Formula (2.1).
- E 39 Compute Formula (2.1).
- E 40 Set up constants for shaping.

- E 41 Shape commands for computing Formula (2.2).
- E 42 Transfer constants (00 0001 0000 0000) to i-counter.
- E 43 Compute nondiagonal coefficient of given row using Formula (2.2).
- E 44 Check if all nondiagonal coefficients of given row have been computed; if yes go to E 46; if no go to E 45.
- E 45 Readdress commands for computing next nondiagonal coefficient and go to E 43.
- E 46 Check if all coefficients $A_{k,i}$ have been computed; if yes go to F; if not go to E 5.

<u>Block F</u> /97

- F 1 Retrieve variable commands.
- F 2 Clear counter for k.
- F 3 Compute Formula (3.1).
- F 4 Check if ϕ_k have been computed for all values α_j ; if yes go to F 5, if o no go to F 3.
- F 5 Transfer computed $\varphi_k(\alpha_i)$ to drum.
- F 6 Readdress variable commands.
- F 7 Check if all $\varphi_{\textbf{L}}$ have been computed; if yes go to F 8; if no go to F 3.
- F 8 Retrieve variable commands and set up constants.
- F 9 Copy values $\varphi_k(\alpha_i)$ from drum.
- F 10 Compute the formula

$$c = \frac{\pi}{125} \sum_{j=1}^{250} \varphi_k(\alpha_j) \varphi_i(\alpha_j).$$

- F 11 Check k = i; if yes go to F 17; if no go to F 12.
- F 12 Check Condition (3.3); if it is satisfied go to B 21; if not go to F 13.
- F 13 Transfer value C to cell 0001.
- F 14 Refer to B 4.
- F 15 Print out C.
- F 16 Refer to F 21.

- F 17 Check Condition (3.2); if satisfied go to B 21; if not go to F 18.
- F 18 Transfer value 1 C to cell 0001.
- F 19 Refer to B 4.
- F 20 Print out 1 C.
- F 21 Readdress variable commands and constants.
- F 22 Check if Conditions (3.2) and (3.3) have been verified for all ϕ_k ; if yes go to A 8, if no go to F 9.

Block G

- G 1 Transfer programs for computing boundary function $f(\alpha)$ from drum to main memory.
- G 2 Clear counter for k.
- G 3 Transfer coordinates of auxiliary points $x_1^{(k)}$ and $x_2^{(k)}$ to working cells.
- G 4 Refer to B 5.
- G 5 Readdress variable commands.
- G 6 Check if all F_{t} have been computed; if yes go to G 7; if no go to G 3.

<u>/98</u>

- G 7 Set up variable commands and shaping constants.
- G 8 Clear counter for i.
- G 9 Shape commands for computing product $A_{k,i}F_k$.
- G 10 Compute product A_{k,i}F_k.
- G 11 Compute Formula (4.1).
- G 12 Check if all terms of Formula (4.1) have been computed; if yes go to G 13; if no go to G 10.
- G 13 Transfer values Φ_i to storage.
- G 14 Readdress variable commands and constants.
- G 15 Check if all Φ_i have been computed; if yes go to G 16; if no go to G 9.
- G 16 Retrieve variable commands and set up constants for shaping.
- G 17 Clear counter for i.
- G 18 Transfer value $\phi_i(\alpha_i)$ from drum to main memory.
- G 19 Shape commands for computing Formula (4.3).
- G 20 Compute Formula (4.3).
- G 21 Readdress variable commands.

- G 22 Check if values of normal derivative of unknown function $\phi(\alpha)$ for all α , have been computed; if yes go to G 23; if no go to G 18.
- G 23 Check if necessary to print out; if yes go to G 24; if no go to $\mbox{\tt H}.$
- G 24 Refer to B 4.
- G 25 Print out $\varphi(\alpha_i)$.

Block H

- H 1 Set up shaping constants
- H 2 Transfer coordinates of points outside ellipse from drum to main memory.
- H 3 Retrieve variable commands and constants.
- H 4 Compute Formula (5.1).
- H 5 Refer to B 4.
- H 6 Print out ξ , η and $u(\xi, \eta)$.
- H 7 Readdress variable commands.
- H 8 Check if computation of Formula (5.1) for all transferred points is finished; if yes go to H 9; if no go to H 4.
- H 9 Check if all points are transferred from drum; if yes to go to H 11, if no go to H 10.
- H 10 Readdress shaping constants and go to H 2.
- H 11 Stop.

INSTRUCTION

1. Set Up of Initial Data

The initial data for the program consist of two parts:

1. Initial data in which programs are included for computing the boundary function and certain initial data.

The program for computing the boundary function $f(\alpha)$ must begin with cell 0626. The argument α is taken from cell 0001, and the result must be

/99

transferred to cell 0001. In the operation of the program for the boundary function in cells 0017 and 0020, we will find $\cos \alpha$ and $b \sin \alpha$, respectively. They may be used for computing the boundary function. In certain instances this greatly reduces the commands in the program for computing the boundary function.

The program for computing the boundary function certainly must end with the command 34 - 0555, i.e., after its operation it must transfer control to cell 0555. In setting up the program for computing the boundary function, as the working cells we can use 0.013-0.016, 0.021-0.033 and 0.0616-0.0625.

- The following initial data are transferred to cells 0622-0625:
- 0622-(b-b) is the difference between the minor semiaxes of the fundamental S and the auxiliary S_1 ellipses in the decimal notation system.
- 0623-b is the minor semiaxis of the basic ellipse, in the decimal notation system.
- 0623-N is the length of the program for computing the boundary function $f(\alpha)$ in the third address in the octal notation system. $N < 600_{(10)}$.
- 0625 is the cell with conditional data. Depending on which of the two numbers 0000, 0010 is found in the first address, the program will transfer the following numbers: 0010 250 values are printed out for the normal derivative of the unknown function at the points $\alpha_j = (j-1) \frac{\pi}{125} \,. \qquad 0000 \,-\, \text{no values are printed out for the normal derivative of the unknown function.}$

In the second address N_1 is registered - the number of points at which we are required to find a solution in the octal system of notation $N_1 < 3777_{(8)}$, and in the third address - 0000.

2. Numerical data (coordinates (ξ_i , η_i) of the points outside the

ellipse) must follow directly after the program for computing the boundary function. Thus, in cell 0626 + N we must find the abscissa ξ_1 of point Q_1 . In cell 0627 + N — the ordinate η_1 of this point. In the cell 0630 + N — the abscissa ξ_2 of point Q_2 , etc.

For input of the initial data we must make the following "input card":

30 0100		n-1
31	0622	0010
77		0060
0622	0002	0622
34		0134

where n is the length of the initial data.

2. Operation of Console

/100

The entire punchcard deck is assembled in the following order:

- 1. Operation code.
- 2. Blank card.
- Initial data input card.
- 4. Blank card.
- 5. Initial data.
- 6. Blank card.
- 7. Numerical data.

TABLE OF CONTROL STOPS

0013 33 0022 33 0032 33 0037 33 0151 33 0216 33 1036 33		0001 0002 0003 0004		input.	Repeat read in.
0022 33 0032 33 0037 33 0151 33 0216 33 1036 33	Annual .	0002 0003 0004			
0032 33 0037 33 0151 33 0216 33 1036 33		0003 0004		Incorrect drum	
0037 33 0151 33 0216 33 1036 33	- dynamics ,	0004		Incorrect drum	L_, a a
0151 33 0216 33 1036 33				•	With key start repeat
0216 33 1036 33				access.	access to drum.
1036 33	***	0005			
		0006			
		0007			
1056 33	*******	0010			
1064 33	*******	0011	*****		
0344 33	***************************************	0012			
	******	0013			
0464 33		0014	****	I .	Clear problem and enter
0073 33	******	0002	********	numbers from decimal to binary system.	again.
0153 33	***************************************	.0013	*****	Argument for which logar- ithm is sought is negativ	e.
0365 33	- Over-the	0010	******	Radicand negative.	Carry out command 34
1104 33		_	0001	Product (φ_k, φ_i) when $k \neq 0570$ from console. Continue computation key start. Difference $1-(\varphi_k, \varphi_i)$ when $k \neq 0570$ from console. Continue computation key start.	Continue computation with
1114 33	*****		0002		Continue computation with
0533 33	0002	_	-		
Elitable			T.	End of computation.	

If the stops given above are repeated several times, then the problem must be cleared and the machine checked.

It may happen that with the machine in good working order there occurs the stop 0365 (33 - 0010 -). In this case the difference (b- \overline{b}) must be decreased.

If the machine is in good working order and if the stops 1104 (33 — /101 0001) and 1114 (33 - 0002) are repeated several times, then it is necessary to decrease the difference (b - \overline{b}).

Interpretation of the Final Results of Machine Print Out

The program prints out the coordinates of the auxiliary points in the sequence:

$$x_1^{(1)}, x_2^{(1)}; x_1^{(2)}, x_2^{(2)}; x_1^{(3)}, x_2^{(3)}; \dots, x_1^{(24)}, x_2^{(24)}.$$

In checking the orthonormalization it may happen that Conditions (3.2) and (3.3) are not satisfied. If Condition (3.2) is not satisfied, then the machine prints out the value of the difference 1- (φ_h, φ_l) and the conditional digit (00 000 001) and if Condition (3.3) is not satisfied then only the value (φ_h, φ_l) is printed.

If it is required to print out the values of the normal unknown function $\varphi(\alpha)_i$, then the program prints out 250 values at the points $\alpha_j=(j-1)$ $\frac{\pi}{125}$ $(j=1,\,2,\,\ldots,\,250)$ in the sequence:

$$\varphi(\alpha_1), \varphi(\alpha_2), \ldots, \varphi(\alpha_{250}).$$

The program prints out the coordinates of the points at which solution to the boundary value problem and the solutions corresponding to it are found

$$\xi_1, \ \eta_1, \ u(\xi_1, \ \eta_1); \ \xi_2, \ \eta_2, \ u(\xi_2, \ \eta_2); \ \dots, \ \xi_{N_1}, \ \eta_{N_1}, \ u(\xi_{N_1}, \ \eta_{N_1}).$$

Numerical Examples

Numerical Example 1. Let us look at the solution to the Dirichlet

problem for the ellipse

$$S: y_1 = \cos \alpha, \quad y_2 = 0.80 \sin \alpha,$$

under the boundary condition

$$f(y) = \frac{\xi}{\xi^2 + \eta^2} , \quad y(\xi, \eta) \in S.$$

The auxiliary points $x^{(k)} \in B_i$ were taken on the confocal ellipse

$$S_1$$
: $x_1^{(k)} = 0.75 \cos \alpha_k$, $x_2^{(k)} = 0.60 \sin \alpha_k$ $(k = 1, 2, ..., 24)$.

Such values for the semiaxes of the auxiliary ellipse of the program are selected in the case when as the initial data in the cell 0622 we find the number 0.20.

The coordinates of the auxiliary points

$$x_1^{(1)}, x_2^{(1)}; x_1^{(2)}, x_2^{(2)}, \ldots, x_1^{(24)}, x_2^{(24)}$$

on the ellipse S_1 are given in Table 8.

In this case, it was found that the orthonormalization was checked with $\frac{102}{100}$ an accuracy exceeding 10^{-4} , i.e., the diagonal terms within an accuracy of 10^{-4} were equal to unity and the nondiagonal terms within this same accuracy were equal to zero.

Since as the initial data we were not required to print out the values for the normal derivative of the unknown function $\varphi(\alpha_j)$ (in the first address of cell 0625 we have 0000), the program does not print them out.

A precise solution to this problem has the form

$$u(\xi, \eta) = \frac{\xi}{\xi^2 + \eta^2}, \quad (\xi, \eta) \in B_a,$$

and, consequently, it was possible to compare the approximate solution with the exact solution and compute the error ϵ .

Table 9 gives the coordinates of the points outside the ellipse, the approximate solutions to them and the deviation of the approximate solution from the exact one.

<u>Numerical Example 2.</u> As another numerical example, let us look at the solution to the Dirichlet problem for the ellipse,

$$S: u_1 = \cos \alpha$$
, $u_0 = 0.50 \sin \alpha$.

under the boundary condition

$$f(y) = -\frac{2 \xi \eta}{(\xi^2 + \eta^2)^2}, \quad y(\xi, \eta) \in S.$$

The auxiliary points $x^{(k)} \in B_i$ were taken on the conformal ellipse

$$S_1: x_1^{(k)} = 0.80 \cos \alpha_k, \quad x_2^{(k)} = 0.50 \sin \alpha_k \quad (k = 1, 2, ..., 24).$$

The coordinates of the auxiliary points are given in Table 10.

In this case, the orthonormalization was also carried out with an accuracy exceeding 10^{-4} .

The exact solution to this problem has the form

$$u(\xi, \eta) = -\frac{2 \xi \eta}{(\xi^2 + \eta^2)^2}, \quad (\xi, \eta) \in B_a.$$

Table 11 gives the coordinates of the points outside the ellipse, the approximate solutions corresponding to them and the deviation of the approximate solution from the exact one. The distribution of points outside the ellipse, at which the values are computed for solution to the boundary value problem, for the first numerical example is given on Figure 4, and for the second example - on Figure 5.

TABLE 7

k	α_k	k	α_h	k	α_k
1 2 3 4 5 6 7 8	90° 270° 0° 180° 225° 45° 315° 135°	9 10 11 12 13 14 15	330° 150° 120° 300° 60° 240° 30° 210°	17 18 19 20 21 22 23 24	75° 255° 105° 285° 15° 195' 165° 345°

TABLE 8

k	$x_1^{(k)}$	$X_2^{(k)}$	k	$x_1^{(k)}$	$\chi_2^{(h)}$
1 2 3 4 5 6 7 8 9 10	-0.10971885.10-7 0.32915659.10 0.7500000 -0.75000000 -0.53033006 0.53033011 -0.53033009 0.64951907 -0.64951906 -0.37500001 0.37500003	0,6000000 -0,60000000 0,000000000 -0,17555016·10-7 -0,42426408 0,42426407 -0,42426404 0,42426406 -0,29999997 0,29999997 0,51961523 -0,51961522	13 14 15 16 17 18 19 20 21 22 23 24	0,37499999 -0,37499997 0,64951905 -0,64951904 0,19411427 -0,19411429 0,19411431 0,72444437 -0,72444437 0,72444438	0,51961524 -0,51961525 0,30000000 -0,30000001 0,57955549 -0,57955549 -0,57955549 0,15529142 -0,15529144 0,15529141 -0,15529139

TABLE 9

N_1	ξ _{N1} .	η _N ,	$u\left(\xi_{N_1}, \ \eta_{N_1}\right)$	ε
1	-0_80	1.00	0_48780488	-0.1.10-7
2	0.80	1.20	0.38461536	0.2.10-7
$\frac{2}{3}$	0.80	1.40	0,30769227	0.3-10-7
4	0.80	1,60	0.24999996	0.4 10-7
5	0.80	1.80	0.20618553	0,3 10 7
6	0.80	2.00	0.17241376	0.3.10-7
7	0.80	2.40	0,12499997	0.3.10-7
8	0,80	2.60	0,10810808	0.2.10-7
9	0,90	1.10	0.44554454	0,1.10-7

TABLE 9 (con't)

10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31	0.90 0.90 0.90 0.90 0.90 0.90 1.20 1.20 1.20 1.20 1.20 1.20 1.20 1.2	1.60 2.10 2.60 3.10 3.60 4.60 5.60 1.20 2.80 3.60 4.40 5.20 6.80 1.30 2.33 3.30 3.30 5.30 6.30 7.30	0,26706228 0,17241376 0,11889033 0,86372339 · 10-1 0,65359456 · 10-1 0,40964933 · 10-1 0,27976357 · 10-1 0,41666664 0,22058820 0,12931032 0,53333312 · 10-1 0,57692283 · 10-1 0,42134813 · 10-1 0,25167768 · 10-1 0,25167768 · 10-1 0,3251264 · 10-1 0,25167768 · 10-1 0,3251264 · 10-1 0,25324693 · 10-1 0,62324693 · 10-1 0,62324693 · 10-1 0,34910089 · 10-1	0.3.10-7 0.3.10-7 0.2.10-7
	1,20	3,60	0,53333312.10	0.2.10-
	1.20	3,60	0.53333312.10-1	0.2.10
21	1,20	4.40	0.57692288 10-1	$0.2 \cdot 10^{-7}$
	1,20	5 _e 20	0,42134813.10-1	$0.2 \cdot 10^{-7}$
	1,20	€,00	0.32051264 10-1	$0.2 \cdot 10^{-7}$
	1,20	6.80	0.25167768·10 ⁻¹	$0.2 \cdot 10^{-7}$
	2,00	1,30		$0.3 \cdot 10^{-7}$
	2,00	2,30		0_3.10-7
	2,00	3,30	0,13431831	$0.2 \cdot 10^{-7}$
28		4.30	0,88928392.10-1	$0.2 \cdot 10^{-7}$
29		5,30	0,62324693 · 10-1	$0.2 \cdot 10^{-7}$
30	2,00	6,30	0.45777047 • 10-1	$0.2 \cdot 10^{-7}$
31	2,00	7 30	0.34910089-10-1	$0.2 \cdot 10^{-7}$
32	2,00	8,30	0.27438588 · 10-1	$0.2 \cdot 10^{-7}$
33	5,00	1,40	0.18545992	0.2.10-7
34	5,00	2,50	0 15999998	0.2.10-7
35	5,00	3,60	0,13171757	$0.2 \cdot 10^{-7}$
36	5,00	4,70	0,10617963	$0.2 \cdot 10^{-7}$
37	5,00	5,80	0.85266012.10-1	0.2.10-7
- 38	5,00	6 , 90	0.68861020 • 10-1	0.2.10 7
39	5,00	8,00	0.56179757 · 10-1	G_2-10-7
40	5,00	9,10	0.46377870 - 10-1	0.2.10-7
,		,	-	1

TABLE 10

/104

k	$x_1^{(k)}$	$X_2^{(k)}$	k	$x^{(h)}$	$\chi_2^{(k)}$
1 2 3 4 5 6 7 8 9 10 11 12	-0.11703344.10-7 0.35110033.10-7 0.5000000 -0.50568540 0.50568542 0.50568543 -0.50568543 0.69282034 -0.69282033 -0.4000001 0.40000003	0,40000000 -0,40000000 -0,00000000 -0,11703344·10-7 -0,28284272 0,28284271 -0,28284270 -0,19999998 0,19999999 0,34641015 -0,34641015	13 14 15 16 17 18 19 20 21 22 23 24	0,39999999 -0,39999997 0,69282032 -0,69282031 0,20705522 -0,20705524 0,20705527 0,77274066 -0,77274066 0,77274066 0,77274067	0,34641016 -0,34641017 0,200900000 -0,20000001 0,38637033 -0,38637032 -0,38637032 0,10352761 -0,10352760 -0,10352760

TABLE 11

N_1	ξ _N .	η_{N1}	$u (\xi_{N_1}, \eta_{N_1})$	ε		
1	0.10	0.85	-0,31638123	0,4.10-3		
2	0.10	0.90	-0.26741077	0 3 10-3		
2 3	0.10	0.95	-0.22799725	0.2.10-3		
4 5 6	0,10	1.00	-0,19593167	0.1.10-3		
5	0.10	1.05	-0.16958642	0.9.10-4		
6	0.10	1.10	<u></u> -0,14774571	0.6.10-4		
7	0.40	1.20	0,37494110	$0.2 \cdot 10^{-3}$		
8	0.40 0.40	1.40	-0.24916701	0.3.10-4		
9	0.40	1,60	-C.17299237	0.2.105		
10	0.40	1 80	-0.12455676	0-1-10-4		
11	0.40	2.00	$-9.92448923 \cdot 10^{-1}$	0.7.40-5		
12	0,40	2,20	-0.70395625 · 10-1	0.4.10-4		
13	0.50	0.85	-0.89872762	0.2.10-		
14	0.40 0.40 0.40 0.50 0.50	2,50	—0.59168693·10¬1	0,3.10-4		
15	1 0,50	3,00	-0.35060798 10-1	0,1.10-5		
16	0,50	3,50	-0.22399381-10-1	0.6-10-		
17	0.50	4.00	-0.15147633·10 ⁻¹	0.3.10-6		
18	0.50	4.50	-0.10707785·10-1	0.1-10-6		
19	0.70	0.80	-0.87710776	6.2.10-4		
20	0.70 0.70	0.90	-0,74554028	0.2.10-4		
21	0.70	1.50	-0,27969678	0.2 10-4		
22	9.70	1.70	-0.20831214	0.1·10-4		
23	0.70	1.90	-0.15822948	0,1.10-4		
24	0.70	2.10	-0.12244221	0.7.10-3		
25	1.00	0.80	-0.59488192	0.2.10-8		
26	1,00	1.10	-0.45043029	0,1.10-4		
27	1.00	1.30	-0.35929693	0.1.10-4		
28 29	1.00	2.30	-0.11626231	0.5.10-5		
30	1.00	2.40	-0.10503420	0.4.10-5		
31	1.00	2,50	$-0.86350308 \cdot 10^{-1}$	0.3.10-5		
32	1.50	0.80	-0.28736243	0.1.10-4		
33	1.50	3,00	$-0.71109321 \cdot 10^{-1} \\ -0.43685470 \cdot 10^{-1}$	0.2.10-5		
34	1.50 1.50	3.70 4.40	-0,43065470·10 · -0,28265522·10-1	0,9·10 ⁻⁶ 0,5·10 ⁻⁶		
35	1.50	5 10	-0.19157636·10-1	$0.3 \cdot 10^{-7}$		
36	1.50	5.10 5.80	$-0.13137030.10^{-1}$ $-0.13508267.10^{-1}$	$0.8 \cdot 10^{-7}$		
37	2.00	0.80	-0.14863768	$-0.5 \cdot 10^{-5}$		
38	2,00	0.90	-0.14505750 -0.15560525	$-0.3 \cdot 10^{-5}$		
39	2,00	1.00	-0,16000339	-0.3.10-5		
40	2,00	2,00	-0.12499848	0,2.10-5		
41	2.00	3,00	-0.71004589·10 ⁻¹	0,1.10-5		
42	2,00	4.00	-0.39999326.10-1	0.7.10-8		
43	2.00	5.00	-0.23780922 · 10-1	0,3.10-6		
-		- •		0 9		

INITIAL DATA FOR FIRST NUMERICAL EXAMPLE

Address	Command			Comments
0000 1 2 3 4	30 010 31 77 34 062	0622 00 00 2 0002 06	010 007 060 522 134	Initial data input card.

INITIAL DATA

Address		Command		d Comments
0622 2 3 4 5 6 7 0630 1 2	0 0 03 03 01 04 34	0000 0017 0020 0001 0001 0017	2000 8000 0050 0017 0020 0002 0001	$\begin{array}{c} (b-\overline{b}) \text{ is the difference bet. semiaxes S and S}_1. \\ 0005 \\ 0000 \\ 0000 \\ 0001 \\ 0001 \\ 0002 \\ 0002 \\ 0002 \\ 0002 \\ 0003 \\ 0004 \\ 0006 \\ 0006 \\ 0006 \\ 0007 \\ 0007 \\ 0008 \\ 0008 \\ 0008 \\ 0009 \\ $

NUMERICAL INFORMATION

Address	Numbers	Address	Numbers
0633 4 5 6 7 0640 1 2 3 4 5 6 7 0650 1 2 3 4 5 6 7 0660 1 2 3 4 5 6 7 0730 1 2 3 4 5 6 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	+ 0 + 8000 + 1 + 1000 + 0 + 8000 + 1 + 1200 + 0 + 8000 + 1 + 1600 + 0 + 8000 + 1 + 1600 + 1 + 1	0670 1 2 3 4 5 6 7 0700 1 2 3 4 5 6 7 0710 1 2 3 4 5 6 7 0720 1 2 3 4 0740 1 2 3 4 0750 1 2 3 4 0750 1 2	+ 1 + 4600 + 0 + 9000 + 1 + 1200 + 1 + 13600 + 1 + 1200 + 1 + 1200 + 1 + 1300 + 1 + 1200 + 1 + 1300 + 1 + 1300 + 1 + 2000 + 1 + 2000 + 1 + 2300 + 1 + 2000 + 1 + 3300 + 1 + 2000 + 1 + 5300 + 1 + 5000 + 1 + 6900 + 1 + 5000 + 1 + 5000

Address	Command		Comments
0000 1 2 3.	30 0100 31 77 0622	0622 0014 0007 0060 0002 0622 0134	Initial data input card.

INITIAL DATA

Address	Command		Command Comments		Comments
7 0630 1 2 3 4	0 + 1000 0 0 0000 0053 003 0017 0017 003 0020 0020 001 0001 0001 003 0017 0020 003 0017 0020 004 0002 0001 15 0001 0565	0011 0000 0001 0002 0001 0001 0002 0002	(b-b) is difference bet. semiaxes S and S ₁ . b is the semi-minor axis of basic ellipse S. N is length of prog. for computing boundary func. Values of norm. derivative of unknown func. N ₂ =53 ₍₈₎ . Beg. of program for computing boundary function.		

NUMERICAL DATA

Address	Numbers	Address	Numbers
0637 0640 1 2 3 4 5 5 6 7 0660 1 2 3 4 5 6 7	+ 0 + 1000 + 1 + 1400 + 1 + 1400 + 1 + 1400 + 1 + 1800 + 1 + 1800 + 1 + 1 + 1800 + 1 + 2000 + 5000	6 7 0650 1 2 3 4 2 3 4 5 6 7 0730 1 2 3 4	+ 1 + 1000 + 1 + 1050 + 1 + 1050 + 1 + 1100 + 1 + 1100 + 1 + 1100 + 1 + 1200 + 1 + 1300 + 1 + 1000 + 1 + 1000 + 1 + 1000 + 1 + 1000 + 1 + 1500 + 1 + 1500

NUMERICAL DATA (con't)

Address	Numbers	Address	Numbers
40670 1 2 3 4 5 6 7 70700 1 2 3 4 5 6 7 70710 1 2 3 4 5 6 7 0720 1	+ 0 + 8500 + 0 + 5000 + 1 + 2500 + 0 + 5000 + 1 + 3000 + 1 + 3500 + 0 + 5000 + 1 + 4000 + 0 + 5000 + 1 + 4000 + 0 + 5000 + 1 - 4500 + 0 + 7000 + 1 - 4500 + 1 - 4500 + 0 + 7000 + 1 - 1500 + 0 + 7000 + 1 + 1 + 1500 + 0 + 7000 + 1 + 1 + 1700 + 1 + 1900 + 1 + 1900 + 1 + 1900 + 1 + 1900 + 1 + 1000 + 1 + 1000 + 1 + 1000 + 1 + 1000 + 1 + 1000	5 6 7 0740 1 2 3 4 5 6 7 0750 1 2 3 4 5 6 7 0760 1 2 3	+ 1 + 1500 + 1 + 3000 + 1 + 1500 + 1 + 3700 + 1 + 1500 + 1 + 2000 + 1 + 2000

OPERATIONAL CODE FOR METHOD OF FUNCTIONAL EQUATIONS

Address	Command		Address	Command		······································
0000 1 2 3 4 5 6 7 0010 1 2 3 4 5 6 7	00 30 31 35 33 000 42 033 30 140 31 30 040 71 35 33 34 30 140 31 30 040 71 35 30 040 71 35 30 040 040 040 040 040 040 040	0014 0050 0006 2 2154 1211 1043 0342 0050 1044 0015 0001 0006 1044 0255 1406 0050	0020 1 2 3 4 5 6 7 0030 1 2 3 4 5 6 7	33 34 30 31 34 30 04 31 35 00 33 34 30 04	050 0041 0002 100 0001 100 0060 007 0044 0003 104 0340 0041 0004	0041 0024 0015 0004 0001 1043 0007 0474 0027 0255 0007 0340

Address	Command		Address	Comn	nand	
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§ 12. SOLUTION TO THE TWO-DIMENSIONAL EXTERNAL DIRICHLET PROBLEM BY THE METHOD OF GENERALIZED FOURIER SERIES

Computer Program

The computational process consists of the following steps:

- (1) Computation of uniformly distributed points on auxiliary ellipse;
- (2) Computation of scalar products;
- (3) Computation of coefficients of orthonormalization;
- (4) Construction of orthonormalized systems;
- (5) Checking accuracy of this orthonormalization;
- (6) Computation of Fourier coefficients B_{i} ;
- (7) Computation of coefficients C_{i} .
- (8) Finding harmonic function outside ellipse s.

Let us take two confocal ellipses:

the basic ellipse s: $s: x_1 = a\cos\varphi$, $x_2 = b\sin\varphi$ and the auxiliary ellipse

$$s_1: x_1^{(i)} = \bar{a}\cos\alpha_i, \quad x_2^{(i)} = \bar{b}\sin\alpha_i \quad (1);$$

$$M(x_1^{(i)}, x_2^{(i)}) \in s_1, i=1, 2, ..., 24.$$

The points $M(x_1^{(i)}, x_2^{(i)})$ are distributed on the auxiliary ellipse uniformly with an interval of $\pi/12$; the values of the arguments α_i (i=1, 2, ..., 24) are given in Table 7.

The points $M(x_1^{(i)}, x_2^{(i)})$ are computed and printed out in the following sequence $x_1^{(i)}, x_2^{(i)}; x_1^{(i)}, x_2^{(2)}; ...; x_1^{(24)}, x_2^{(24)}$. The scalar products

$$(\varphi_{i}(y), \varphi_{k}(y)) = \int_{S_{1}} \varphi_{i} \varphi_{k} dS_{1},$$

$$\varphi_{i} = \frac{1}{2} \ln \left[(x_{1} - x_{1}^{(i)})^{2} + (x_{2} - x_{2}^{(i)})^{2} \right] \quad i = 1, 2, ..., 24; \quad k = 1, 2, ..., i,$$

$$(2)$$

are computed, as are the coefficients of orthonormalization \mathbf{A}_{ik} by the following formulas:

$$A_{k,k} = \frac{1}{\|g_{k}\|}, \quad k = 1, 2, ..., 24$$
 (3₁)

$$A_{k,k-1} = A_k \sum_{j=1}^{i} \alpha_{k,k-j} A_{k-j,k-i}, \qquad k=2,3,4,\ldots, 24 \\ i=1,2,3,\ldots, k-1$$
 (3₂)

where

$$\|g_{k}\| = \sqrt{\int_{s} \left[\varphi_{k} + \sum_{j=1}^{k-1} B_{k, j} \varphi_{j}\right]^{2} ds_{y}} =$$

$$= \sqrt{\sum_{j=0}^{k-1} B_{k, k-j}^2 \int_{s}^{\varphi_{k-j}^2 ds_y} + 2 \sum_{j=0}^{k-2} B_{h, h-j} \sum_{i=j+1}^{k-1} B_{h, i} \int_{s}^{\varphi_{k-j}} \varphi_{i} ds_y}, \qquad (3_3)$$

$$= \sqrt{\sum_{j=0}^{k-1} B_{k, k-j}^2 \int_{s}^{\varphi_{k-j}^2 ds_y} + 2 \sum_{j=0}^{k-2} B_{h, h-j} \sum_{i=j+1}^{k-1} B_{h, i} \int_{s}^{\varphi_{k-j}} \varphi_{i} ds_y}, \qquad (3_3)$$

$$= \sqrt{\sum_{j=0}^{k-1} B_{k, k-j}^2 \int_{s}^{\varphi_{k-j}^2 ds_y} + 2 \sum_{j=0}^{k-2} B_{h, h-j} \sum_{i=j+1}^{k-1} B_{h, i} \int_{s}^{\varphi_{k-j}} \varphi_{i} ds_y}, \qquad (3_3)$$

$$\alpha_{h, h-j} = -\sum_{i=1}^{k-j} A_{h-j, i} (\varphi_{h}(y) \varphi_{i}(y)), \quad k=2, 3, 4, \dots, 24 \\ j=k-1, k-2, \dots, 1$$
 (3₄)

$$B_{h,j} = \sum_{i=1}^{k-j} \alpha_{h,h-i} A_{h-i,j}, \qquad k=2, 3, 4, ..., 24$$

$$j=k-1, k-2,...,1$$
(3₅)

After this we construct the orthonormalized system

$$\psi_{i}(\alpha_{j}) = \sum_{k=1}^{i} A_{i,k} \varphi_{k}(\alpha_{j}) \qquad \alpha_{j} = (j-1) \frac{2\pi}{250}$$

$$i = 1, 2, ..., 24$$

$$j = 1, 2, ..., 250$$
(4)

and the orthonormalization is checked within an accuracy of 10^{-4}

$$1 - \int_{0}^{2\pi} \psi_{i} \psi_{k} ds = 1 - \frac{2\pi}{250} \sum_{j=1}^{250} \psi_{i}(\alpha_{j}) \psi_{k}(\alpha_{j}) < 10^{-k} \quad \text{when} \quad i = k,$$

$$\int_{0}^{2\pi} \psi_{i} \psi_{k} ds = \frac{2\pi}{250} \sum_{j=1}^{250} \psi_{i}(\alpha_{j}) \psi_{k}(\alpha_{j}) < 10^{-k} \quad \text{when} \quad i \neq k.$$
(5)

Then we compute the Fourier coefficients

$$B_{l} = \int_{s_{1}} f(\alpha) \psi_{l} ds_{1} = \frac{2\pi}{250} \sum_{j=1}^{250} f(s_{j}) \psi_{l}(\alpha_{j}), \quad i = 1, 2, ..., 24,$$

$$\alpha_{j} = (j-1) \frac{2\pi}{250},$$
(6)

where $f(\alpha)$ is the boundary condition and ψ , are the orthonormalized functions.

After this we compute the coefficients

$$C_{i} = \sum_{b=i}^{24} B_{b} A_{i,b}, \qquad i=1, 2, ..., 24,$$
 (7)

where $\mathbb{A}_{i,k}$ are the coefficients of orthonormalization.

Outside the ellipse we seek the harmonic function $u(\xi,\,\eta)$ in the following manner:

$$u(M) = \sum_{i=1}^{24} C_i \varphi_i(M), \tag{8}$$

where

$$\varphi_i(M) = \frac{1}{2} \ln \left[(x_1^{(i)} - \xi)^2 + (x_2^{(i)} - \eta)^2 \right], \quad M(\xi, \eta) \in G_e.$$

The program consists of the following basic parts:

- (1) Control program;
- (2) A program for processing initial and numerical data;

/117

- (3) First part of fundamental program;
- (4) Second part of fundamental program;
- (5) Finding the harmonic function outside ellipse s.

The program operates in the following sequence: the entire program is fed into the machine. If the read-in is correct, the control program recards on the zero magnetic drum the first part of the program in cells 0000 - 1114, and the second part of the program in cells 1115 - 1331, automatically reads in the initial data input card, which in turn reads in

the initial data in binary notation, converts b and b - \bar{b} from the decimal notation system into the binary, and the control transmits the program for processing the numerical data by the command 0011.

The program for interpreting the initial and numerical data transfers b to cell 0051, and b - \bar{b} to cell 0043, and the program for computing the boundary function $f(\alpha)$ is transferred from cell 0626 - 0626 + (n-1) (where n is the length of the program in the octal notation system) to the zero magnetic drum is cells 1332 - 1332 + (n-1). (In compiling the program for $f(\alpha)$, the usable working cells must certainly be allowed for in the length of the program.) After this the program for processing the initial and numerical data of the coordinates of these points is converted from the decimal notation system to the binary and transferred to the zero magnetic drum from the cell 2462 - $[1420 - n \cdot 2^{-1}]_8$ (if such a number of points exists).

After completion of the operation, the program for processing the numerical data transmits control to the control program by the command 0225, after which the first part of the basic program is read out from the drum.

The first part of the program computes the semiaxes of the auxiliary ellipse $\bar{b}=b-(b-\bar{b})$ and $a=\bar{b}/b$, and computes and prints out the auxiliary points $x_1^{(1)}$, $x_2^{(1)}$; $x_1^{(2)}$, $x_2^{(2)}$; ...; $x_1^{(24)}$, $x_2^{(24)}$. The scalar products $\int_{s_1} \varphi_k \, ds_1$, $i=1,\ldots,24$; $k=1,2,\ldots,i$ are computed from the standard program. We must mention that only the left-hand side of the matrix is computed.

$$\int_{S_{1}} \varphi_{1} \varphi_{1} ds_{1},$$

$$\int_{S_{1}} \varphi_{2} \varphi_{1} ds_{1}, \quad \int_{S_{1}} \varphi_{2} \varphi_{2} ds,$$

$$\vdots \qquad \vdots \qquad \vdots$$

$$\int_{S_{1}} \varphi_{24} \varphi_{1} ds_{1}, \quad \int_{S_{1}} \varphi_{24} \varphi_{2} ds_{1}, \dots, \int_{S_{1}} \varphi_{24} \varphi_{24} ds_{1}.$$

Then the coefficients of orthonormalization $A_{i,k}$ are computed from Formulas (3_1) and (3_2) . In computing the coefficients of orthonormalization, there may be a stop from the command 0343 — if the machine is in good working order, this means that a certain coefficient $A_{k,k}$ or $A_{k,k-1}$ is found to be negative, and in such case it is recommended to change the dimensions of the /118 auxiliary boundary s_1 .

Then the orthonormalized system is computed from Formula (4) and the orthonormalization is verified within an accuracy of 10^{-4} from Formula (5). If the orthonormalization is not carried out within the required accuracy, then the following is printed out

$$1 - \frac{2\pi}{250} \sum_{j=1}^{.250} \varphi_i^2(\alpha_j) > 10^{-4}, \quad i = 1, 2, ..., 24, \quad \alpha_j = (j-1) \frac{2\pi}{250}$$

and the conditional unit, i.e., the diagonal term, does not reach the required accuracy or

 $\begin{array}{ccc}
2\pi & \sum_{j=1}^{250} \varphi_{l}(\alpha_{j}) \varphi_{h}(\alpha_{j}) > 10^{-4}
\end{array}$

is printed out when $i \neq k$, i. e. the nondiagonal term does not reach the required accuracy.

If the number of unprinted diagonal or nondiagonal terms is very high, then the problem must be cleared and the difference b - \overline{b} reduced.

After completion of this check, the first part of the program using the command 1174 transmits control to the control program and the second part of the program is read out from the magnetic drum.

The second part of the program copies the program for computing the boundary function $f(\alpha)$ from the magnetic drum, computes the boundary

values of $\alpha_j = (j-1) \frac{2\pi}{250}$, $j=1, 2, \ldots, 250$, the Fourier coefficients B_i from Formula (6), the coefficients C_i from Formula (7) and prints out the coefficients C_1 , C_2 , ..., C_{24} .

After this, the second program seeks the harmonic function $u(\xi, \eta)$ according to Formula (8) outside the ellipse s, and prints out these points and the solutions corrdesponding to them in the following sequence: ξ_1, η_1 , $u(\xi_1, \eta_1); \xi_2, \eta_2, u(\xi_2, \eta_2); \dots; \xi_n, \eta_n u(\xi_n, \eta_n)$, where n is the number of these points.

Operation of Console

The entire punchcard deck is assembled in the following order:

- (1) Basic program input card;
- (2) Blank punchcard;
- (3) Basic program;
- (4) Blank punchcard;
- (5) Initial data input card;
- (6) Blank punchcard;
- (7) Initial data;
- (8) Blank punchcard;
- (9) Initial data;
- (10) Blank punchcard;
- (11) Numerical data;
- (12) Blank punchcard;
- (13) Numerical data;

TABLE OF CONTROL STOPS

Stop	Contents of instruction storage	Reason for stop	Action
0004 6204 0023 0032	33 00°7 — — 33 0°02 — — 33 0°03 — — 33 0°04 — —	Incorrect program read-in. Incorrect input of numerical data.	Repeat read-in.
0037	33 0005 — —	Incorrect access to zero magne- tic drum.	Repeat access to drum with key start.
0150 0013 0223 1103 1125 1133 0301 0262	33 0006 — — 33 0002 — — 33 0010 — — 33 0011 — — 33 0012 — — 33 0013 — — 33 0016 — —	Incorrect access to first magne-	Stait.
0351 0433	33 0020 — —	tic drum.	
0455	33 0021 — — 33 0002 — —	End of computation. SP-0002 (block transfer 10→2).	·
0153 0370	33 0013 — — 33 0010 — —	SP-0013 (computation of 1m x). SP-0010 (square root extraction).	
1155	33 0014 — —	Nondiagonal term does not reach	Continue computa-
65	33 0015 — —	required accuracy. Diagonal term does not reach required accuracy.	tion with key start.

For stop 33 0007 execute command 34 - - 0176 from console.

It may happen that when the machine is in good working condition it will often stop on commands 1155 and 1165 and print out the difference

$$1 - \sum_{j=1}^{250} \psi_l(\alpha_j) \psi_k(\alpha_j) > 10^{-4} \text{ when } i = k$$

$$i = 1, 2, ..., 24$$

or

$$\sum_{j=1}^{250} \psi_{l}(\alpha_{j}) \psi_{k}(\alpha_{j}) > 10^{-4} \quad \text{when} \quad i \neq k.$$

In this case, the problem must be cleared and the difference b - \bar{b} reduced in the initial data.

The results are printed out in the following sequence: the auxiliary points $\mathbf{x}_1^{(1)}$, $\mathbf{x}_2^{(2)}$; $\mathbf{x}_1^{(2)}$, $\mathbf{x}_2^{(2)}$; ...; $\mathbf{x}_1^{(24)}$, $\mathbf{x}_2^{(24)}$ are printed out, following $\mathbf{x}^{(24)}$, $\mathbf{x}_3^{(24)}$ there will be a bit space and the coefficients \mathbf{C}_1 , \mathbf{C}_2 , ..., \mathbf{C}_{24} are printed out; without the space the coordinates of only the first designated point are printed out and the unknown solution corresponding to it, but the coordinates of the other points and the solutions corresponding to them are printed out with a space. This happens when the accuracy of orthonormalization is better than 10^{-4} .

If any term, diagonal or nondiagonal, does not reach the required accuracy, then following the coefficients C_i , $i=1,\ldots,24$ there will be printed out

$$1 - \sum_{j=1}^{250} \psi_i(\alpha_j) \psi_k(\alpha_j) > 10^{-4} \text{ when } i = k$$

$$i = 1, 2, ..., i$$

or

$$\sum_{j=1}^{250} \psi_i(\alpha_j) \psi_k(\alpha_j) > 10^{-4} \text{ when } i \neq k$$

with a space. After these numbers (not reaching the accuracy), the coordinates of the designated points (ξ_i , η_i) and the solutions corresponding to them are printed out.

/120

TABLE 12. MEMORY CONFIGURATION

Designation of data blocks	Beginning	End	Control sum
Basic program input card. Control program.	0001 0006	0005 0057	0005, 0050
Program for processing initial and numerical data. First program. Second program. Initial data. Numerical data.	0060 0060 0220 0622 0623	0346 1174 0434 1332 3665	0044 0047 0013, 0014 0010, 0011

TABLE	13.	MEMORY	CONFIGURATION	V

	Assig	nment in	internal	memory	Assignm		num-	
Designation of blocks	Durin	g read-in	During tion	opera-	magnet	ic drum		
	Beg.	End	Beg.	End	Beg.	End	Drum	_
Basic program input	0001	0005						
Control program Program for processing initial & numerical	0006	0057						
data	0060	0345						
First part of basic		Í						
program	0346	1463	0060	1174	0000	1114	0	
Working cells	2442	2471	2442	2471]		
	1766	2357	1766	2357				
	2500	3071	2500	3071				
Results			3212	3665		i ·		
			3716	3775		100		
Second part of prog.	1464	1700	0220	0434	1115	1331	0	
Working cells	0500	0511	0500	0511	1			
	1767	2360	1767	0715				
Results_	0600	0.00	3666	3715		·		
b - b	0622	0622	0043	0043		-		
b	0623	0623	0051	0051	7.000	1222		/101
Prog. for computing	0626	0626	0626	0626	1332	1332		<u>/121</u>
boundary function		+(n-1)	1766	+(n-1)	0000	+(n-1)	,	
Orthonormalized func.		٠,	1766	2357	0000	23557	1	
Numerical data, i.e., designated points	0623	3662-n	0626	3665-n	2462	11521-n		_

Set Up of Initial Data

The input card for the initial data has the following form:

30	0100		n-1
31		0622	0014
30	0100		n-1
31		0622	0013
35	0014	0013	0010
33	0022		
34			0001
77			0060
	0622	0002	0622
34			0134
00			
00			

where n is the length of the program for computing the boundary function $f(\alpha)$.

The initial information requires recording the following original data in the cells 0622 - 0625: 0622 — the difference $b - \bar{b}$ in the decimal notation system, where b and \bar{b} , are the semi-minor axes of the confocal ellipses s and s_1 respectively. 0623 - n for the third address — length of the program for computing the boundary function $f(\alpha)$ in the octal notation system. In the second address of cell 0625 — the number of designated points N is written in the octal notation system. The number of designated points must not exceed $[1420-n/2]_8$, if n is even; $[1420-(n-1)/2]_8$, if n is odd.

The program for computing the boundary function must begin from cell 0626. The length of the program for computing the boundary function $f(\alpha)$ must not exceed $600\big|_{10}$ or $1130\big|_{8}$.

If in computing $f(\alpha)$ the values of cos x and sin x are necessary, then they can be taken from cell 0020 and 0021. In compiling the programs the working cells used must certainly be taken into account in the length of the program for $f(\alpha)$.

If cos x and sin x are not necessary, cells 0020 and 0021 may be used as working cells. The numerical data must follow directly after the program for the boundary function $f(\alpha)$; this is $\xi_1, \eta_1; \xi_2, \eta_2; \dots; \xi_n, \eta_n$.

TABLE 14			
Designation of the working	Assignment in internal memory		
block	Beginning	End	
A B C D	0006 0060 6060 0400	0057 0346 0377 0540	
A B C D E F G H I J K	0541 0612 1030 1122 0200	0611 1027 - 1121 1171 0314	
J K	0315 0343	0343 0433	

FLOW DIAGRAM

Overall Flow Diagram

- A Control program block.
- B Block for processing initial and numerical data.
- C Standard program block.
- Block for computing auxiliary points on confocal ellipse according to Formula (1).
- E Block for computing scalar products according to Formula (2).
- F Block for computing coefficients of orthonormalization according to Formulas (3_1) and (3_2) .
- G Block for computing orthonormalized functions according to Formula (4).
- H Block for checking accuracy of orthonormalization.
- I Block for computing Fourier coefficients according to Formula (5).

- J Block for computing coefficients C_i according to Formula (6).
- K Block for finding unknown function outside ellipse according to Formula (7).

Control Program Block

- A 1 Record first part of basic program on zero magnetic drum.
- A 2 Record second part of basic program on zero magnetic drum.
- A 3 Read in initial data input card.
- A 4 Read in initial data.
- A 5 Read out first part of basic program from zero magnetic drum.
- A 6 Read out second part of basic program from zero magnetic drum.

Block for Processing Initial and Numerical Data

/123

- B 1 Standard program for converting array of numbers from decimal ${\tt notation}$ system to binary.
- B 2 Transfer b and b $-\overline{b}$ in cells 0051 and 0043.
- B 3 Record program for computing boundary function on zero magnetic drum.
- B 4 Transfer numerical data, i. e., go to B 1 and record on zero magnetic drum.
- B 5 Go to A 5.

Standard Program Block

- C 1 Standard program for computing sine and cosine.
- C 2 Standard program for computing natural logarithm.
- C 3 Standard program for converting numbers from binary notation system to decimal with floating point.
- C 4 Standard program for computing specified integral by Simpson's method with automatic calling sequence.
- C 5 Standard program for square root extraction.

Block for Computing Auxiliary Points on Confocal Ellipse

- D 1 Compute \overline{a} and \overline{b} and transfer in cells 0050 and 0052.
- D 2 Clear counter for i.
- D 3 Convert from degree units to radians.
- D 4 Readdress i.
- D 5 Check if all degree units have been converted into radians; if yes go to D 6; if no go to D 3.
- D 6 Clear counter for i.
- D 7 Transfer argument in cell 0001.
- D 8 Go to C 1.
- D 9 Compute $x_1^{(i)}$, $x_2^{(i)}$.
 D 10 Transfer $x_1^{(i)}$, $x_2^{(i)}$ in constant cells for storage.
- D 11 Clear counter for j.
- D 12 Transfer argument to cell 0001.
- D 13 Go to C 3.
- D 14 Print out $j-x_1^{(i)}$, $x_2^{(i)}$.
- D 15 Readdress j.
- D 16 Check if both $x_1^{(i)}$, $x_2^{(i)}$ have been printed; if yes go to D 17; if no go to D 1.
- D 17 Readdress i.
- D 18 Retrieve j.
- D 19 Check if all $x_1^{(i)}$, $x_2^{(i)}$ have been computed; if yes go to E 1; if no go to D 7.

Block for Computing Scalar Products

/124

- E 1 Transfer 1 1 A for n.
- E 2 Transfer 1 1 A for i.
- E 3 Transfer 1 1 A for j.
- E 4 Readdress for n.
- E 5 Go to C 4.
- E 6 Clear output for computation by integral formula.

- E 7 Transfer $x_1^{(i)}$, $x_2^{(i)}$ in working cells.
- E 8 Go to C 1.
- E 9 Compute $(x_1-x_1^{(i)})^2+(x_2-x_2^{(i)})^2$.
- E 10 Transfer contents of 0001 to working cell.
- E 11 Transfer argument 0001.
- E 12 Go to C 2.
- E 13 Compute φ_i .
- E 14 Transfer result for storage.
- E 15 Readdress for obtaining $x_1^{(i)}$, $x_2^{(i)}$.
- E 16 Retrieve argument for using standard program C 4.
- E 17 Go to E 8.
- E 18 Output for computing under integral formula.
- E 19 Multiply $\varphi_i \varphi_k$.
- E 20 Output for standard program C 4.
- E 21 Transfer result of integral computation for storage.
- E 22 Readdress for j.
- E 23 Check if all j have been computed; if yes go to E 3; if no go to C 4.
- E 24 Readdress for i.
- E 25 Check if all i have been computed; if yes go to E 25; if no go to E 3.
- E 26 Go to F 1.

Block for Computing Coefficients of Orthonormalization

- F 1 Transfer (φ_1, φ_1) to cell 0001.
- F 2 Refer to C 5.
- F 3 Compute $A_{11} = \frac{1}{\sqrt{(\varphi_1, \varphi_1)}}$.
- F 4 Transfer constants (00 0002 000 0000) to k-counter.
- F 5 Retrieve variable commands and set up constants for shaping.
- F 6 Clear counter for j.
- F 7 Shape commands for computing product $A_{k-j,i}$ (ω_h , ω_i).

- F 8 Compute product $A_{k-i,i}(\omega_k \omega_l)$.
- F 9 Compute Formula (3_h) .
- ${\tt F}$ 10 Check if all terms of Formula (3 $_4$) have been computed; if yes go to F 11, if no go to F 14.
- F 11 Transfer value $\alpha_{k,k-i}$ to storage.

/125

- F 12 Readdress variable commands and constants.
- F 13 Check if all $\alpha_{k,k-j}$ have been computed; if yes go to F 15; if no go to F 5.
- F 14 Set up shaping constants for computing next term and go to F 7.
- F 15 Set up constants for shaping.
- F 16 Clear counter for j.
- F 17 Shape commands for computing product $\alpha_{k,k-i}$, $A_{k-i,j}$.
- F 18 Compute product $\alpha_{k,k-i}$, $A_{k-i,j}$.
- F 19 Compute Formula (3_5) .
- F 20 Check if all terms $B_{k,j}$ have been computed; if yes go to F 21; if no go to F 24.
- F 21 Transfer values $B_{k,j}$ to storage.
- F 22 Readdress variable commands and constants.
- F 23 Check if all $A_{k,j}$ have been computed; if yes go to F 25; if no go to F 17.
- F 24 Set up shaping constants for computing next term and go to F 17.
- F 25 Set up constants for shaping.
- F 26 Shape commands for computing the formula

$$\sum_{j=0}^{k-1} B_{k, k-j} \int_{s} \omega_{k-j}^{2} ds_{y}.$$
 (3₆)

F 27 Compute product

$$B_{k,h-j}\int\limits_{s}\omega_{k-j}^{2}\,ds_{y}.$$

F 28 Compute Formula (3_6) .

- F 29 Check if all terms of Formula (3₆) have been computed; if yes go to F 31; if no go to F 30.
- F 30 Readdress variable commands for computing next term and go to F 27.
- F 31 Shape commands for computation using the formula

$$2\sum_{j=0}^{k-2} B_{k, k-j} \sum_{i=j+1}^{k-1} B_{k, i} \int_{s} \omega_{k-j} \omega_{i} ds_{y}.$$
 (3₇)

F 32 Compute product

$$B_{k, k-j} B_{k, i} \int_{s} \omega_{k-j} \omega_{i} ds_{y}.$$

- F 33 Compute Formula (3_7) .
- F 34 Check if all terms of Formula (37) have been computed; if yes go to $\frac{126}{5}$ F 36; if no go to F 35.
- F 35 Readdress variable commands for computing next term and go to \mathbb{F} 32.
- F 36 Compute radicand.
- F 37 Refer to C 5.
- F 38 Shape commands for computing Formula (1).
- F 39 Compute Formula (1).
- F 40 Set up constants for shaping.
- F 41 Shape commands for computing Formula (2).
- F 42 Transfer constants (00 0001 000 000) in i-counters.
- F 43 Compute nondiagonal coefficient of given row by Formula (2).
- F 44 Check if all nondiagonal coefficients of given row have been computed; if yes go to F 46; if no go to F 45.
- F 45 Readdress commands for computing next nondiagonal coefficient and go to F 43.
- F 46 Check if all coefficients A have been computed; if yes go to G 1; if no go to F 5.

Block for Computing Orthonormalized Functions

- G 1 Transfer some constants to working cells and clear counter for 1.
- G 2 Retrieve some commands and clear counter for k.
- G 3 Compute orthonormalized functions.
- G 4 Check if all orthonormalized functions have been computed for k; if yes go to G 5; if no go to G 2.
- G 5 Copy orthonormalized functions for k from operating memory on first magnetic drum.
- G 6 Readdress some commands for i.
- G 7 Check if all orthonormalized functions for k have been computed; if yes go to H 1; if no go to G 2.

Block for Checking Accuracy of Orthonormalization

- H 1 Transfer some commands in working cells.
- H 2 Clear counter for i.
- H 3 Transfer variable command to working cell.
- H 4 Clear counter for k.
- H 5 Read out orthonormalized coefficients for k from first magnetic drum.
- H 6 Retrieve variable command.
- H 7 Read out orthonormalized coefficients from first magnetic drum.
- H 8 Clear counter for j.
- H 9 Compute $\sum_{j=1}^{250} \varphi_{kj} \varphi_{ij}$, i=1, 2, ..., 24; k=1, 2, ..., i.
- H 10 Readdress for j.
- H 11 Check if cycle for j is completed; if yes go to 10; if not go to 7. /127
- H 12 Check accuracy of orthonormalization; has accuracy been reached; if yes go to 7; if no go to 11.
- H 13 Print out terms that have not reached the accuracy.
- ${\tt H}$ 14 Check if the cycle for k is completed; if yes go to 15; if no go to 7.

Block for Computing Fourier Coefficients from Formula (5)

I 1 Read out program for computing boundary function $f(\alpha)$ from zero

magnetic drum.

- I 2 Transfer argument in cell 0001 and go to C 1.
- I 3 Check if all $f(\alpha_j)$, $j=1,\ldots,250$, $\alpha_j=(j-1)-\frac{2\pi}{250}$, have been computed; if yes go to I 4; if no go to I 2.
- I 4 Read out orthonormalized coefficients from drum.
- I 5 Clear counter for k.
- I 6 Compute Fourier coefficients

$$B_k = \sum_{j=1}^{250} f(\alpha_j) \, \psi_{kj}, \quad k = 1, 2, \dots 24.$$

- I 7 Check if cycle for k is completed; if yes go to J 1; if no go to I 6.
- I 8 Clear counter for i.
- I 9 Clear working cell for variable command.
- I 10 Clear counter for k.
- I 11 Clear working cell for storage of sum.

I 12 Compute
$$C_l = \sum_{k=i}^{24} B_k A_{l,k}$$
.

- I 13 Check if cycle for k is finished; if yes go to I 14, if no go to I 12.
- I 14 Transfer C, for storage; go to C 3 and print out.
- I 15 Readdress variable command of retrieval and readdress for i.
- I 16 Check if cycle for i is finished; if yes go to I 17; if no go to I 9.
- I 17 Transfer designated points from magnetic drum.
- I 18 Clear counter for n.
- I 19 Transfer designated points in working cells.
- I 20 Clear counter for i.
- I 21 Has $u(\xi_n, \eta_n) = \sum_{i=1}^{24} C_i \omega_i$ been computed?
- I 22 Check if cycle for i is finished; if yes go to I 23; if no go to I 2.

- I 23 Print out $u(\xi_n, \eta_n)$.
- I 24 Readdress for n.
- I 25 Retrieve some commands for i.
- I 26 Check if cycle for n is finished; if yes go to I 27; if no go to I 19.
- I 27 Check if all 2N designated points have been computed; if yes go to I 27; if no go to I 19.
- I 28 Retrieve some commands and go to readdress I 17.
- I 29 Check if all designated points have been called; if yes go to I 30; if no go to I 18.
- I 30 Stop.

Control Example 1

Let us look at the following external Dirichlet boundary problem for the ellipse s:

$$x_1 = \cos \varphi$$
, $x_2 = 0.8 \sin \varphi$

under the boundary condition

$$u(\alpha) = \frac{x_1}{x_1^2 + x_2^2}, \quad 0 < \alpha < 2\pi$$

and seek the harmonic function outside the ellipse s.

In cell 0623 we transfer the value of the semi-minor axis b = 0.8. In cell 0622 we read-in the number b - \overline{b} = 0.2. The machine automatically selects the following values of the semiaxes for the auxiliary ellipse s₁:

$$x_1^{(i)} = 0.75 \cos \alpha_i$$
, $x_2^{(i)} = 0.6 \sin \alpha_i$, $i = 1, 2, ... 24$.

In cell 0624 according to the third address, N is the length of the program for computing the boundary function $f(\alpha)$. 0625 according to the second address is the number of designated points - n (i. e. $\xi_1, \eta_1; \xi_2, \eta_2; ...; \xi_n, \eta_n$) in the octal notation system. In our case

$$N = 40 \Big|_{10} = 50 \Big|_{8}$$

The approximate values for solution to this problem must be computed at the designated points in the region $G_{\rm e}$ outside the ellipse s. The values of the designated points are read in from cell 0623.

The precise solution to the problem has the form

$$u(\xi, \eta) = \frac{\xi}{\xi^2 + \eta^2} \qquad (\xi, \eta) \in G_e.$$

Below we derive the initial and numerical data.

/129

Address		Commar	nds	Comments
1 2 3 4 5 6 7 0010 1 2 3 4 4 0622 3 + +	31 30 31 35 33 34 77 00 34 00 00	100 100 0622 014 0013 022 622 0002 + 2000 + 8000	0010 0014 0010 0013 0010 0001 0060 0622 0134	Initial data input card. $b - \overline{b}$ is difference between semiaxes.
3 + 5 6 7 0630 1 2	03 00 03 00 01 00	+ 8000 0050 0020 0021 0002 0001 0002 0001 0001	0000 0005 0001 0002 0001 0001 0272	b is semi-minor axis of basic ellipse. n is length of program for computing boundary func. The number of designated points in octal notation system.

NUMERICAL DATA

Address	Numbers	Address	Numbers	
0623 4 5 6 7 0630 1 2 3 4 5 6 7 0640 1 2 3 4 5 6 7 0650 1 2 3 4 5 6 7 0720 1 2 3 4 5 6 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	+ 0 + 8000 + 1 + 1000 + 0 + 8000 + 1 + 1400 + 0 + 8000 + 1 + 1600 + 0 + 8000 + 1 + 1800 + 0 + 8000 + 1 + 2000 + 0 + 8000 + 1 + 2000 + 0 + 8000 + 1 + 2400 + 0 + 8000 + 1 + 2600 + 1 + 2600 + 1 + 2600 + 1 + 1100 + 0 + 9000 + 1 + 1 1600 + 0 + 9000 + 1 + 1 1600 + 0 + 9000 + 1 + 1 1600 + 0 + 9000 + 1 1 + 2600 + 1 1 + 3100 + 0 + 9000 + 1 1 + 3600 + 1 1 + 3100 + 0 + 9000 + 1 1 + 3600 + 1 1 + 2000 + 1 1 + 3600 + 1 1 + 2000 + 1 1 + 2000	0660 1 2 3 4 5 6 7 0670 1 2 3 4 5 6 7 0700 1 2 3 4 5 6 7 0710 1 2 3 4 0730 1 2 3 4 0730 1 2 3 4 0740 1 2	+ 1 + 4600 + 1 + 5600 + 1 + 1200 + 1 + 1300 + 1 + 2000 + 1 + 1 + 3300 + 1 + 2000 + 1 + 1 + 4300 + 1 + 2000 + 1 + 1 + 5300 + 1 + 5000 + 1 + 5000	/130

The printed results of the control example are shown in Tables 15 and 16.

Table 15 gives the coordinates of the auxiliary points on the confocal ellipse in the following sequence:

$$x_1^{(1)}, x_2^{(1)}; ...; x_1^{(24)}, x_2^{(24)}$$

and the value of the Fourier coefficients \mathbf{C}_1 , \mathbf{C}_2 , ..., \mathbf{C}_{24} .

Table 16 gives the coordinates of the designated points (ξ_i, η_i) , and the solutions $u(\xi_i, \eta_i)$, corresponding to them obtained on the machine, and the error

$$\varepsilon_i = \left[\frac{\xi}{\xi^2 + \eta^2} - u(\xi, \eta) \right], i = 1, 2, ... 40.$$

The operating time of the machine for this example is 45 minutes. The distribution of designated points is shown on Figure 4.

TABLE 15

i	$x_1^{(l)}$	$\chi_2^{(l)}$	c_i
1	-0,10971885 · 10-7	0,60000000	-0,22206542 10-5
2 3	0.32915656 10 ⁻⁷ 0.75000000	0,6000000 0,0000000	0,20515213 10-5
4	-0.75000000	-0.17555016·10 ⁻⁷	-0.76608258·10 ⁻¹
5	-0. 53033006	-0,42426408	0.76589811·10 ⁻³ 0.10152.26
4 5 6 7	0.53033008	0.42426407	-0.10152320 -0.10152297
7	0.53033011	-0,42426404	-0.10152237 -0.10152337
8	-0.53033009	0,42426406	0,10152883
8 9	0.64951907	-0.29999997	-0.90643412.10-1
10	-0.64951906	0.29999998	0.90631226 10-3
11	-0.37500001	0.51961523	0.99701809 · 10-1
12	0,37500003	-0,51961522	-0.99703552 10 ⁻¹
13	0,37499999	0.51961524	-0.99706374·10 ⁻³
14	-0,37499997	0.51961525	0.99706651 10-1
15	0,64951905	0,30000000	-0.90641500 10-1
16	-0,64951904	-0.30000001	0.90637014 10-1
17	0,19411427	0, 57955549	0,66432247-10-1
18	-0. 19411425	0 ,57955550	0,66432366 10-1
19	-0.19411429	0,57955549	0 66436770 10-1
20	0,19411431	0,57955549	-0,66436330 10 ⁻¹
21	0.72444437	0.15529142	-0.80437784 · 10-1
22	-0.72444436	-0.15529144	0,80449894 10-1
23	-0.72444437	0,15529141	0.80453934 · 10-1
24	0.72444438	-0,15529139	-0,80435528 ·10 ⁻¹

TABLE 16

					/131
n	ξ_n	η_n	$u(\xi_n\eta_n)$	$oldsymbol{arepsilon}_n$	7131
1	0,80000000	0.10000000	0.48780491	-0.4.10-7	
2	0.80000000	0.12000000	0.38461539	$-0.1 \cdot 10^{-7}$	
3	0.80000000	0,13999999·10 ¹	0.30769231	$-0.1 \cdot 10^{-7}$	
4	0.80000000	0.16000000 - 101	0.25000001	$-0.1 \cdot 10^{-7}$	
- 5	0.80000000	0,17999999 10 ¹	0.20618559	$-0.3 \cdot 10^{-3}$	
6	0.80000000	0_200000000 · 101	0.17241383	$-0.4 \cdot 10^{-7}$	
7	0,80000000	0.24000000 101	0,12500006	$-0.6 \cdot 10^{-7}$	
8	0.80000000	0.25999999 101	0,10810818	$-0.8 \ 10^{-7}$	
9	0.90000000	0,11000000 101	0.44554459	$-0.4 \ 10^{-7}$	
10	0,90000000	0_16000000 - 104	0.26706233	$-0.2 \cdot 10^{-7}$	
11	0,90000000	0,20999999 101	0.17241384	$-0.5 \cdot 10^{-1}$	
12	0,90000000	0.25999999 101	0.11889043	$-0.8 \cdot 10^{-7}$	
13	0,90000000	0.30999999.101	0.86372452·10 ⁻¹	$-0.92 \cdot 10^{-6}$	
14	0.90000000	0.35999999.101	0,65359581 10-1	$-0.104 \ 10^{-6}$	
15	0,90000000	0.45999999·10 ¹	0.40965076.10-1	$-0.124 \cdot 10^{-5}$	
16	0.90000000	0.55999999 10 ¹	0,27976515·10 ⁻¹	0 _p 14 10 ⁻⁶	
17	0.12000000 101	0 12000000 · 101	0.41666670	$-0.4 10^{-7}$	
18	0,12000000·10t	0.20000000.101	0,22058829	$-0.6 \cdot 10^{-7}$	
19	0.12000000 101	0.27999999 101	0.12931042	$-0.8 \cdot 10^{-7}$	
20	0.12000000 101	0 _• 35999999•10¹	0 83333438 10 ⁻¹	$-0.105 \cdot 10^{-6}$	
21	$0,12000000 \cdot 10^{1}$	0.44000000 - 101	$0.57692429 \cdot 10^{-1}$	$-0.1(2 \cdot 10^{-6})$	
22	0_12000000 101	0,51999999-101	$0.42134966 \cdot 10^{-1}$	$-0.135 \cdot 10^{-6}$	
23	0.120000000.101	0.60000000.101	$0.32051428 \cdot 10^{-1}$	$-0.146 \ 10^{-6}$	•
24	$0.12000000 \ 10^{1}$	0.68000000 101	$0.25167941 \cdot 10^{-1}$	-0,156 10-6	
25	$0.20000000 \cdot 10^{1}$	$0.12999999 \cdot 10^{1}$	0.35149391	$-0.7 \ 10^{-7}$	
26	0.20000000 101	0,22999999·10 ^t	0,21528533	$-0.8 10^{-7}$	
27	$0.20000000 \cdot 10^{1}$	$0,32999999 \cdot 10^{1}$	0,13431844	$-0.11 \cdot 10^{-7}$	
28	0.20000000 10'	0,43000000 101	0,88928536 · 10-1	-0.124.10-6	
29	$0.20000000 \cdot 10^{1}$	0,53000000 · 101	0,62324850 10-1	-0.139 10-6	
30	0.20000000 101	0,63000000 · 10 ¹	0.45777217 10-1	-0.152 10-6	
31	0.200000000.101	0.73000000 101	0.34910269 10-1	-0.162.10-6	
32	0.20000000 101	0,83000000 101	0.27438778 · 10-1	-0.172.10-6	
33	0.50000000 101	0,13999999 · 101	0,18546007	-0.13 10-6	
34	0.50000000.101	0.25000000.101	0.16000013	-0.13.10-6	
35 36	0,50000000.101	0,35999999.101	0.13171774	-0.15·10-8	
30 37	0.50000000.101	0.46999999·10 ¹ 0.58000000·10 ¹	0.10617981 0.85266193·10 ⁻¹	$\begin{array}{c c} -0.16 \cdot 10^{-6} \\ -0.163 \cdot 10^{-6} \end{array}$	
38	0.50000000-101	0,69000000·10 ¹	0.68861210 · 10-1	-0.103.10 ° -0.172.10-8	
39	0.50000000 101		0.56179955 10-1	-0.172.10° -0.18.10-6	
39 40	0.50000000 101	0,80000000·10 ¹ 0,91000000·10 ¹			
70	0,50000000.101	o'aroonoo.io,	0,46378075 · 10-1	-0,188 10-8	

Control Example 2

Let us look at the external Dirichlet boundary problem for the ellipse

$$x_1 = \cos \varphi$$
, $x_2 = 0.5 \sin \varphi$.

Under the boundary condition

$$u(\alpha) = \frac{-2x_1x_2}{[x_1^1 + x_2^2]^2}, \ 0 \le \alpha \le 2\pi$$

S

we seek the harmonic function outside the ellipse s.

In cell 0623, we transfer the value for the semi-minor axis b = 0.5. In cell 0622 we read in the number b $-\overline{b}$ = 0.1. The machine selects the following values of the semiaxes for the auxiliary ellipse s₁:

$$x_1^{(i)} = 0.8 \cos \alpha_i$$
, $x_2^{(i)} = 0.4 \sin \alpha_i$, $i = 1, 2, ..., 24$.

In this case, the number of designated points is $i={}^{43}|_{10}={}^{53}|_{8}.$

/132

The exact solution to this problem has the form

$$u(\xi,\eta) = \frac{-2\xi\eta}{[\xi^2 + \eta^2]^2}, \quad (\xi,\eta) \in G_e.$$

Below we give the initial and numerical data.

Address	C	omman	d		Address	Command				
1 2 3 4 5 6 7 0010 1 2 3 4	30 31 30 31 35 33 34 77 34 00	0100 0100 0014 0022 0622	0622 0622 0013	0014 0014 0014 0013 0010 0001 0060 0622 0134	0622 3 4 5 6 7 0630 1 2 3 4 5	++	0 0 03 03 01 03 03 03 04 34 02	0020 0021 0001 0001 0020 0636 0002	1000 5000 0053 0020 0021 0002 0001 0021 0002 0001	0000 0000 0011 0001 0002 0001 0001 0002 0002 0002 0001 0272

	NUMERICAL DATA												
Address			Co	mmand		Address			Com	nand			
0000 1 2 3 4	++++	0 0 0 0 0	++++	1000 8500 1000 9000 1000		0040 1 2 3 4	++++	0 1 0 1 0	+ + + + + +	5000 4000 5000 4500 7000			

NUMERICAL DATA (con't)

Address		N	umbers	Address			Nu	mbers	-
5 6 7 0010 1 2 3 4 5 6 7 0020 1 2 3 4 5 6 7 0030 1 2 3 4 5 6 7	+ + + + + + + + + + + + + + + + + + + +	01	9500 1000 1000 1000 1000 1100 1100 4000 1200 4000 1400 4000 2000 4000 2200 5000 8500 5000 5000 3500 3500	5 6 7 0050 1 2 3 4 5 6 7 0060 1 2 3 4 5 6 7 0070 1 2 3 4 5 6 7	+++++++++++++++++++++++++++++++++++++++	0 0 0 1 0 1 0 1 1 1 1 1 1 1 1 1 1 1 1 1	+++++++++++++++++++++++++++++++++++++++	8000 7000 9000 7000 1530 7000 1700 7000 1900 7000 2100 1000 1000 1300 1000 2300 1000 2400 1000 2400 1500 8000 1500	
0100 1 2 3 4 5 6 7 0110	+ -	1	1500 3700 1500 4400 1500 5100 1500 5800 2000 8000 2000	3 4 5 6 7 0120 1 2 3 4	+++++++++		+++++++	9000 2000 1000 2000 2000 2000 3000 2000 400 2000 5000	

TABLE 17

i	$x_{i}^{(i)}$	$x_2^{(i)}$	c_i
1 2 3 4 5 6 7 8 9 10	-0.11703344 10 ⁻⁷ -0.35110033 10 ⁻⁷ 0.80000000 -0.80000000 -0.56568540 -0.56568542 0.56568545 -0.56568543 0.69282034 -0.69282033 -0.40000001 0.40000003	0.4000000 -0.40000000 0.0000000 -0.11703344·10-7 -0.28284272 0.28284271 -0.28284269 0.28284270 -0.19999998 0.19999999 0.34641015 -0.34641015	0.96853857·10-6 -0.16354052·10-5 -0.29542828·10-4 -0.20274971·10-4 0.17703348 0.17703663 -0.17703063 -0.17702067 -0.38290288·10-1 -0.3829288·10-1 -0.65954406 -0.65954315

TABLE 17 (con't)

í	x _i (i)	x(i)	C _i
13 14 15 16 18 18 19 20 21 32 23 24	0.39999999 -0.39999997 0.69282032 -0.69282031 0.20705522 -0.20705520 -0.20705524 0.20705527 0.77274066 -0.17274065 0.77274066 0.77274067	0.34641016 -0.34641017 0.20000000 -0.200000001 0.38637033 -0.38637032 -0.38637032 0.10352761 -0.10352763 0.10352760 -0.10352759	0,65954371 0,65954367 0,38276880.10 ⁻¹ 0,38283523.10 ⁻¹ 0,15523954.10 ¹ 0,15523975.10 ¹ -0,15523971.10 ¹ -0,15523962.10 ¹ 0,97296802.10 ⁻² 0,96886752.10 ⁻² -0,96832523.10 ⁻²

TABLE 18

$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		1	1	1.	,
2	i	ξ,	η_i	$u(\xi_i, \eta_i)$	ϵ_i
2		1	<u> </u>	<u> </u>	!
2	1	0.10000000	0.85000000	-0.31584753	0 101214-10-2
3 0.10000000 0.95000000 -0.22780316 0.38224 10-8 4 0.10000000 0.10000000 0.1049999 10¹ -0.19580721 0.25200-10-3 5 0.10000000 0.11600000-10¹ -0.14768900 0.12072-10-3 6 0.40000000 0.12000000 10¹ -0.37490475 0.9525-10-4 7 0.40000000 0.1600000-10¹ -0.24914741 0.5159 10-4 9 0.40000000 0.17999999-10¹ -0.12485015 0.1732-10-4 10 0.40000000 0.17999999-10¹ -0.12485015 0.1732-10-4 11 0.40000000 0.22000000-10¹ -0.292444604-10-1 0.11017-10-3 42 0.40000000 0.25000000-10¹ -0.89885234 -0.66-10-6 14 0.50000000 0.35000000-10¹ -0.59166383-10-1 0.5214-10-4 15 0.50000000 0.35000000-10¹ -0.23398476-10-1 0.2244-10-4 16 0.50000000 0.35000000-10¹ -0.23398476-10-1 0.963-10-8 18 0.50000000 0.45000000-10¹ -0.1744309				-0 26709592	0.60187.10-3
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$				-0 22780316	
$\begin{array}{cccccccccccccccccccccccccccccccccccc$					0.25200.10-3
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	5				0 16182 10-3
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$					
$\begin{array}{cccccccccccccccccccccccccccccccccccc$					
$\begin{array}{c} 9 \\ 10 \\ 10 \\ 0 \\ 0 \\ 40000000 \\ 0 \\ 0 \\ 17999999 \\ 10^1 \\ 0 \\ 0 \\ 20000000 \\ 10^1 \\ 0 \\ 0 \\ 10000000 \\ 10^1 \\ $	8				0.5150 10-4
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	9				0 2895.10-4
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	10				
$\begin{array}{cccccccccccccccccccccccccccccccccccc$.11	0.40000000			0 11017-10-3
$\begin{array}{cccccccccccccccccccccccccccccccccccc$		1	1	1	1
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	12	0.40000000	0,220000000.101	-0-70392605 10-1	0.7395.10-4
$\begin{array}{cccccccccccccccccccccccccccccccccccc$: 13				
$\begin{array}{cccccccccccccccccccccccccccccccccccc$.0.50000000	0.25000000.101		
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	15		0.30000000 101		
$\begin{array}{cccccccccccccccccccccccccccccccccccc$		0.50000000	0.35000000 101		
$\begin{array}{cccccccccccccccccccccccccccccccccccc$			0.40000000 101		
$\begin{array}{c} 19 \\ 20 \\ 0,70000000 \\ 0,70000000 \\ 0,70000000 \\ 0,70000000 \\ 0,15000000 \cdot 10^1 \\ 22 \\ 0,70000000 \\ 0,17000000 \\ 0,17000000 \cdot 10^1 \\ 23 \\ 0,70000000 \\ 0,19000000 \cdot 10^1 \\ 0,10000000 \\ 0,19000000 \cdot 10^1 \\ 0,10000000 \cdot 10^1 \\ 0,10000000 \cdot 10^1 \\ 0,10000000 \cdot 10^1 \\ 25 \\ 0,10000000 \cdot 10^1 \\ 0,10000000 \cdot 10^1 \\ 0,10000000 \cdot 10^1 \\ 27 \\ 0,10000000 \cdot 10^1 \\ 0,12999999 \cdot 10^1 \\ 0,10000000 \cdot 10^1 \\ 28 \\ 0,10000000 \cdot 10^1 \\ 0,22999999 \cdot 10^1 \\ 0,24000000 \cdot 10^1 \\ 0,24000000 \cdot 10^1 \\ 0,25999999 \cdot 10^1 \\ 0,2599999 \cdot 10^1 \\ 0,259999$		0.50000000	0.45000000.101		
$\begin{array}{cccccccccccccccccccccccccccccccccccc$			0,80000000		-0-1881 10-4
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$			0.90000000	-0.74555695	
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$		0.70000000	0.15000000·101	-0.27968637	
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$		0.70000000	0.17000000 101		
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$		0.70000000	0,19000000.101		
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$			0.20999999.101	-0.12243752	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$				-0.59488382	
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$			0°10000000·10 ₇	-0.45042692	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			0.129999999.101	-0 35929066	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			0.22999999.101	-0.11625829	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$				-0,10503055	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$				-0.86347263.10-1	
$\frac{32}{22}$ 0.15000000 · 101 0.30000000 · 101 -0.71106808 · 10-1 0.4303 · 10-5				-0.28734960	
0, 10000000 10 - 1 0,2070.10	33	$0.15000000 \cdot 10^{1}$	0.37000000.101	-0.43683835 10 ⁻¹	0.2573.10-6
$34 0.15000000 \cdot 10^{1} 0.44000000 \cdot 10^{1} -0.28264387 \cdot 10^{-1} 0.1615 \cdot 10^{-5}$	34	0°12000000 · 10 ₁	0.44000000:101	-0.28264387.10-1	

TABLE 18 (con't)

j.	ξ _i	η _i	u(ξ _i η _i)	ε _i	
35 36 37 38 39 40 41 42 43	0,15000000 10 ¹ 0,15000000 10 ¹ 0,20000000 10 ¹	0,50999999.101 0,58000000.101 0,80000000 0,90000000 0,10000000.101 0,20000000.101 0,4000000.101 0,50000000.101	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	0,1065·10-5 0,740·10-6 0,283·10-5 0,332·10-5 0,381·10-5 0,578·10-5 0,3867·10-5 0,1292·10-5	

The printed results of the control example are shown on Tables 17 and 18.

Table 17 gives the coordinates of the auxiliary points on the confocal ellipse and the value of the Fourier coefficients.

Table 18 gives the coordinates of the designated points $(\xi_i \eta_i)$ and the solutions corresponding to them $u(\xi_i, \eta_i)$, obtained on the machine and error

$$\varepsilon_i = \left[\frac{-2\xi\eta}{[\xi^2 + \eta^2]^2} - u(\xi, \eta) \right], \quad i = 1, 2, ..., 43.$$

The machine time for this example is 50 minutes.

The distribution of designated points is shown on Figure 5.

OPERATIONAL CODE FOR THE METHOD OF GENERALIZED FOURIER SERIES

Address		Comm	nand		Address	C	Command			
0000 1 2 3 4 5 6 7	00 30 31 35 33 67 30 31	0005 0 0001 0 0077 2 1400	0014 0050 2357 0347	1664 0050 0006 0426 1114 0044	0010 1 2 3 4 5 6 7	30 71 35 33 34 30 31 30	0400 0044 0002 1400 0400	0050 1115 1464 1115	1114 0050 0015 0006 0214 0047 0214	

Address	C	ommand		Address		Comm	and	
0020 1 2 3 4	71 35 33 34 30 010	03	0050 0024 0015 0013	0120 1 2 3 4	41 36 33 35	0004 0125	0132 0004 0002	0004 0072 0003 0074 0001
5 6 7 0030 1 2	31 34 30 31 35 004 33 000	0060 4 0010	0001 1114 0010 0505	5 6 7 0130 0 2	37 04	1200 3700 1100 2040	3777	3777
3 4 5 6 7 0040	34 30 31 35 35 004 33 34	7 0220	0027 0214 0010 0256	3 4 5 6 7 0140	34 14 62	1463 0622 0623 0624 0042	0631 0350	2315 0351 0043 0051 0042 0352
1 2 3 4	00 00 00 00		0034	1 2 3 4	22 22 00 31	0323 0324	0124 0352 0352 0626	0.352 0143 0145 0046
5 6 7 •0050	00 00 00 00 00			5 6 7 0150 1	00 71 35 33 34	0046 0006	0625 0010	0010 0152 0143
2 3 4 5 6 7 0060	00 00 00 00 00 00 00 34	0000	0001	2 3 4 5 6 7	22 62 17 35 62	0145 0321 0327 0352 0353 0352	0042 0352 0124 0124	0054 0352 0352 0353 0160 0352
1 2 3 4 5 6	26 000 22 012 33 17 012 20 000 22 012	4 0063 0002 5 0001 0004	0061 0063 0063 0001 0004 0076 0076	0160 1 2 3 4 5	26 22 17 17 75 17	0352 0352 0353 0625 0625 0354 0625	0013 0322 0325 0125	0055 0353 0057 0056 0354 0237 0354
7 0070 1 2 3 4	22 012 22 012 22 000 76 000 33 17 012	5 0004 6 0001 2 0124 1 0133 0002	0001 0122 0063 0117	7 0170 1 2 3 4	22 26 36 62 62	0354 0354 0354 0354 0124 0352	0354 0113 0352 0352	0354 0354 0232 0354 0351 0355
5 6 7 0100 1	35 33 22 007 22 012 45	0001 0002 0126	0063 0002 0076 0122 0002	5 6 7 0200	22 00 31 00	0330 0177	0355	0177 0201 0010
2 3 4 5 6	26 000 03 012 17 013 76 013 41 013	2 0106 7 0002 0 0001 1 0003	0004 0002 0003 0073	2 3 4 5 6	31 35 33 34	0010 0007	0623 0011	0011 0206 0177
0110 1 2	01 000 66 000 76 25 000	3 0002 0004 0001 0004	0004 0002 0001 0103 0001	0210 1 2 3	22 77 00 00 22	0331	0353	0210 0060 0215
3 4 5 6 7	36 013 04 000 42 000 35 000	0127	0121 0001 0004 0113 0001	3 4 5 6 7	22 22 00 31 00	0334 0335	0352 0352 0623	0217 0220 0010

Address		Co	mmand		Addres	ss		Co	mmanc		en europea europea (en en e
0220 1 2 3 4 5 6 7 0230 1 2 3 4 5 6 7 0240 1 2 3 4 5 6 7 0250 1 2 3 4 5 6 7 0260 1 2 3 4 5 6 7 0270 1 2 3 4 5 6 7 0270 1 2 3 4 5 6 7 0270 1 2 3 4 5 6 7 0270 1 2 3 4 5 6 7 0270 1 2 3 4 5 6 7 0270 1 2 3 4 5 6 7 0270 1 2 3 4 5 5 6 7 0270 1 2 3 4 5 5 6 7 0270 1 2 3 4 5 5 6 7 0270 1 2 3 4 5 5 6 7 0270 1 2 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 3 4 5 6 7 03000 1 2 3 3 4 5 5 6 7 03000 1 2 3 3 4 5 5 6 7 03000 1 2 3 4 5 5 6 7 03000 1 2 3 3 4 5 5 6 7 03000 1 2 3 3 4 5 5 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 3 3 4 5 5 6 6 7 03000 1 2 5 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	00 31 35 33 34 35 22 22 20 00 34 26 34 22 22 22 25 02 03 03 03 03 03 03 03 04 03 01 34 02 34 00 01 34 02 34 03 04 04 05 06 06 07 07 07 07 07 07 07 07 07 07	0010 0010 0010 0350 0335 0045 0354 0352 0336 0336 0216 0625 0001 0337 0623 0002 0341 0006 0005 0005 0006 0006 0006 0006 000	0623 0333 0351 0057 0124 0013 0013 0211 0344 0336 0077 0353 0007 0005 0007 0007 0003 0007 0001 0264 0001 0264 0001 0264	0010 0225 0215 0027 0335 0045 0171 0351 0352 0353 0174 0352 0216 0001 0333 037 0002 0003 0311 0004 0007 0006 0007 0006 0007 0006 0303 0303	0320 1 2 3 4 5 6 7 0330 1 2 3 4 5 6 7 0340 1 2 3 4 5 6 7 0350 1 2 3 4 5 6 7 0360 1 2 3 4 5 6 7 0370 1 2 3 4 5 6 7 0400 1 2 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	38	34 30 30 30 30 30 30 77 20 30 01 34 34 34 34 41 26 03 03 01 03 01 01 03 01 01 01 03 01 01 01 01 01 01 01 01 01 01	1400 0400 3777 0100 0623 1403 3777 0010 1400 1000 0003 0005 0001 0004 0004 0002 0125 0002 0003 0002 0002 0002 0002 0125 0004 0002 0127 0004 017 0004 0002 0127 0004 017 0004 0002 0003 0005 0001 0004 0002 0003 0005 0003 0005 0001 0004 0002 0003 0005 0003 0005 0001 0004 0002 0003 0003 0005 0003 0005 0003 0004 0003 0005 0003 0005 0003 0005 0003 0005 0003 0005 0003 0005 000	0001 1332 1332 3777 0333 2462 0003 0126 0003 0130 0046 0003 0130 0046 0121 0004 0002 0003 0122 0002 0003 0123 0124 0003 0002 0003 0004 0003 0004 0003 0004 0003	0311 0626 3666 0623 3777 0623 0003 0002 0265 0270 0276 0626 0627 0004 0004 0003 0005 0004 0003 0002 0003 0002 0003 0002 0003 0002 0003 0002 0003 0002 0003 0002 0004 0004	
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